

Adversarial Machine Learning

Ian Goodfellow, Senior Staff Research Scientist

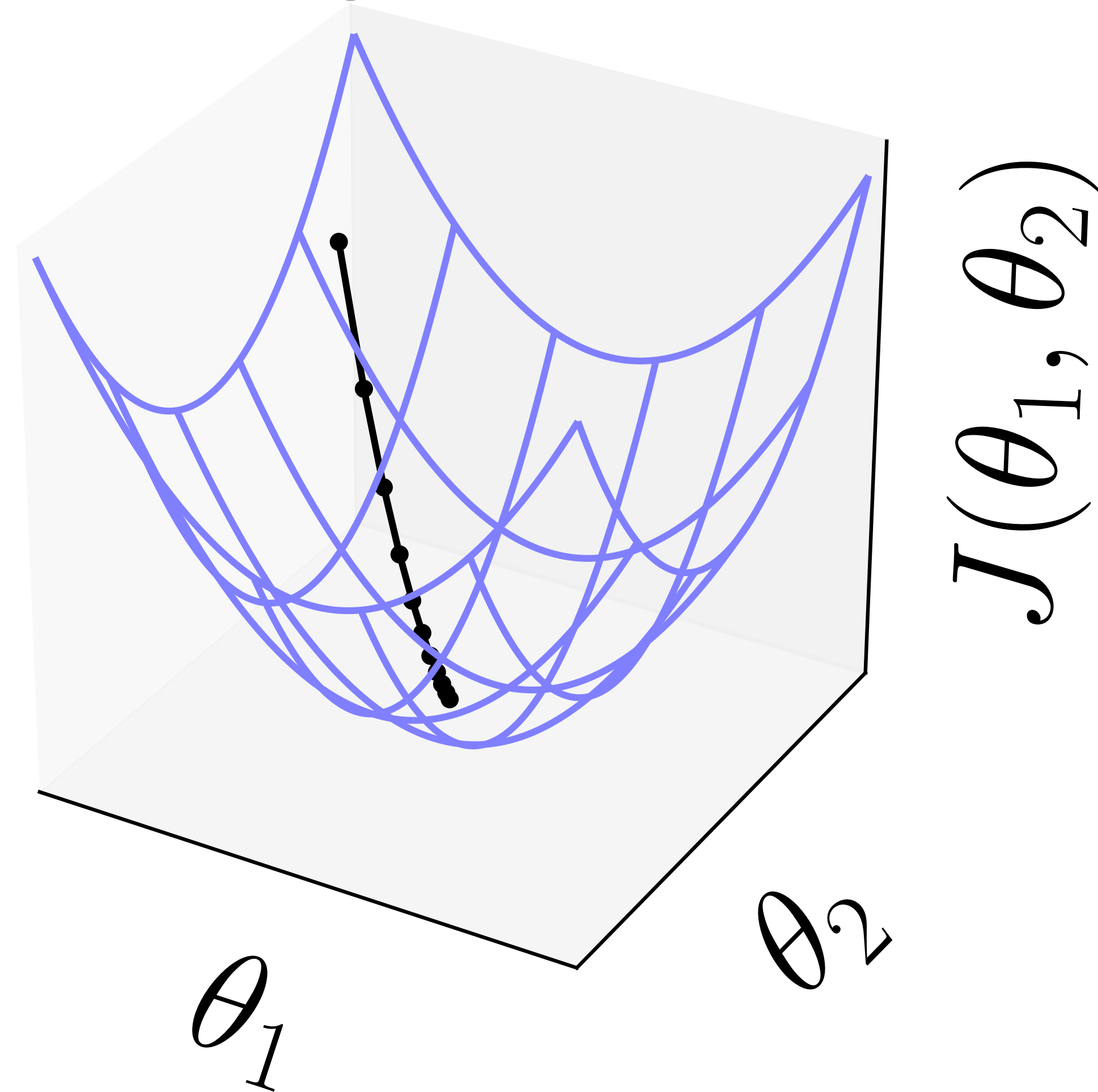
AAAI

2019-01-30



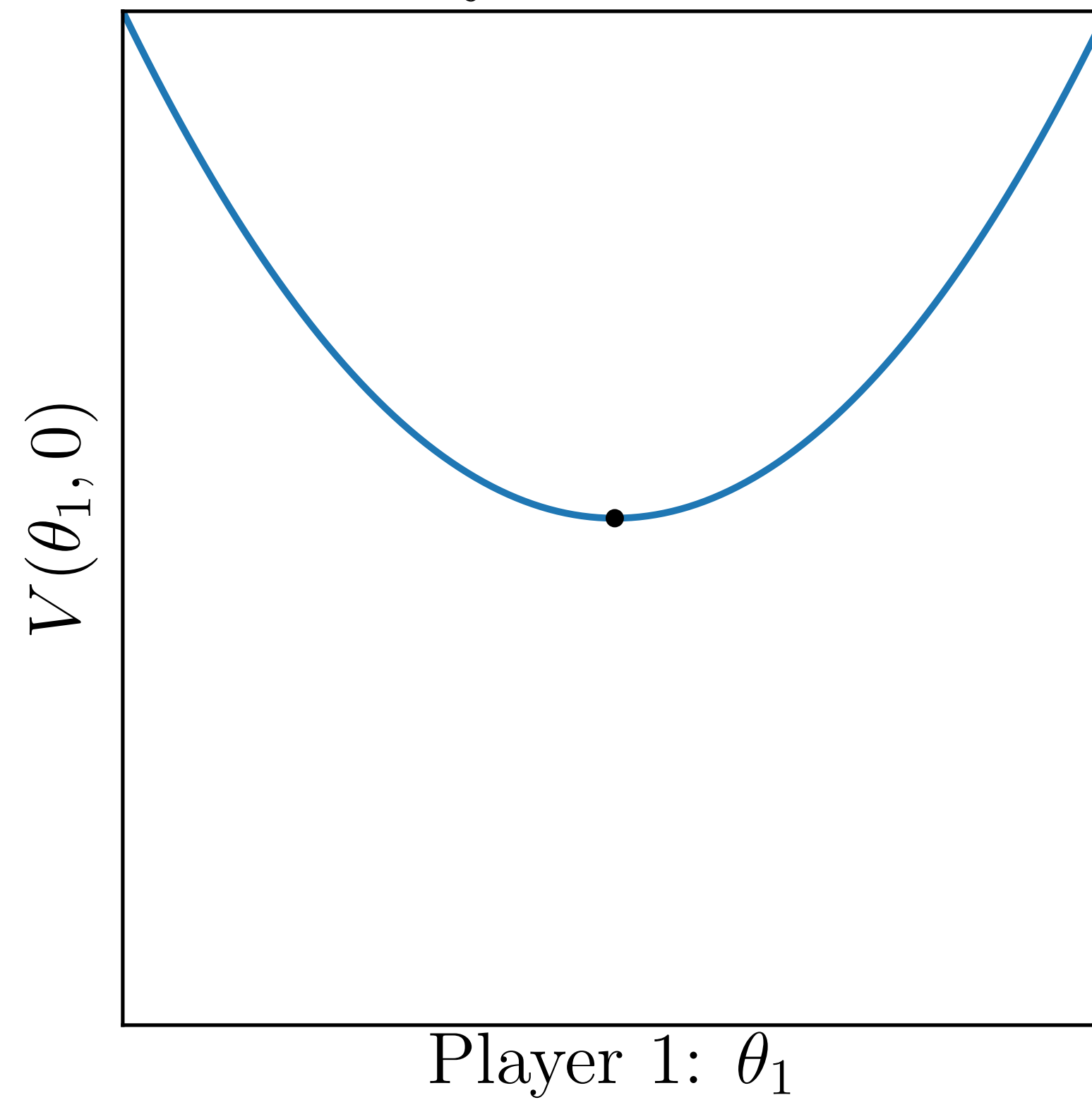
Google AI

Most Traditional Machine Learning: Optimization

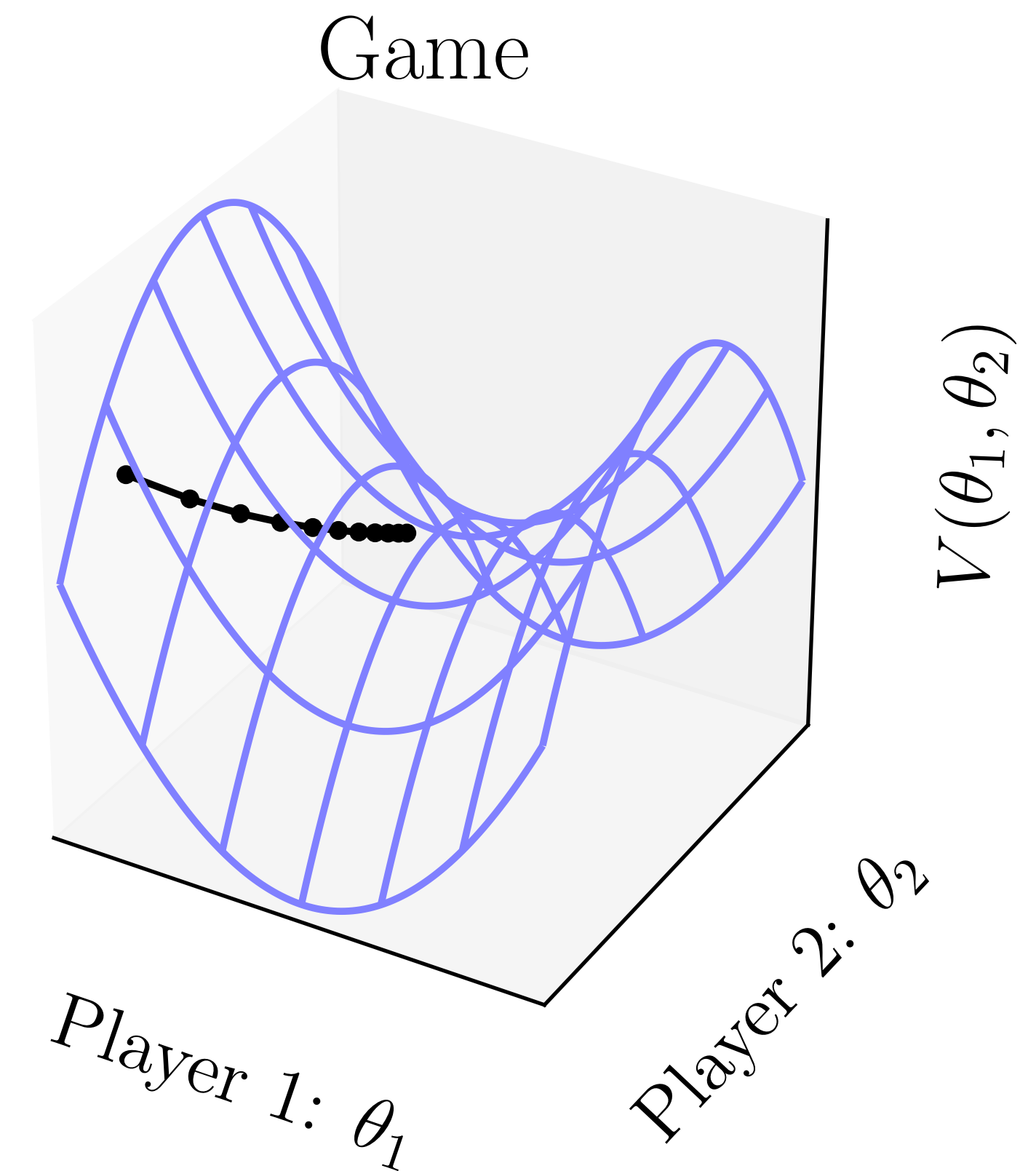
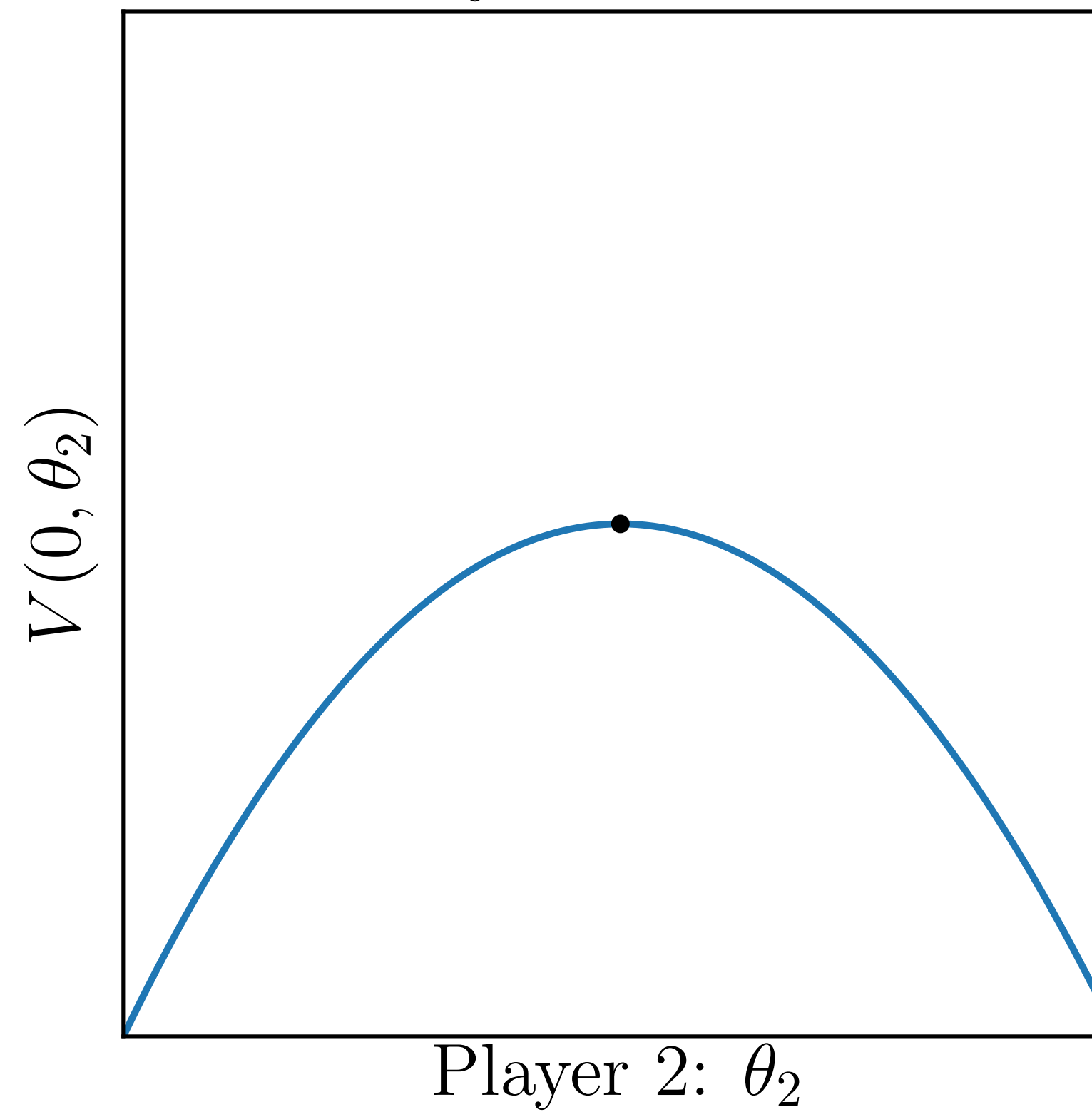


Adversarial Machine Learning: Game Theory

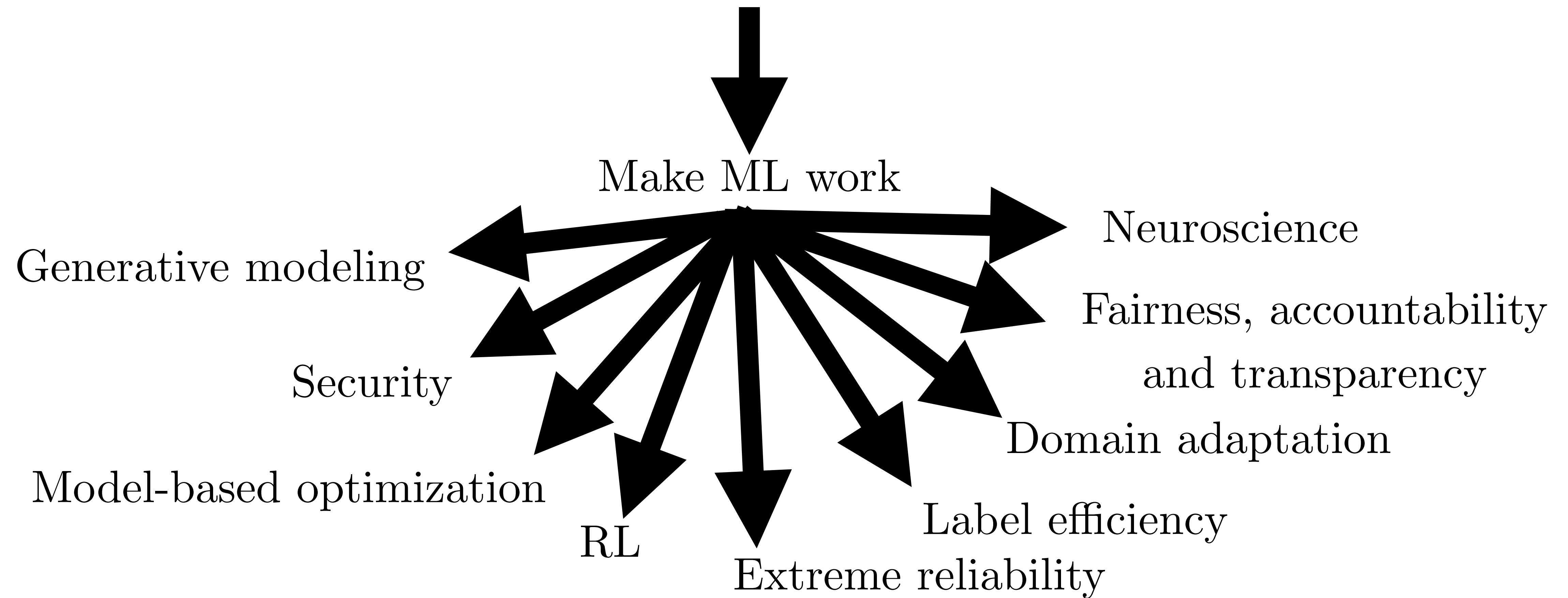
Player 1's view



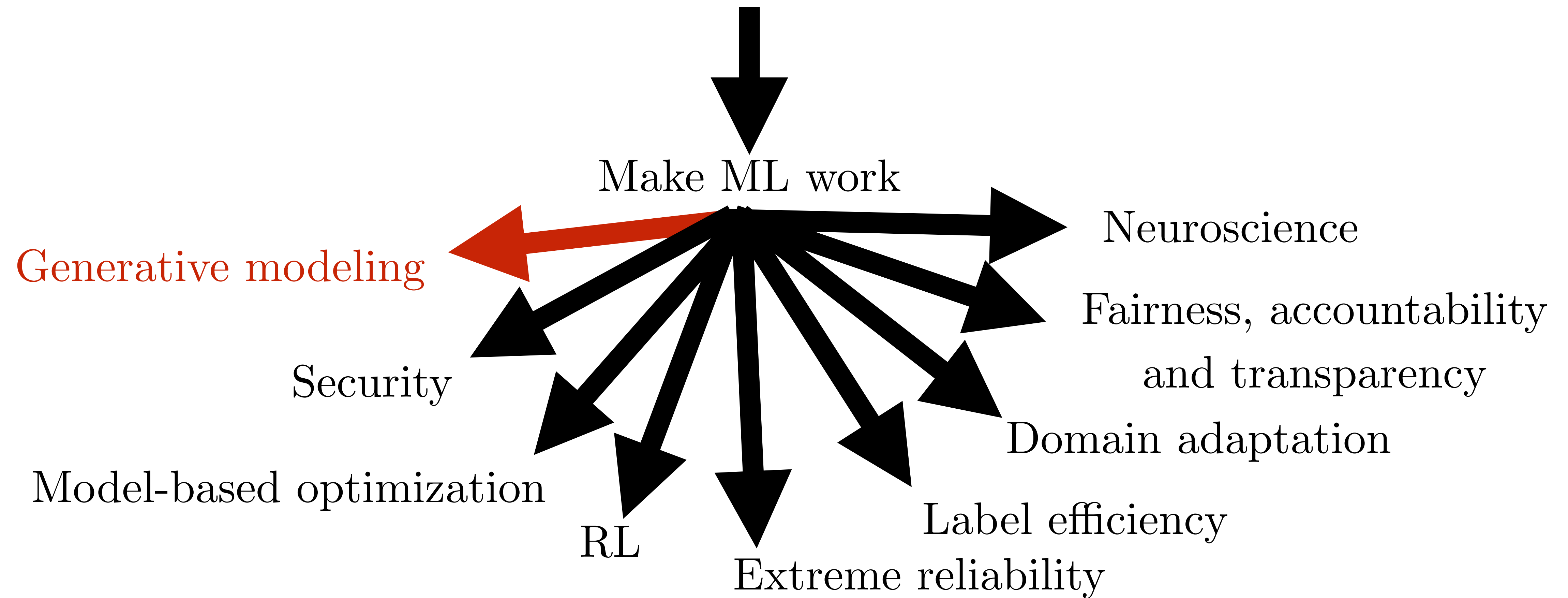
Player 2's view



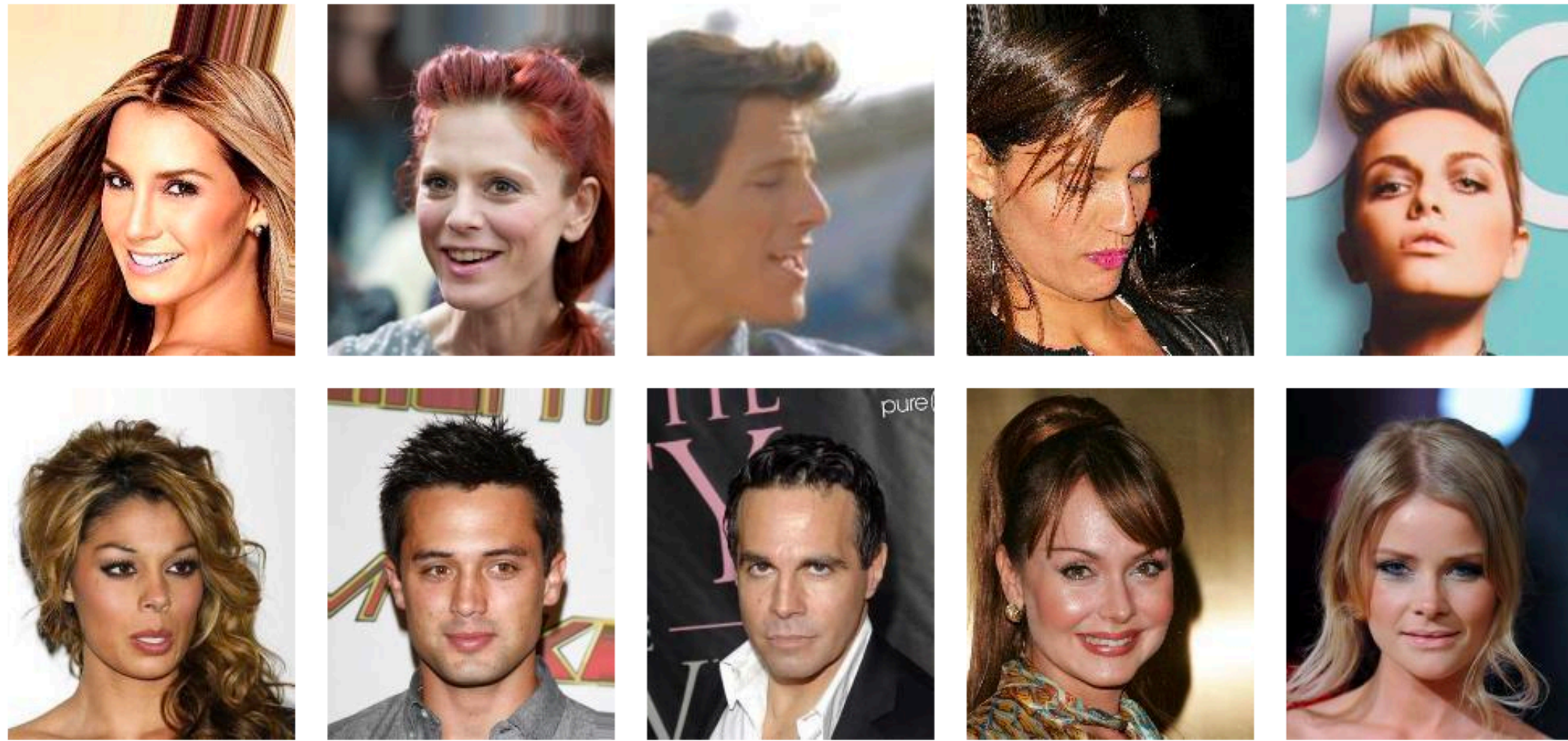
A Cambrian Explosion of Machine Learning Research Topics



A Cambrian Explosion of Machine Learning Research Topics



Generative Modeling: Sample Generation

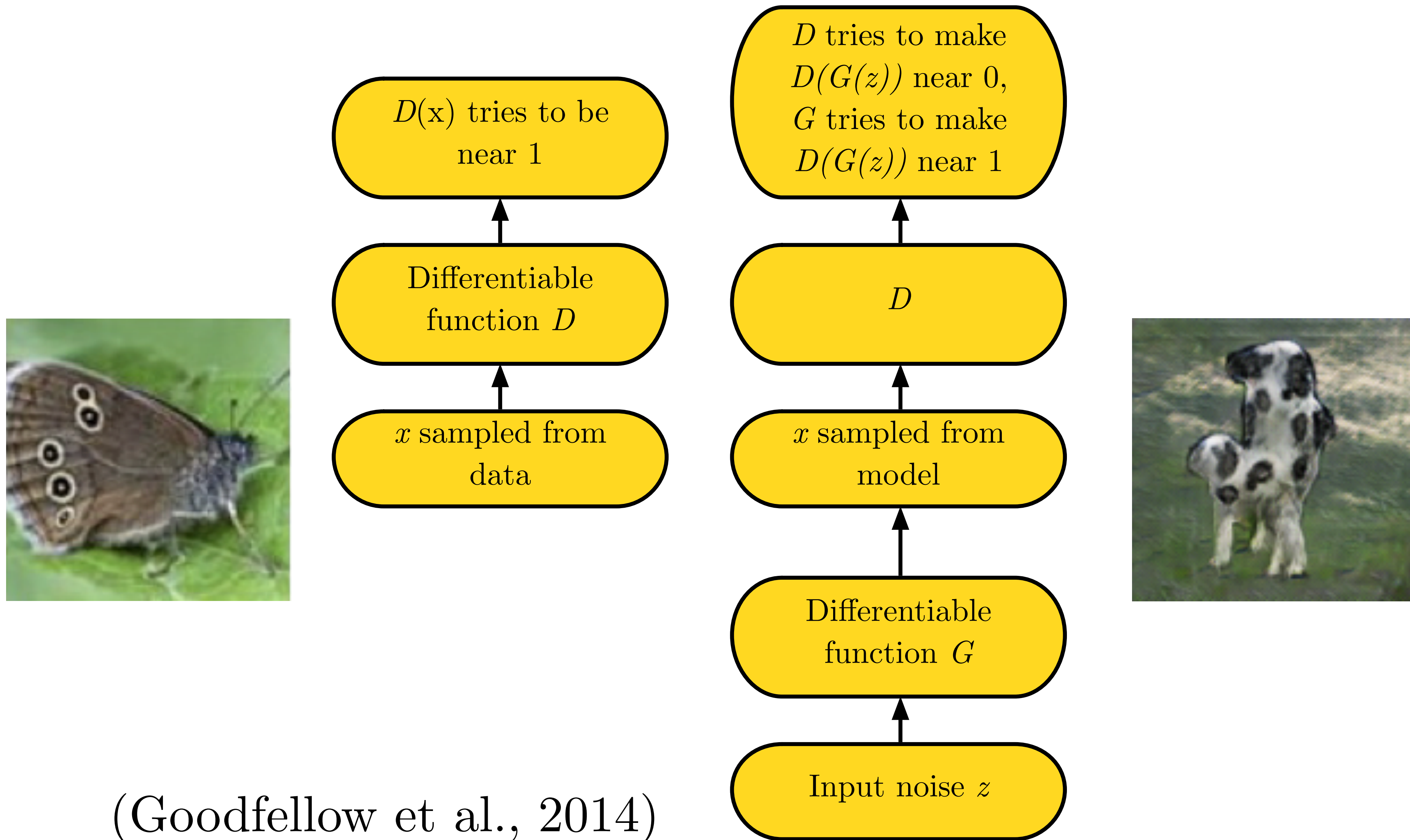


Training Data
(CelebA)



Sample Generator
(Karras et al, 2017)

Adversarial Nets Framework



4.5 years of progress on faces



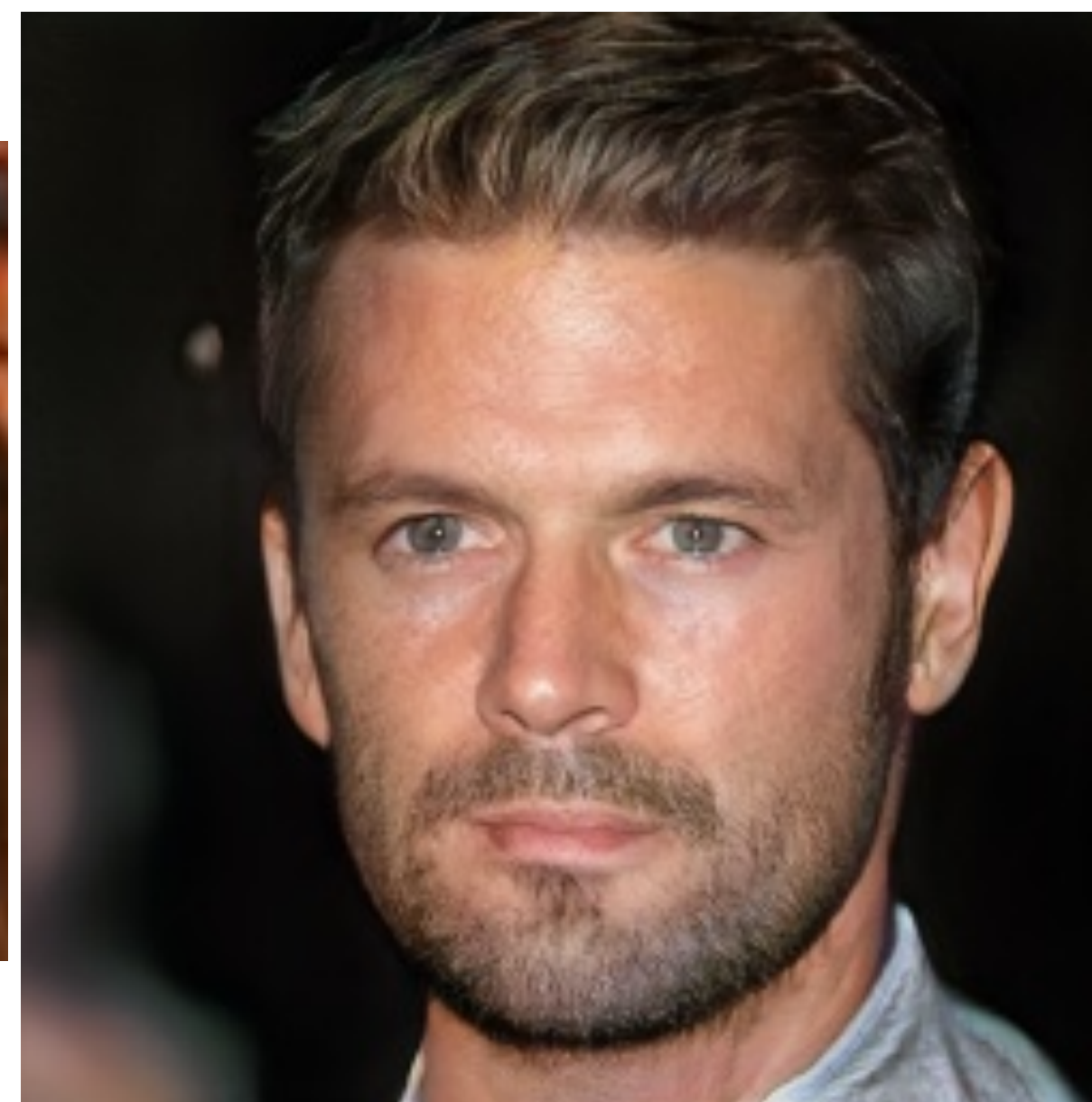
2014



2015



2016

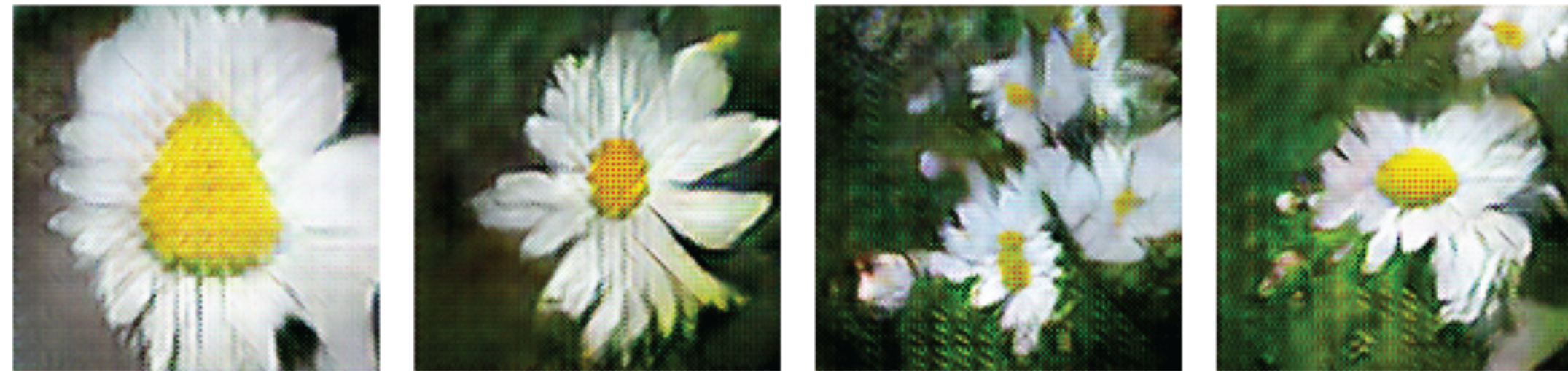


2017



2018

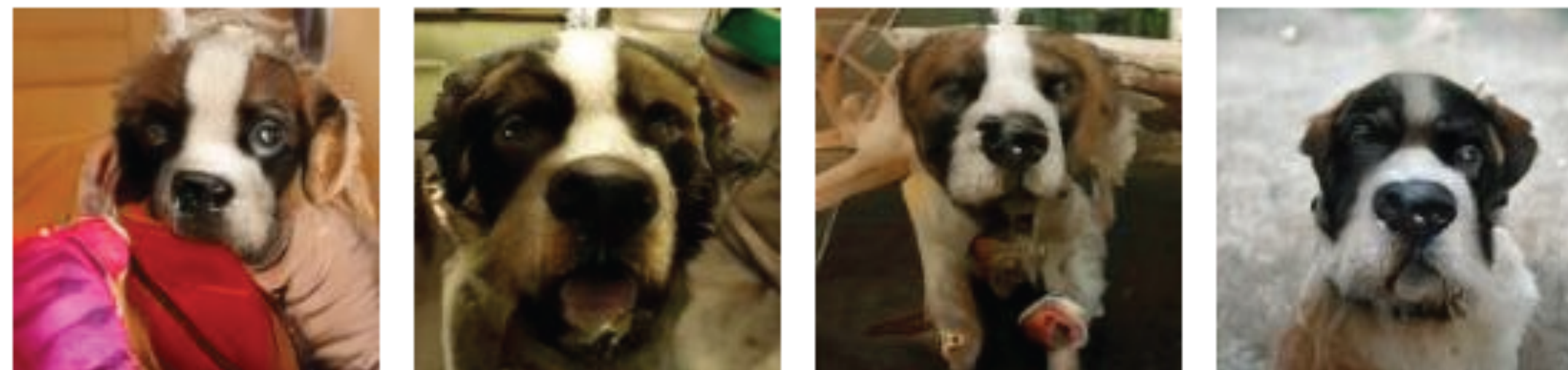
2 Years of Progress on ImageNet



Odena et al
2016



Miyato et al
2017



Zhang et al
2018

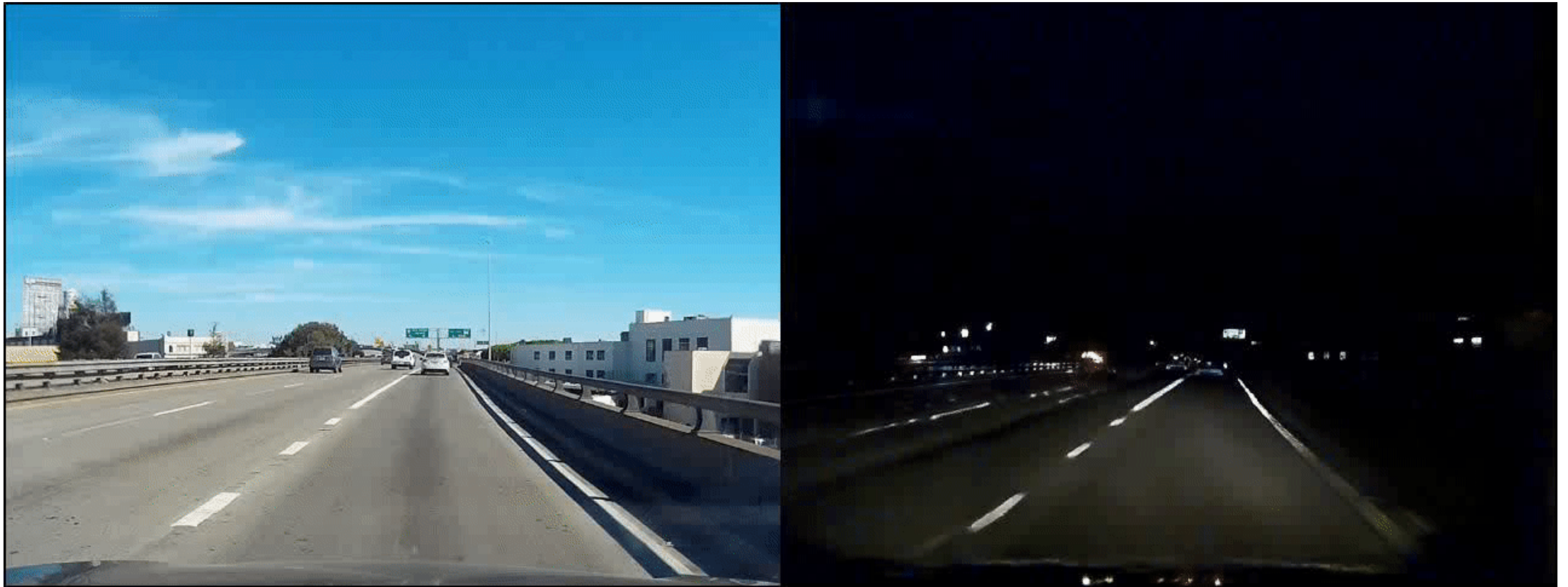


Brock et al
2018

(Odena 2018)

Unsupervised Image-to-Image Translation

Day to night



(Liu et al., 2017)

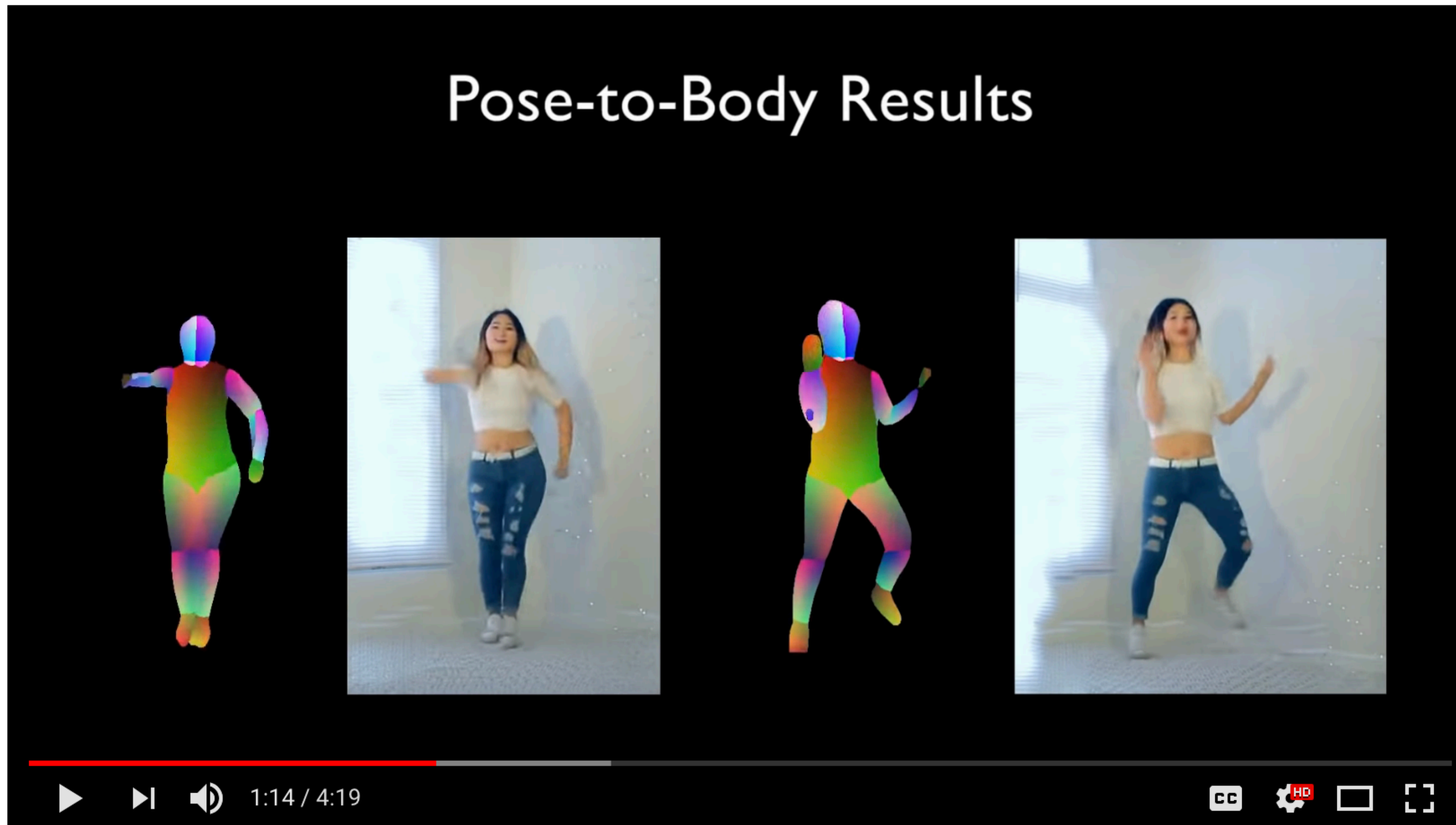
CycleGAN



(Zhu et al., 2017)

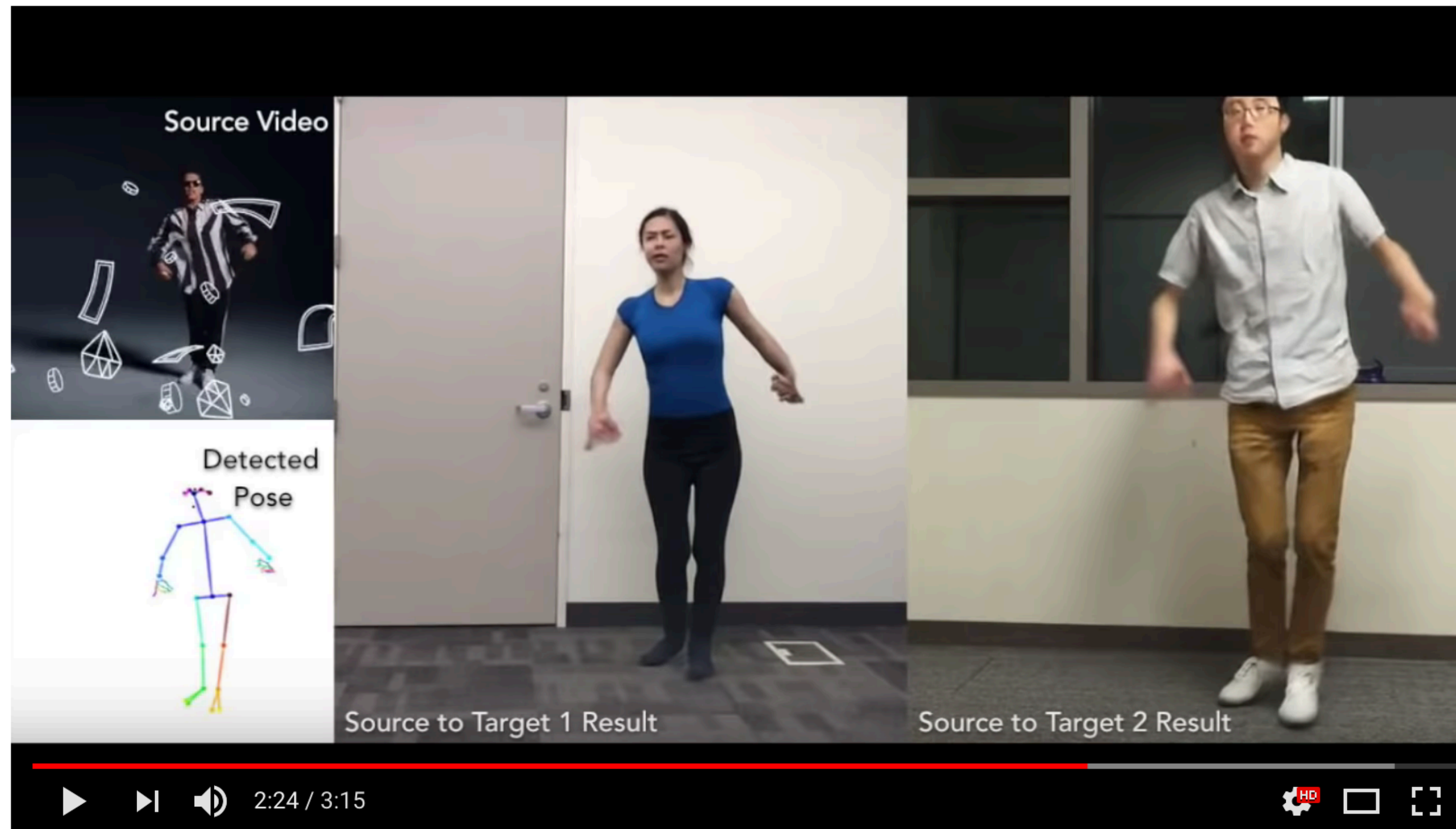
Video-to-Video

Pose-to-Body Results



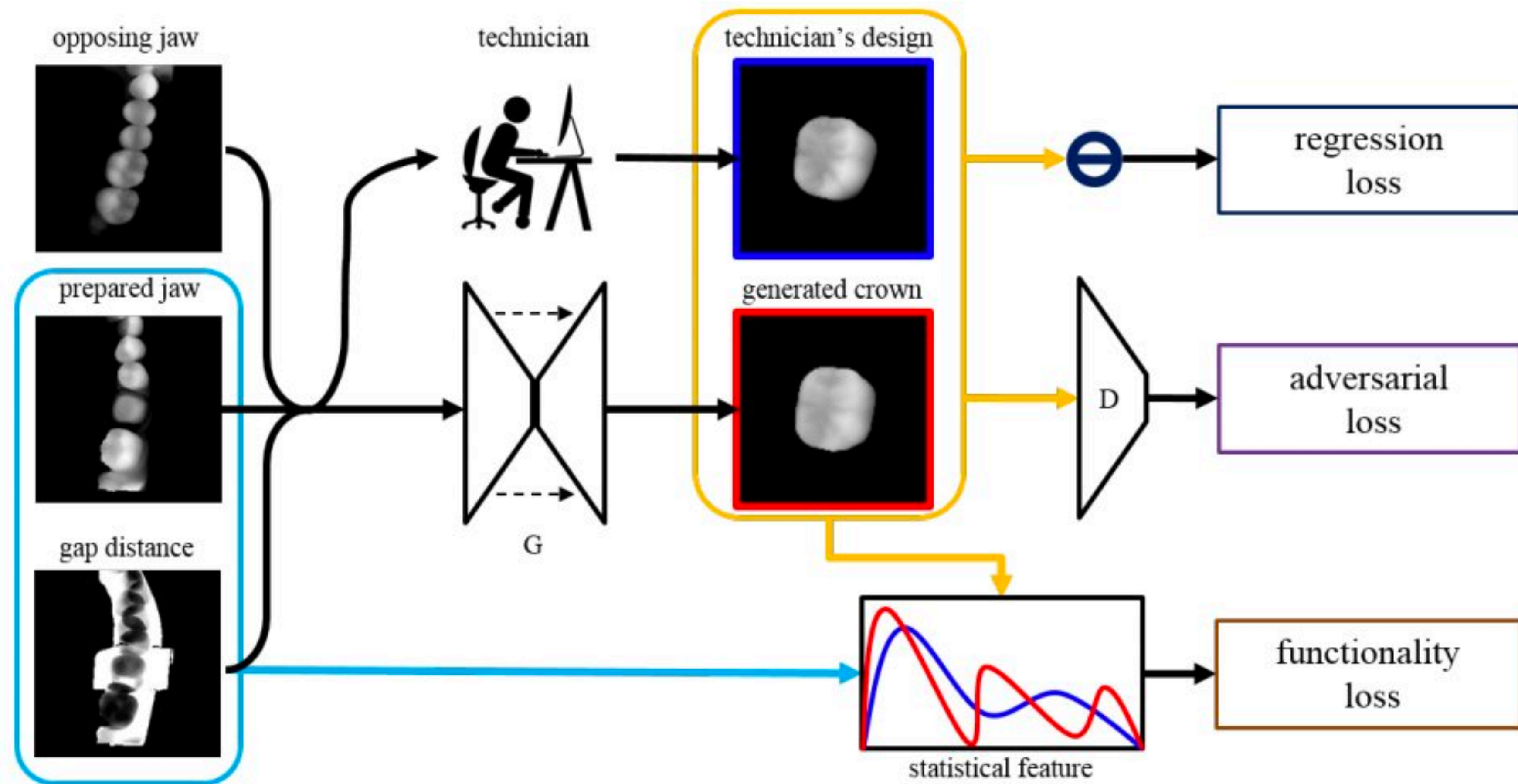
(Wang et al, 2018)

Everybody Dance Now



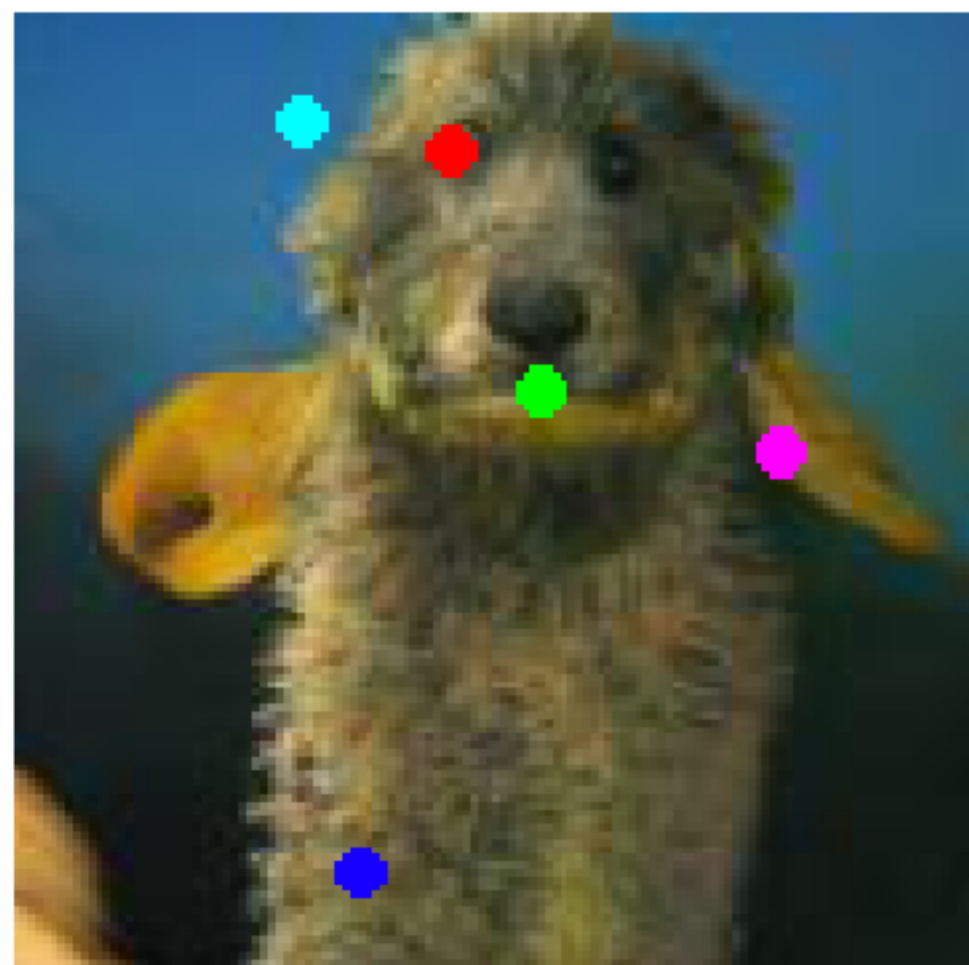
(Chan et al 2018)

Personalized GANufacturing



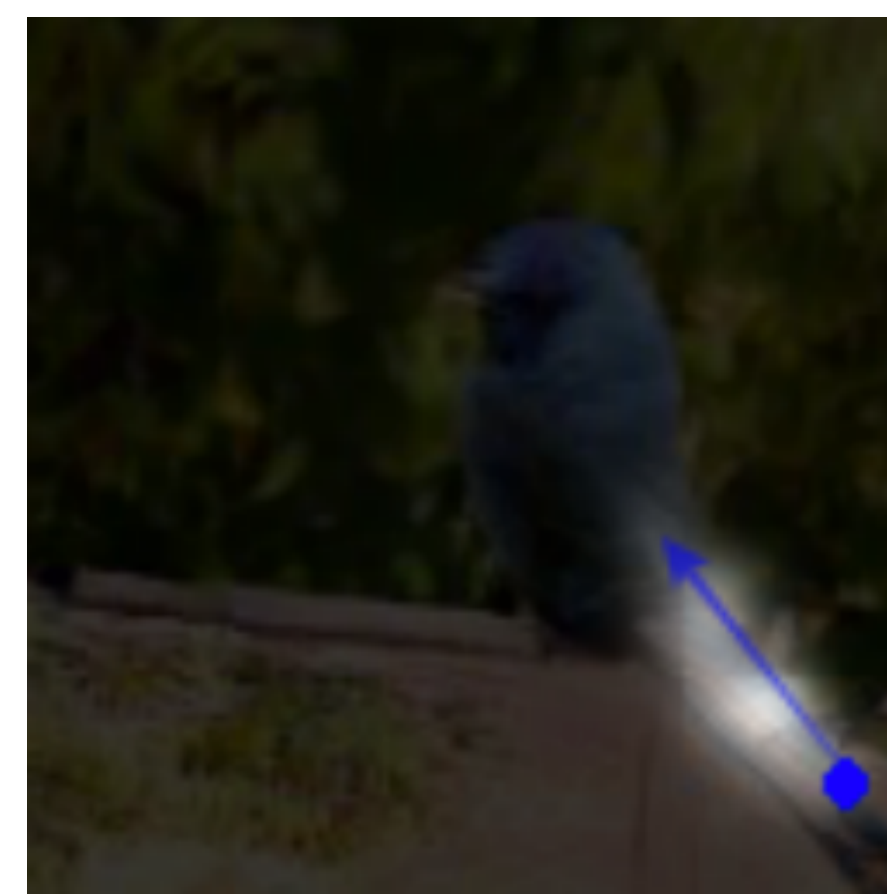
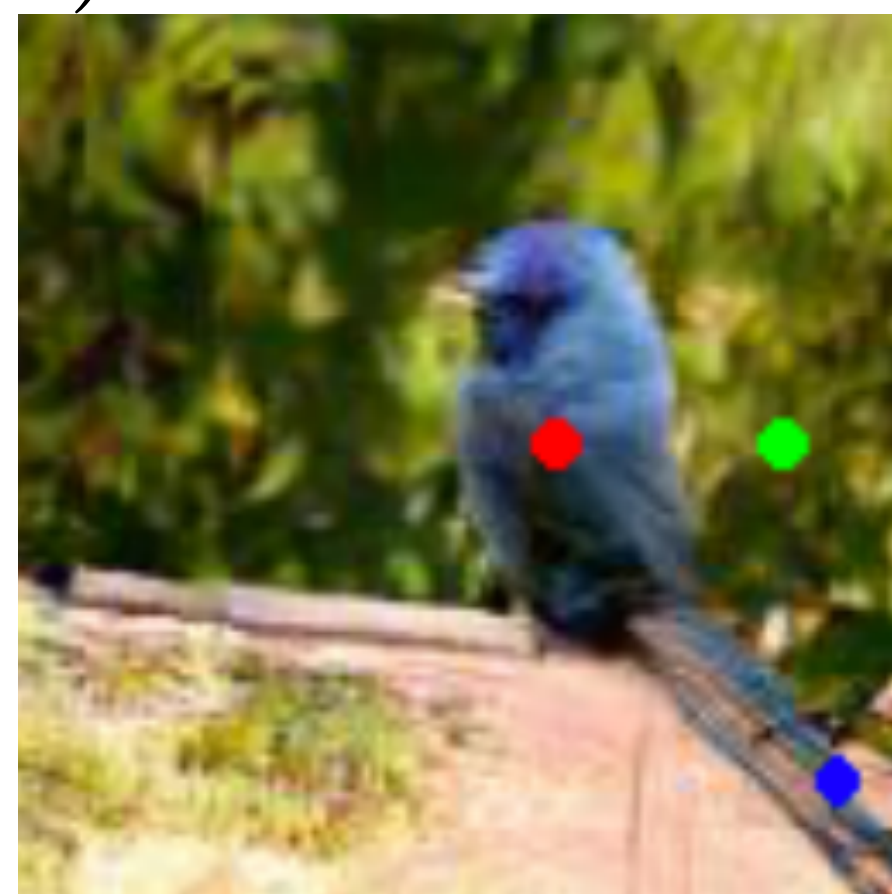
(Hwang et al 2018)

Self-Attention



(Zhang et al., 2018)

Use layers from
Wang et al 2018



Recent Advances



(Brock et al, 2018)

BigGAN

Large scale TPU
implementation



Starting sample
(Fake)



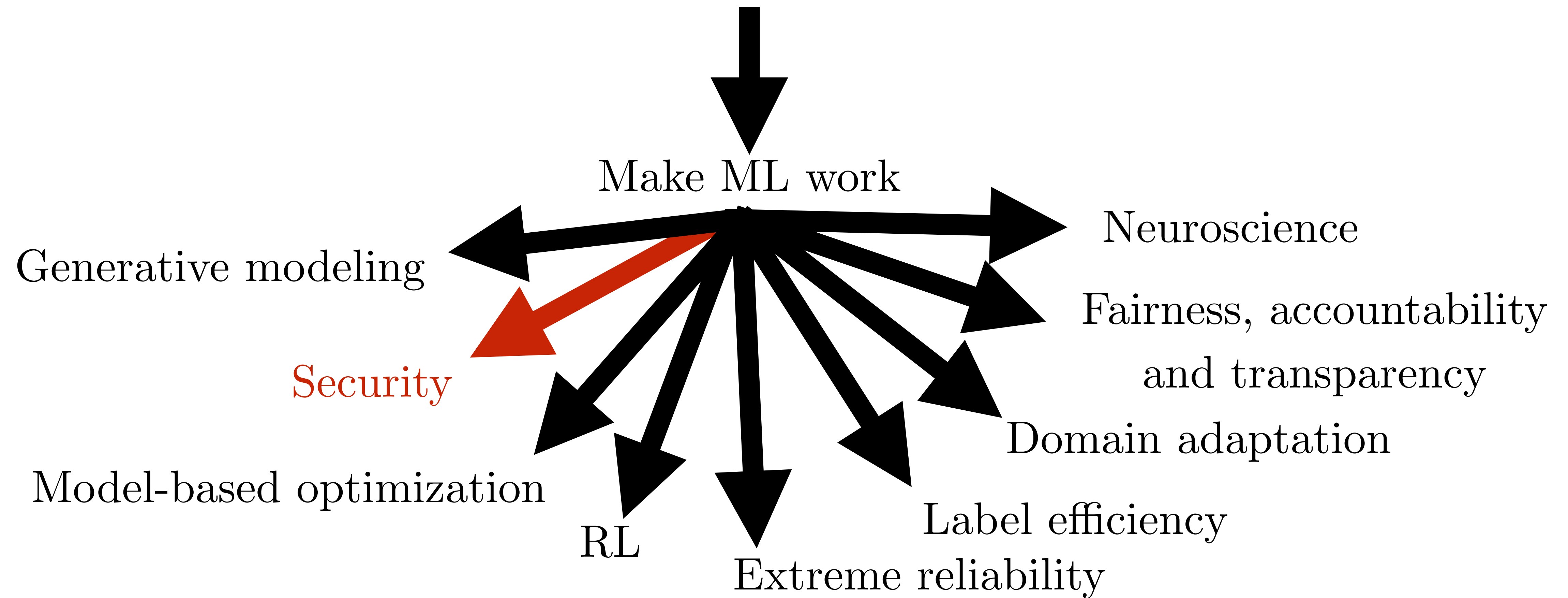
Sample for coarse
style (also fake)



Result
(still fake)

Style-based generators
(Karras et al, 2018)

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Adversarial Examples



58% panda

$+ .007 \times$



$=$

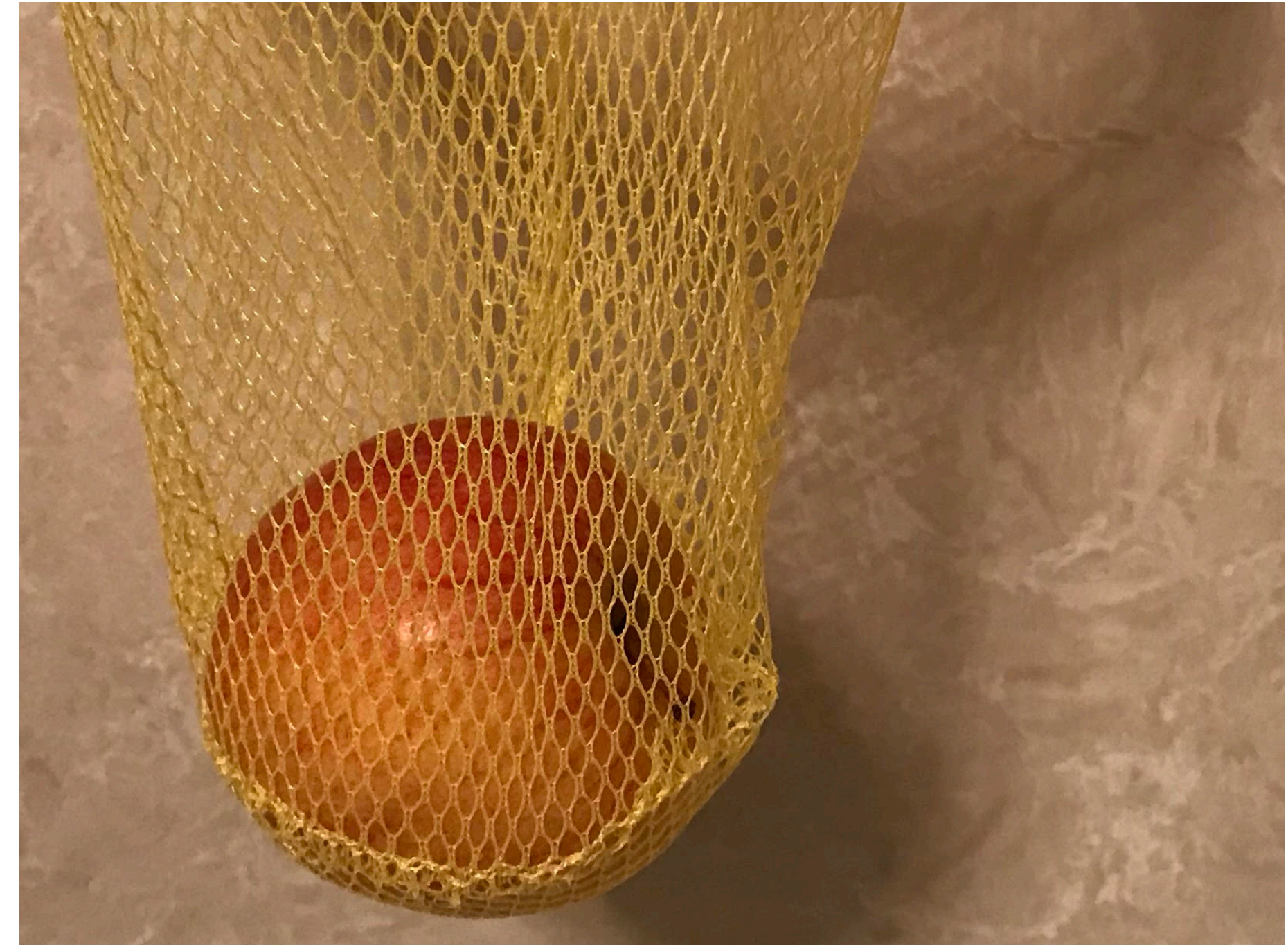


99% gibbon

Also Adversarial Examples

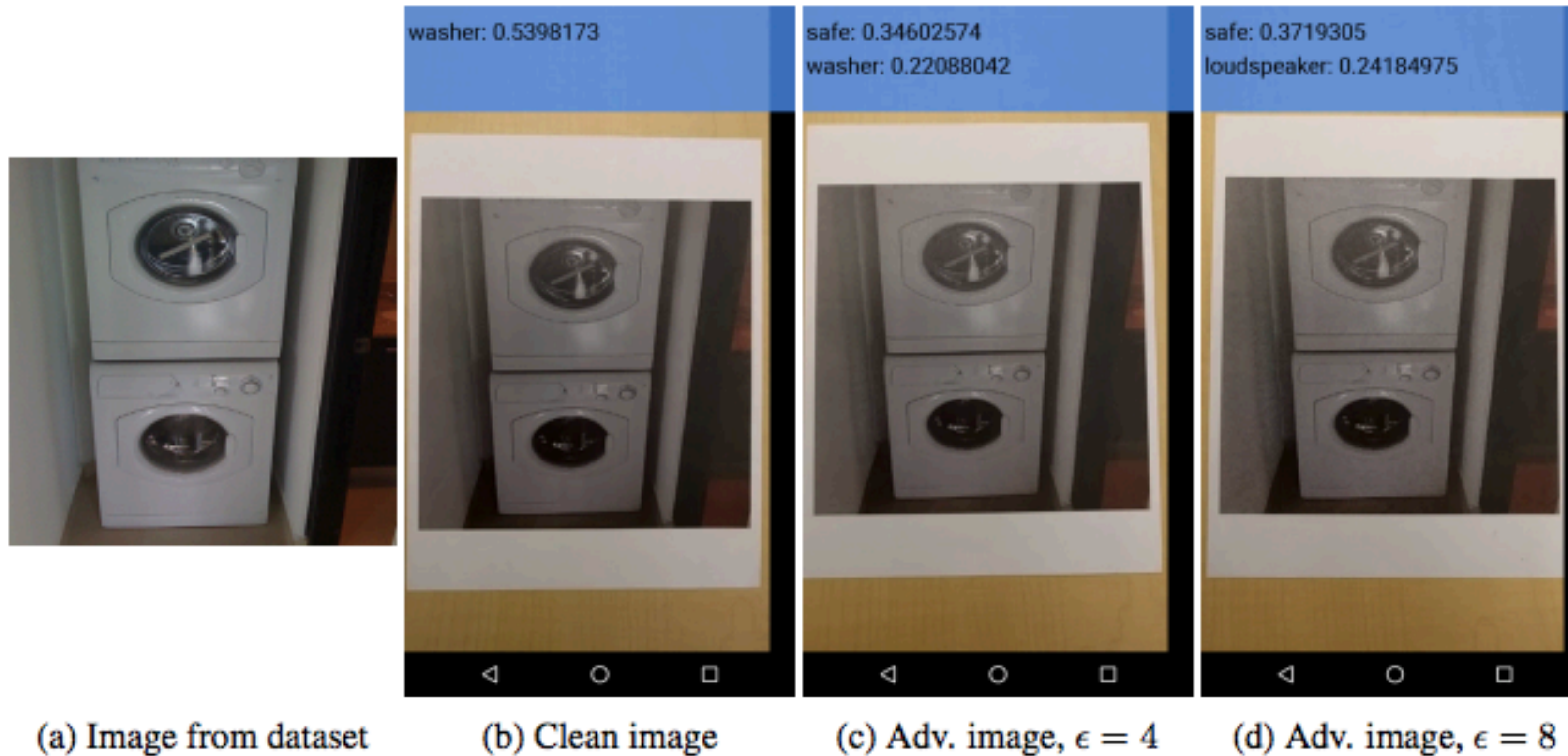


(Eykholt et al, 2017)



(Goodfellow 2018)

Adversarial Examples in the Physical World



(Kurakin et al, 2016)

Adversarial Training as a Minimax Problem

“Adversarial training can be interpreted as a minimax game,

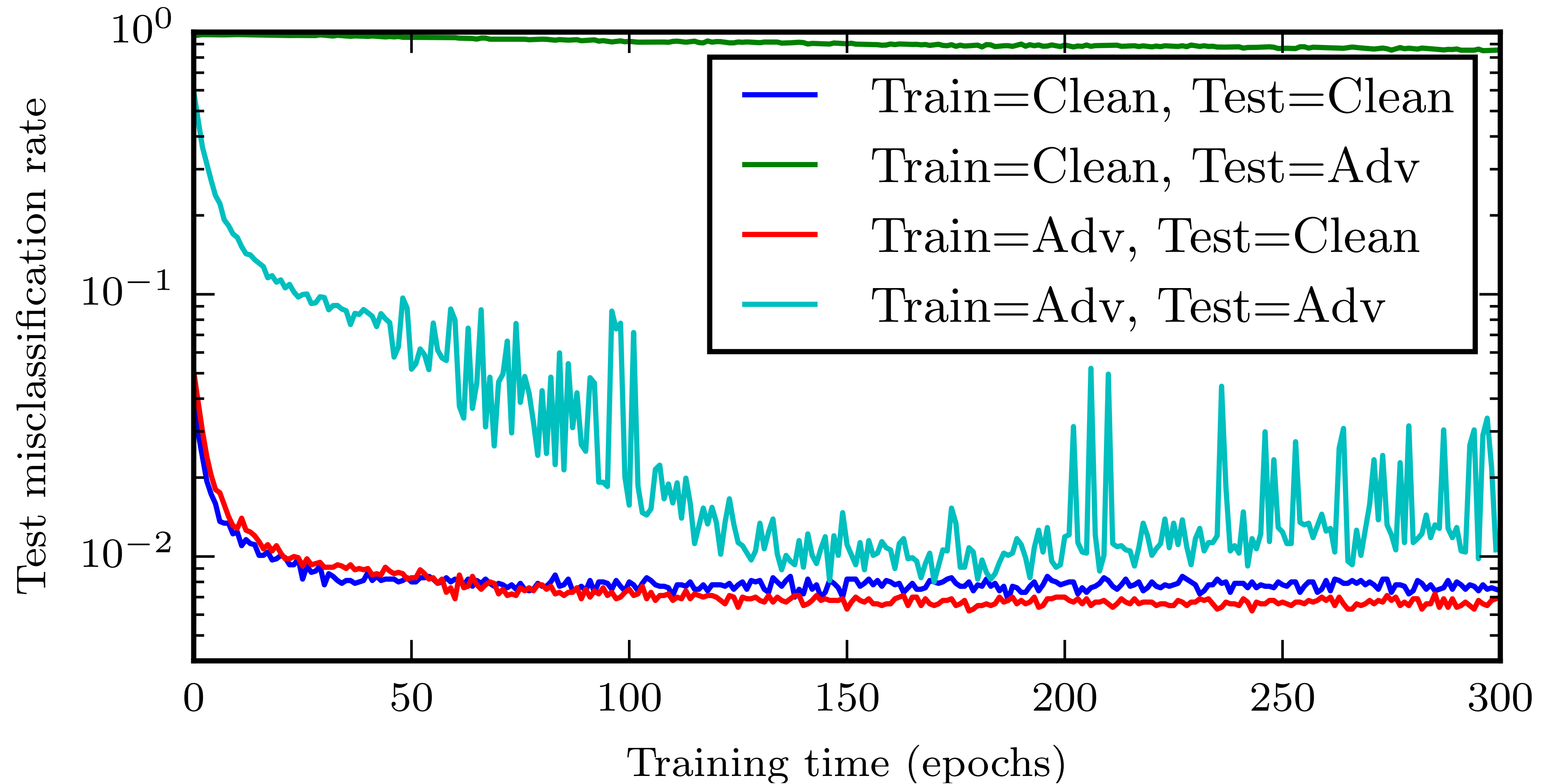
$$\boldsymbol{\theta}^* = \operatorname{argmin}_{\boldsymbol{\theta}} \mathbb{E}_{\boldsymbol{x}, y} \max_{\boldsymbol{\eta}} [J(\boldsymbol{x}, y, \boldsymbol{\theta}) + J(\boldsymbol{x} + \boldsymbol{\eta}, y)],$$

with the learning algorithm as the minimizing player and a fixed procedure (such as L-BFGS or the fast gradient sign method) as the maximizing player.”

Original implementation: Goodfellow et al 2014

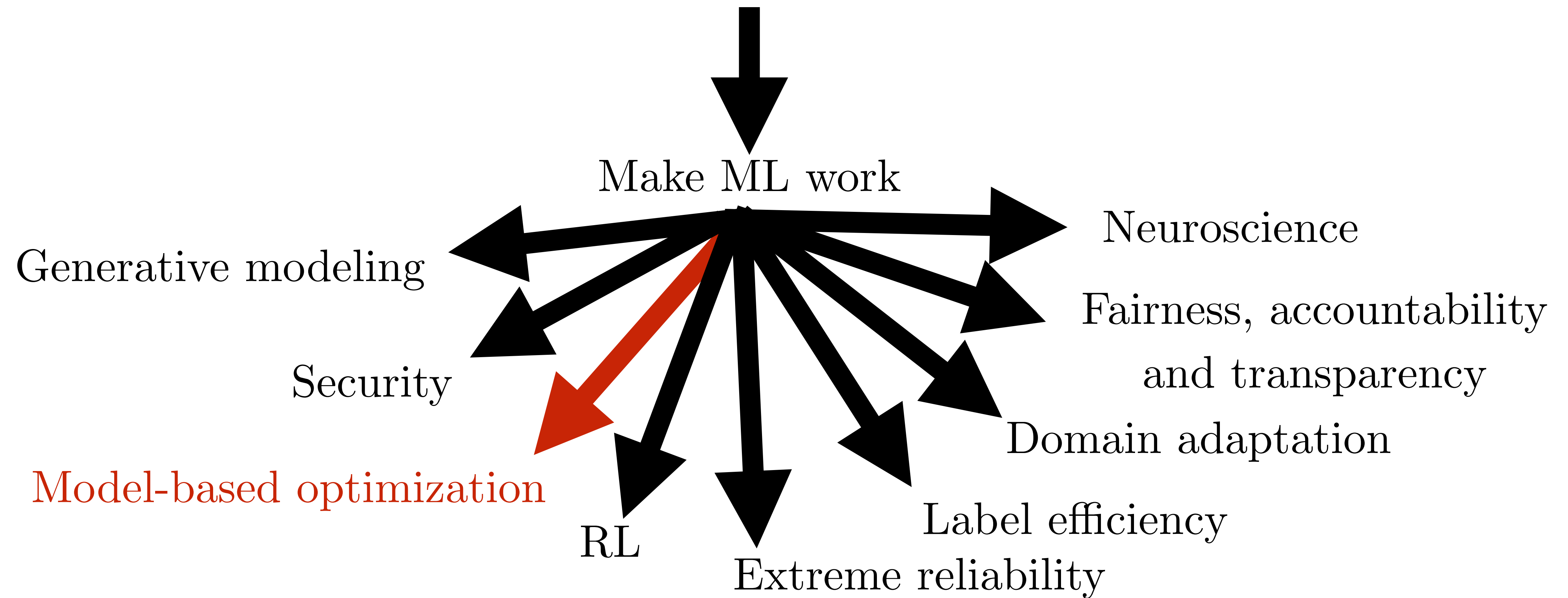
Explicit use of “minimax”: Farley and Goodfellow, 2016

Training on Adversarial Examples



(CleverHans tutorial, using method of Goodfellow et al 2014)

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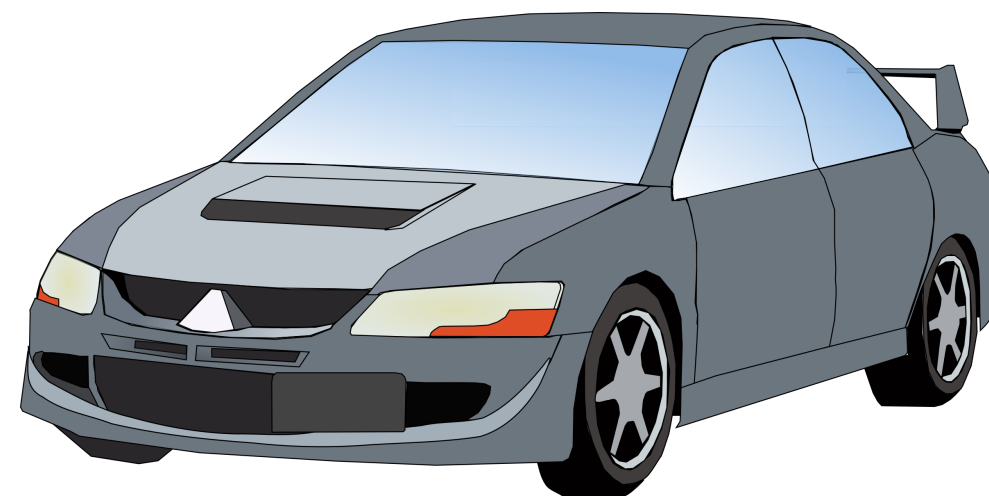
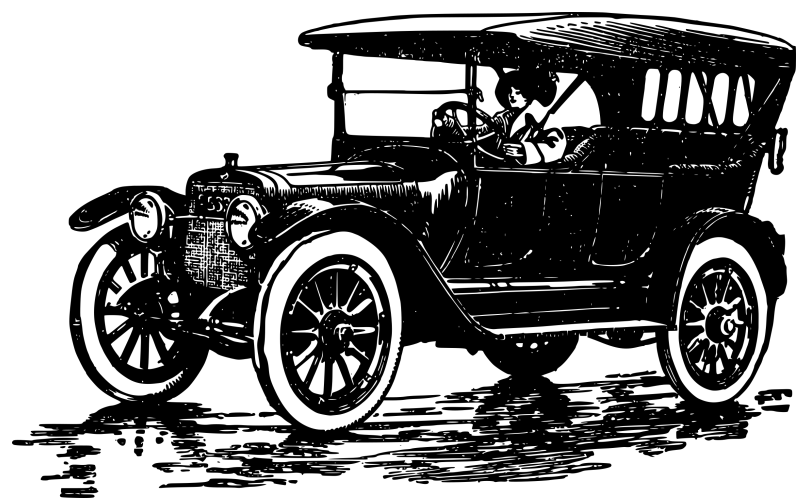


Model-Based Optimization

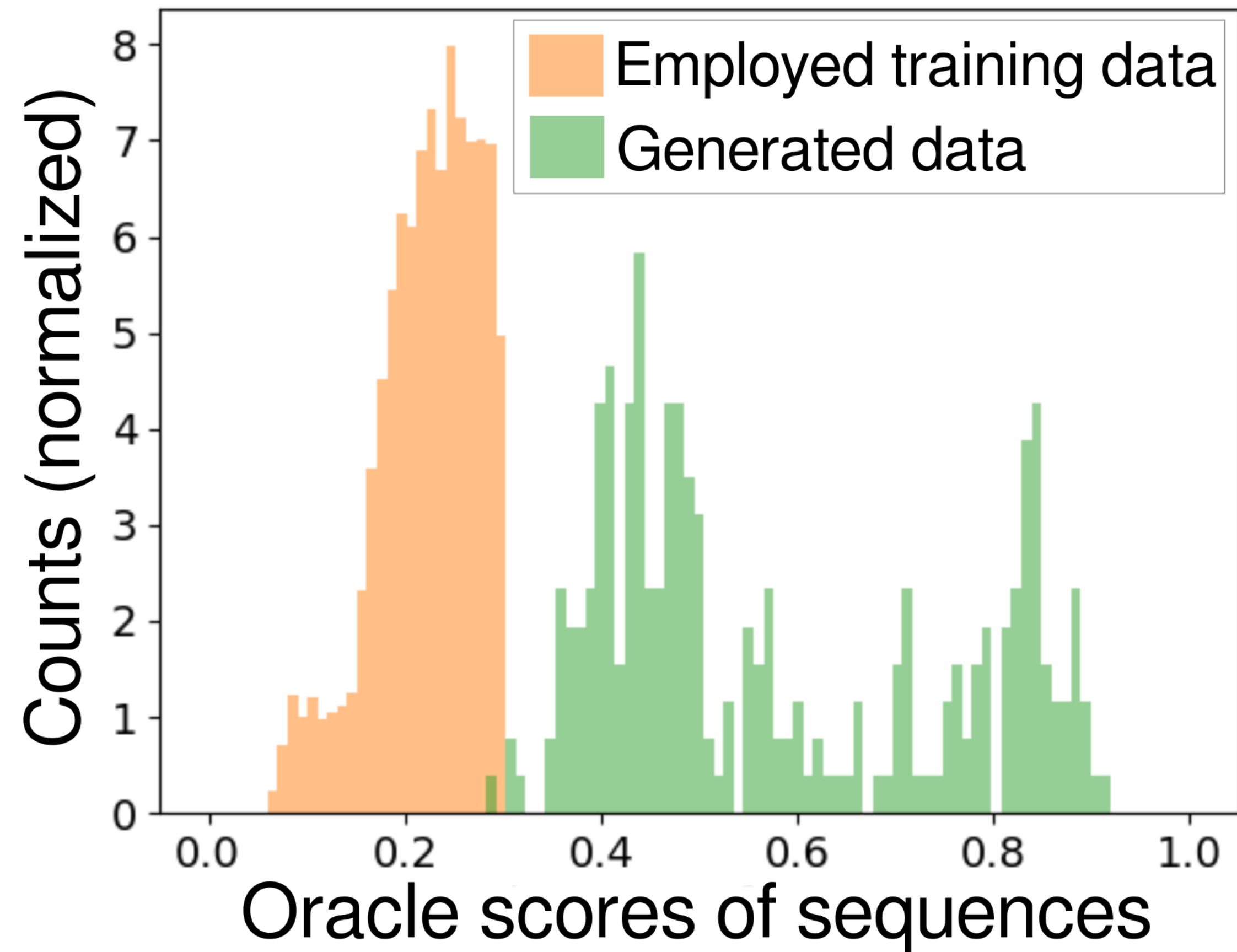
Make new inventions by finding input
that maximizes model's predicted
performance

Training data

Extrapolation



Designing DNA to optimize protein function

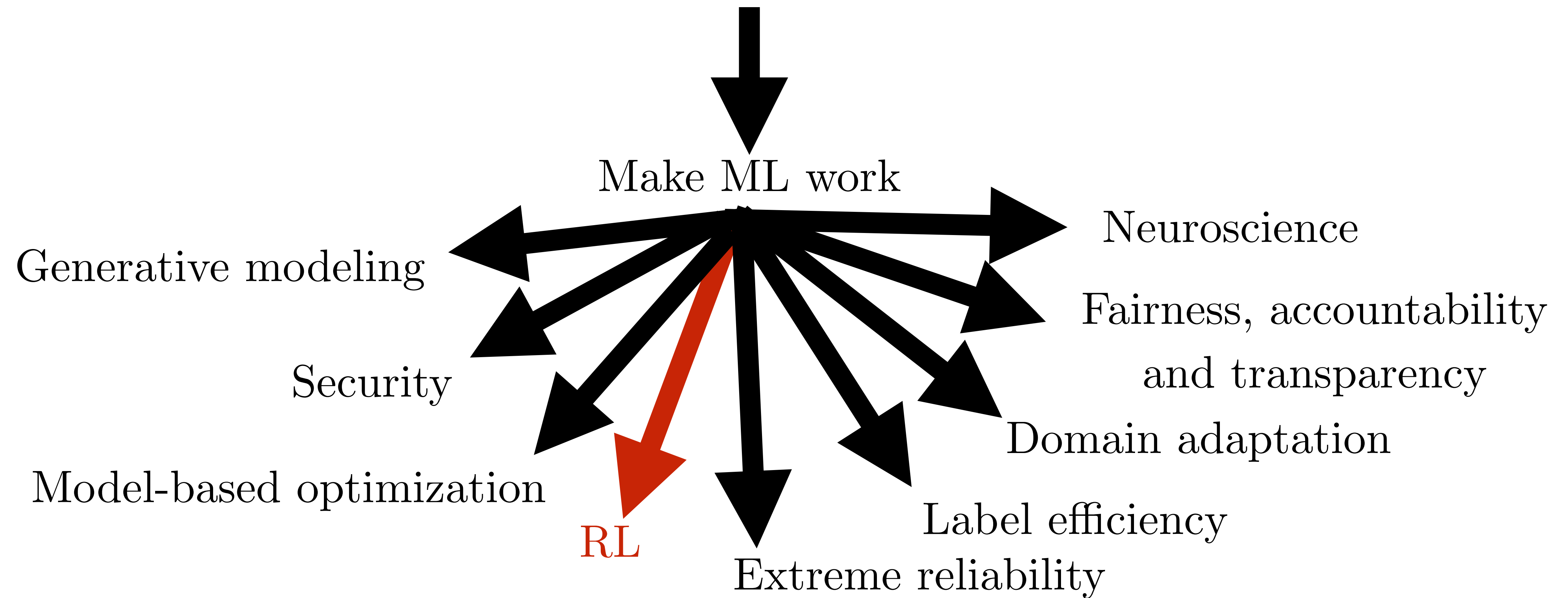


(Killoran et al, 2017)

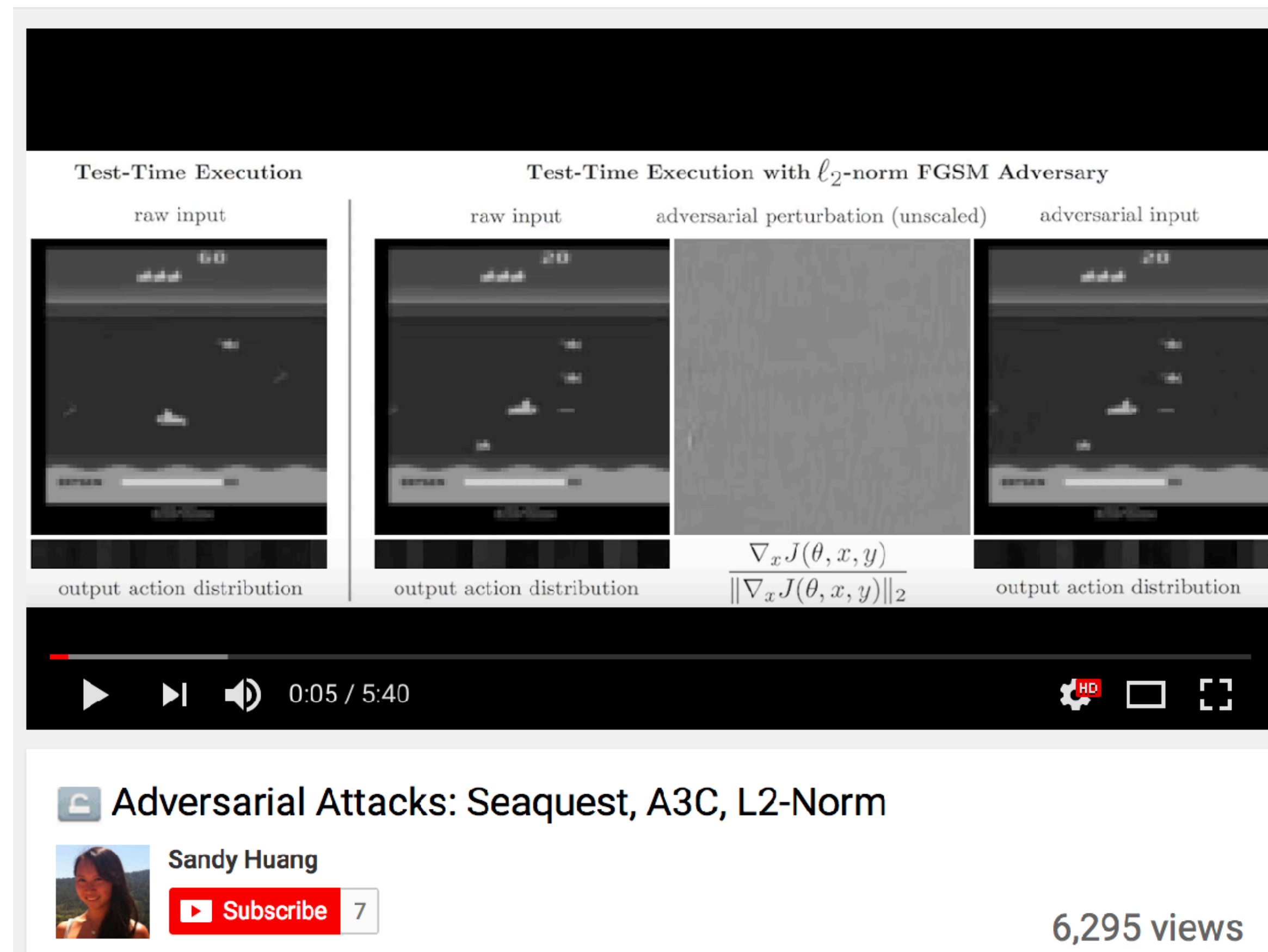


(Gupta and Zou, 2018)

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Adversarial Examples for RL



(Huang et al., 2017)

Self-Play

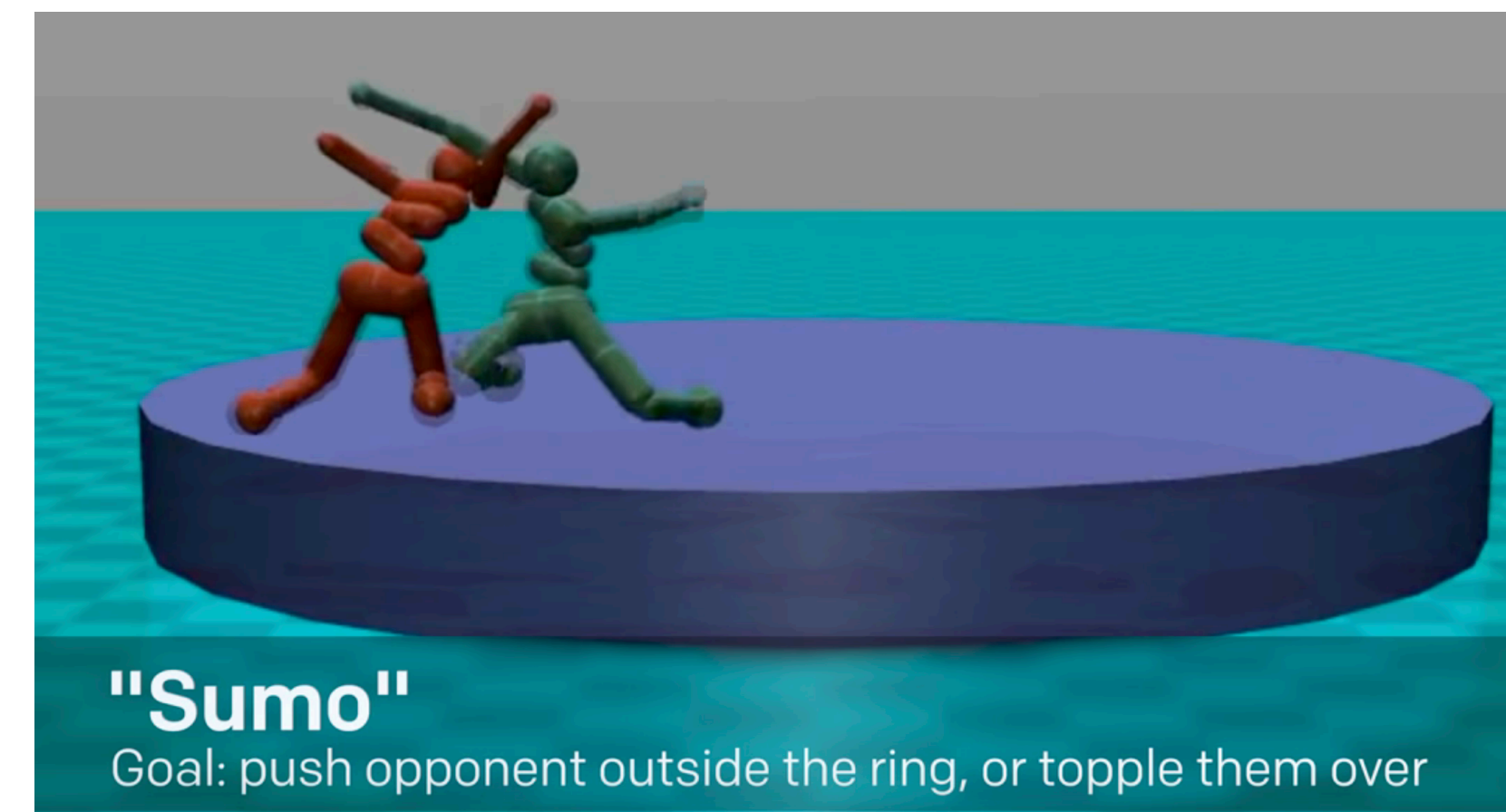
1959: Arthur Samuel's checkers agent



(Silver et al, 2017)



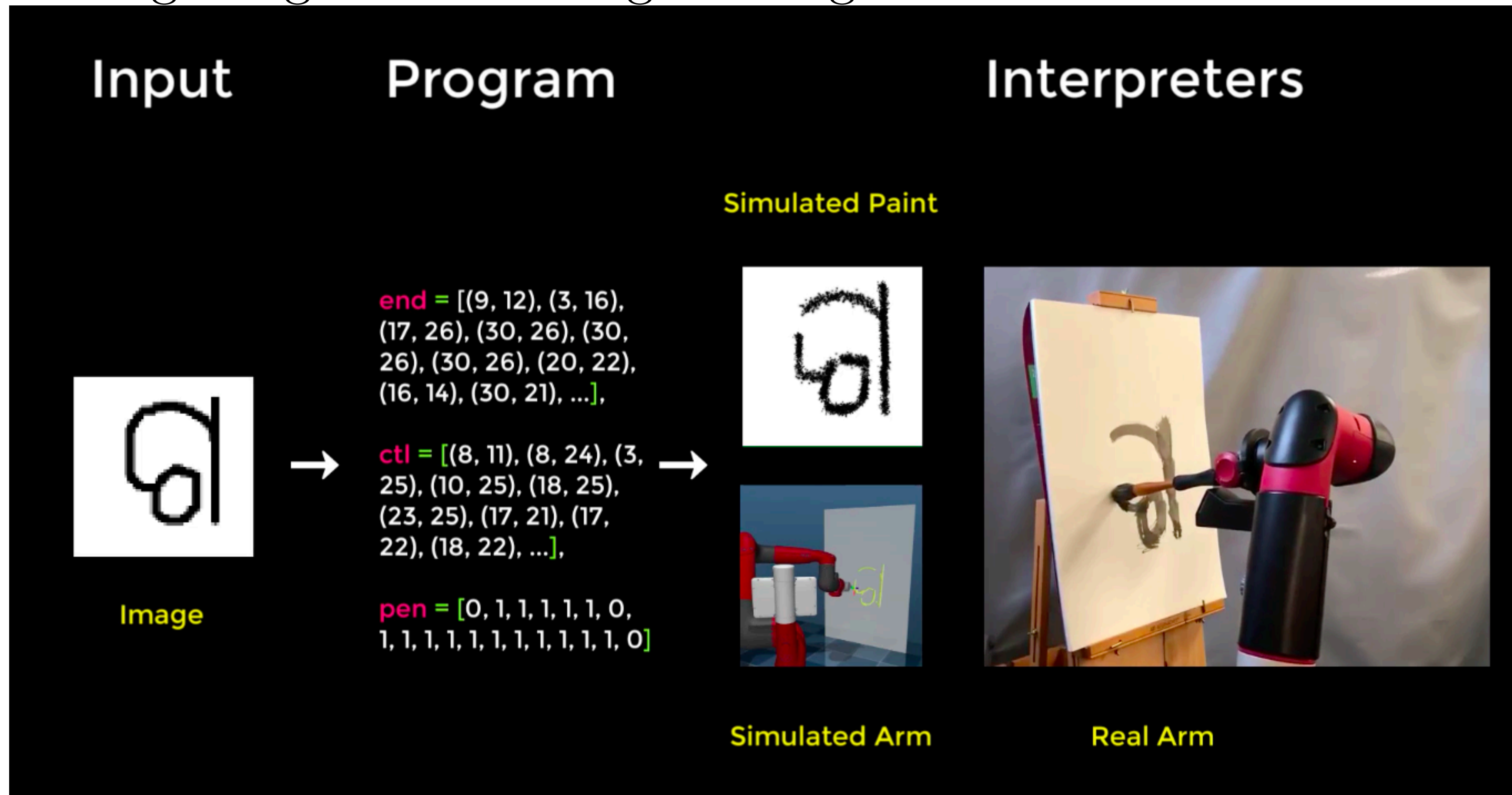
(OpenAI, 2017)



(Bansal et al, 2017)

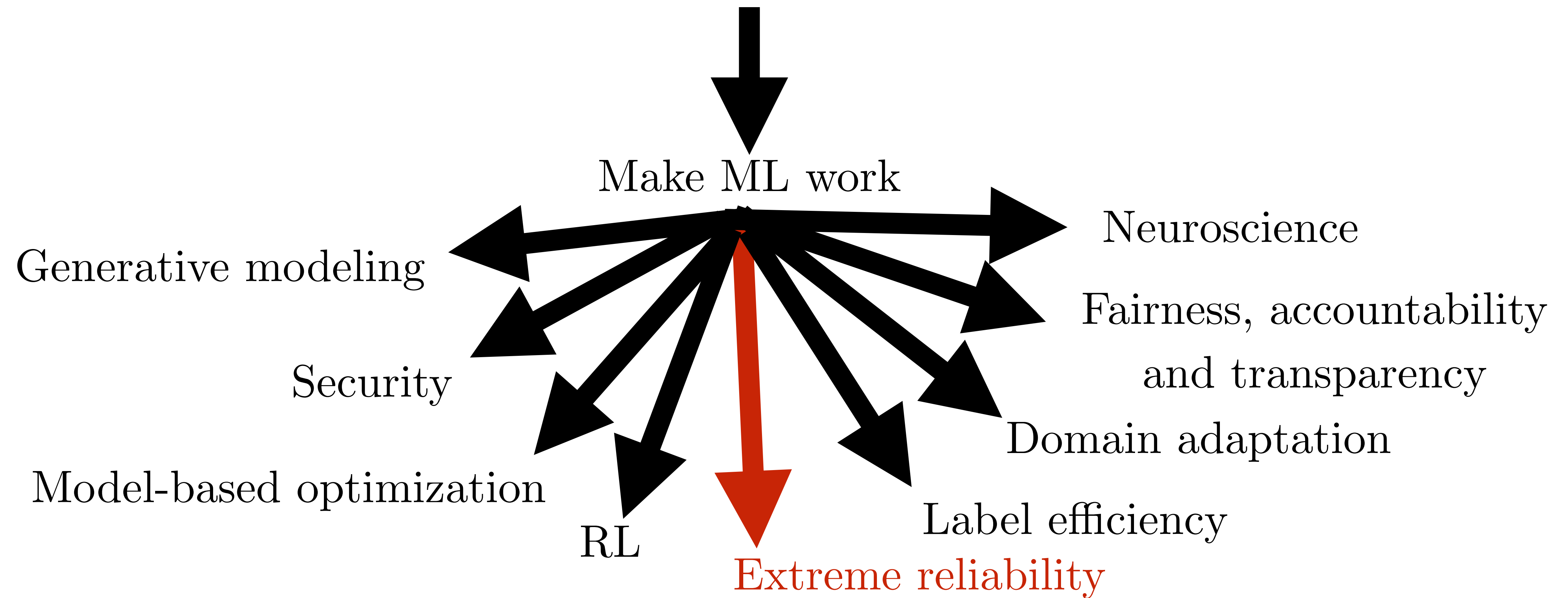
SPIRAL

Synthesizing Programs for Images Using Reinforced Adversarial Learning



(Ganin et al, 2018)

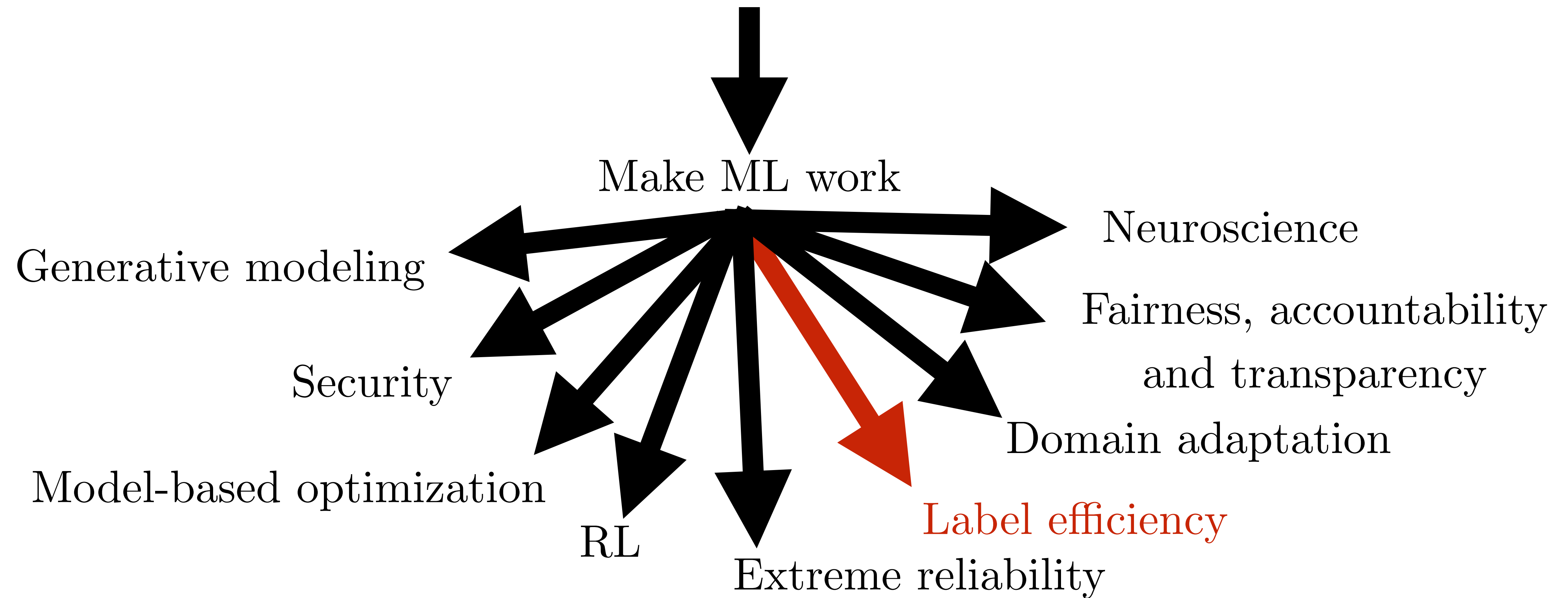
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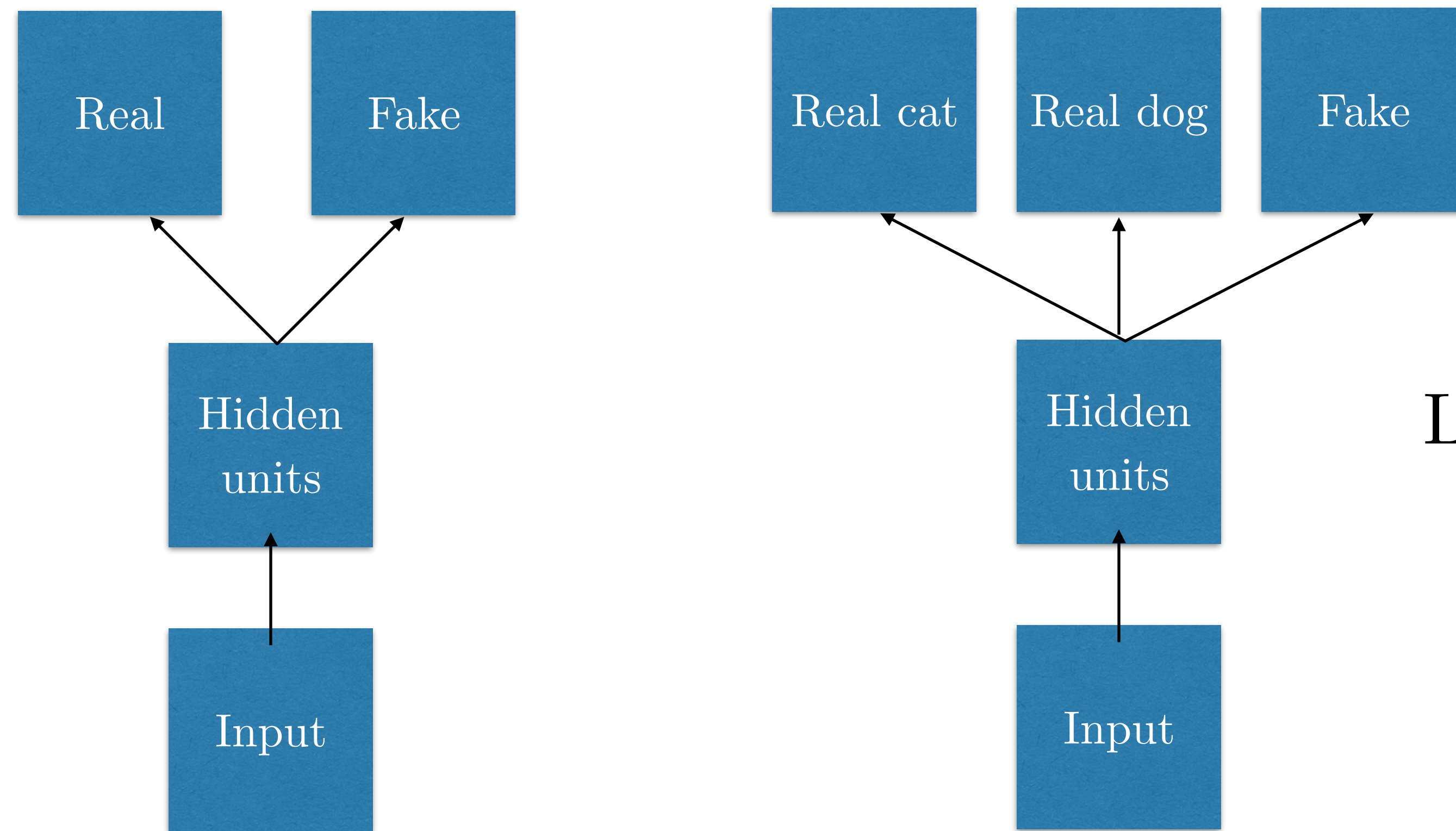
Extreme Reliability

- We want extreme reliability for
 - Autonomous vehicles
 - Air traffic control
 - Surgery robots
 - Medical diagnosis, etc.
- Adversarial machine learning research techniques can help with this
 - Katz et al 2017: verification system, applied to air traffic control

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Supervised Discriminator for Semi-Supervised Learning

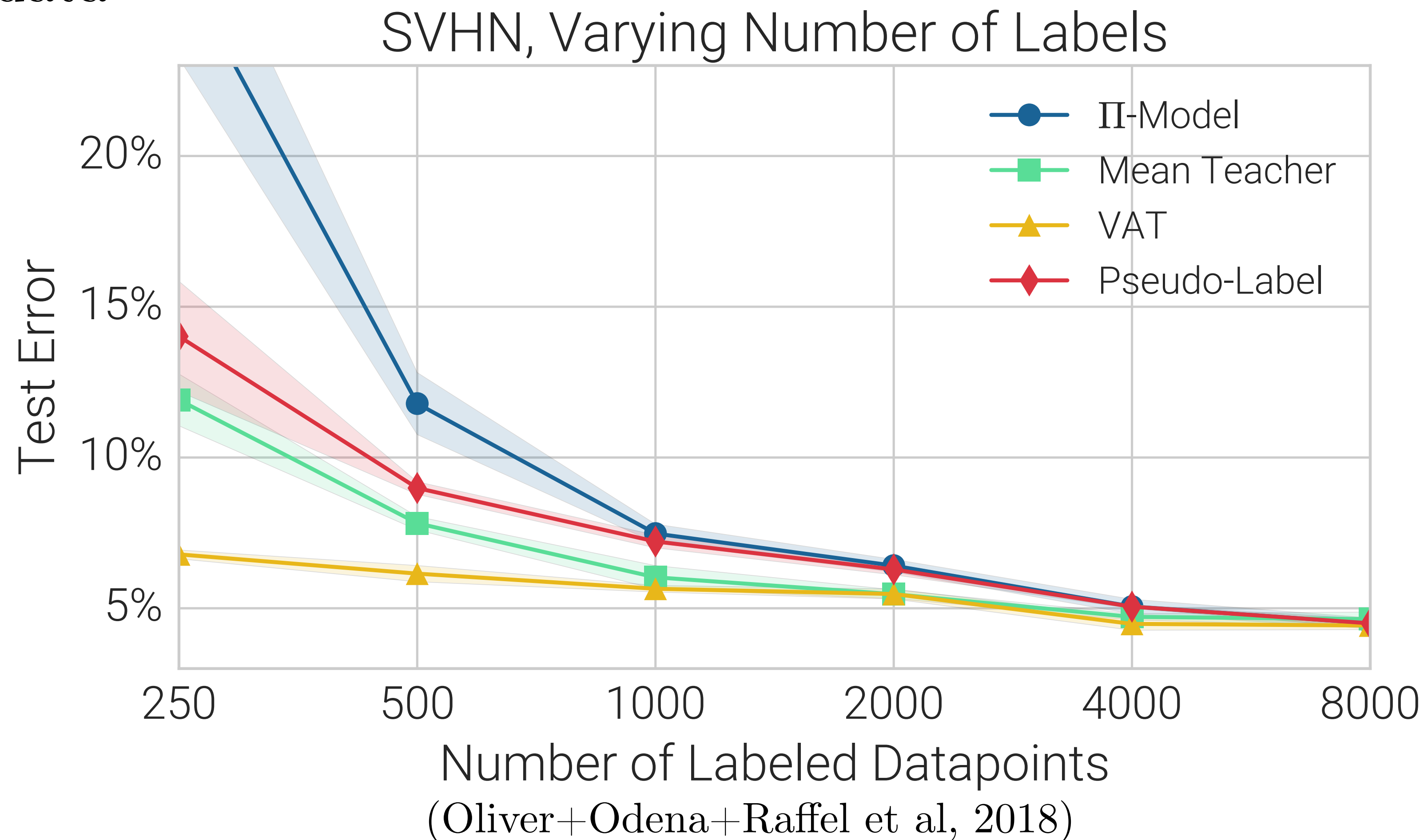


Learn to read with
100 labels rather
than 60,000

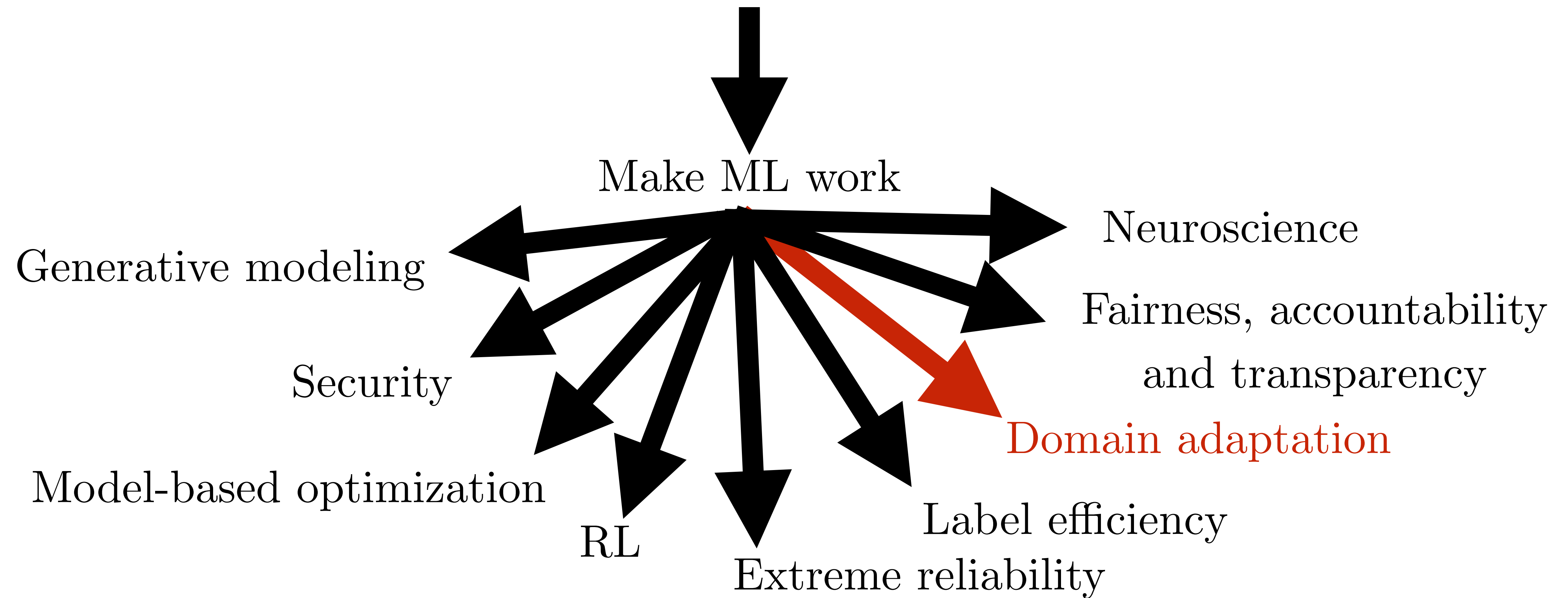
(Odena 2016, Salimans et al 2016)

Virtual Adversarial Training

Miyato et al 2015: regularize for robustness to adversarial perturbations of *unlabeled* data



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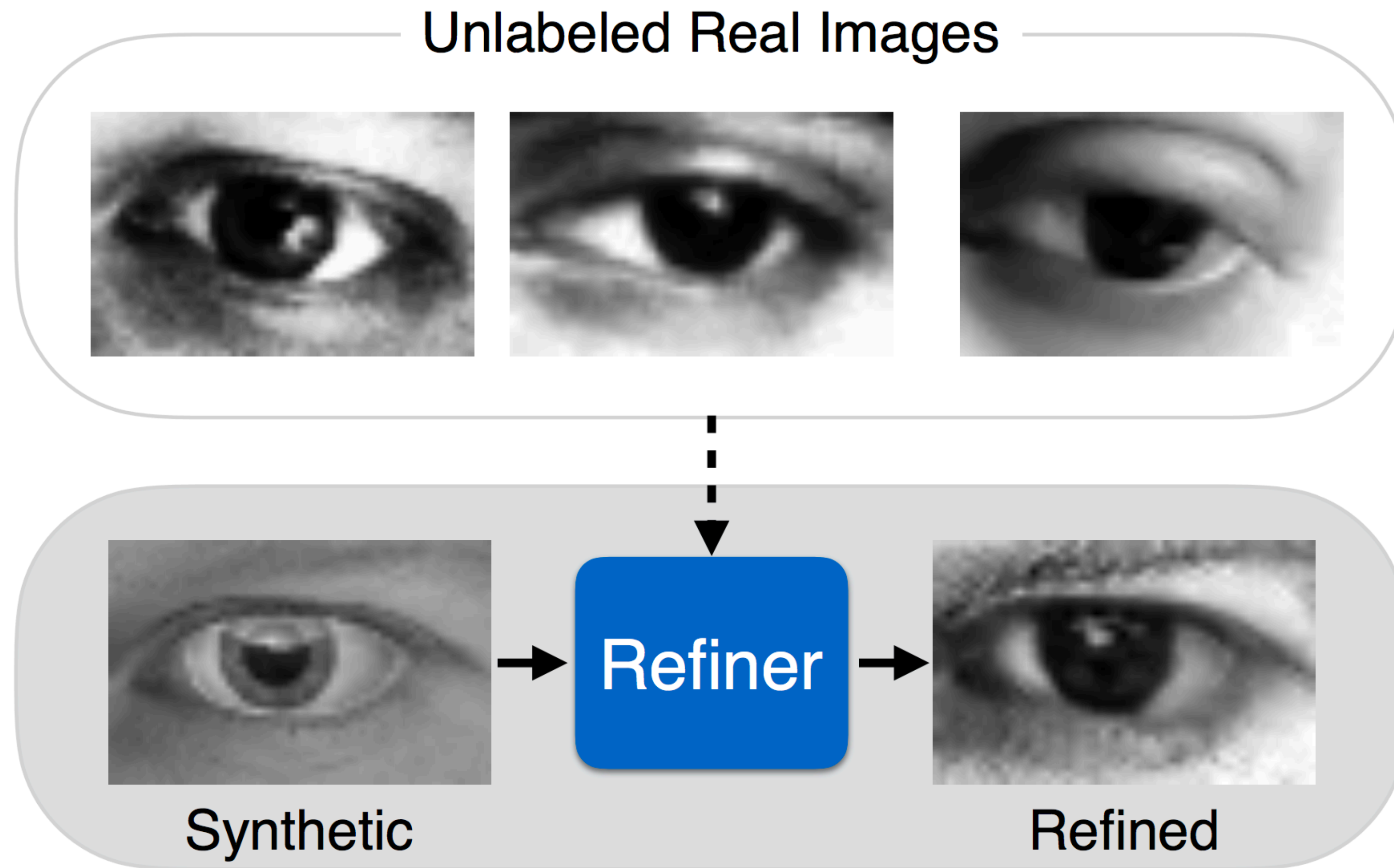
Domain Adaptation

- Domain Adversarial Networks (Ganin et al, 2015)



- Professor forcing (Lamb et al, 2016): Domain-Adversarial learning in RNN hidden state

GANs for simulated training data



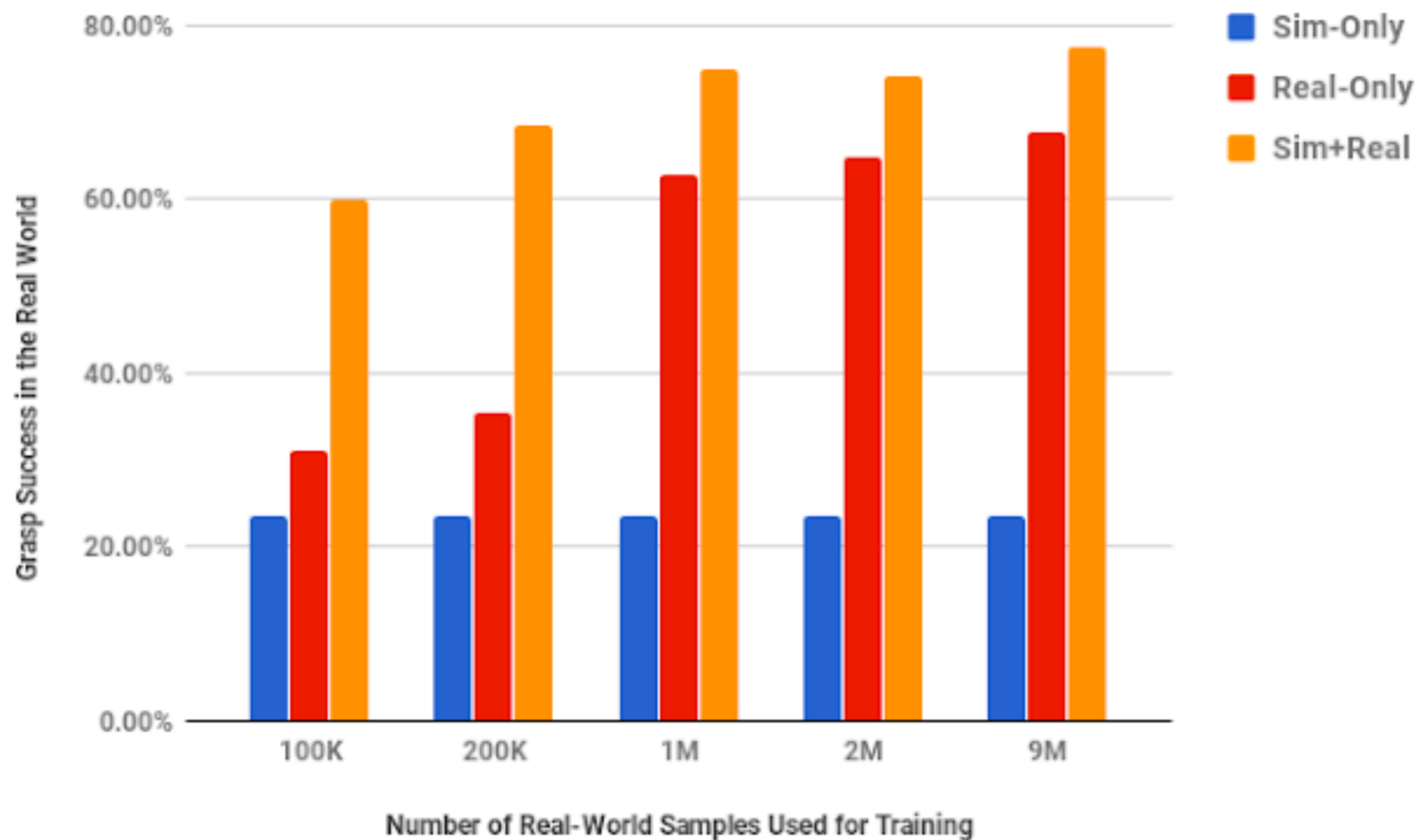
(Shrivastava et al., 2016)

GraspGAN



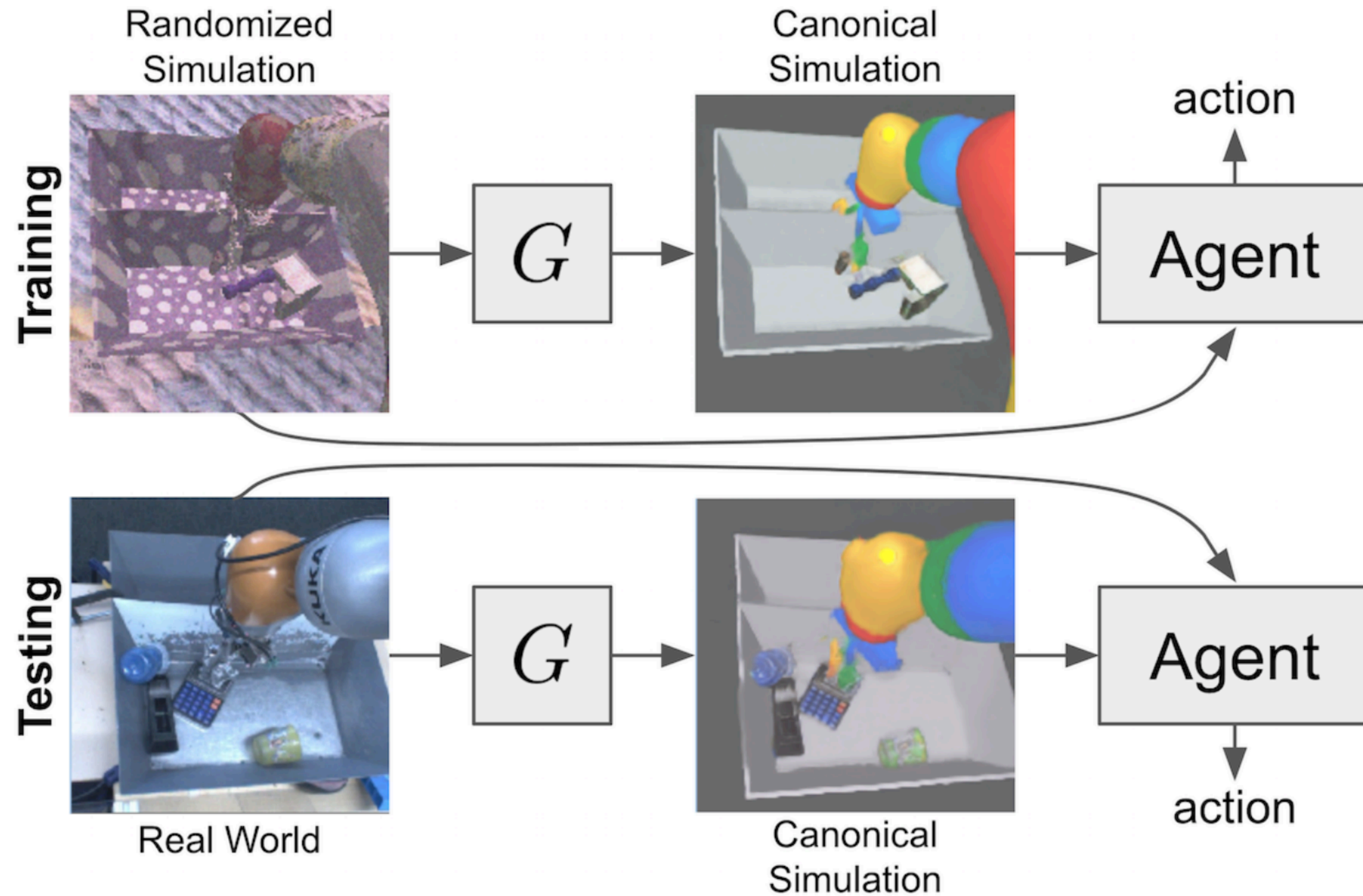
(Bousmalis et al, 2017)

GraspGAN



(Bousmalis et al, 2017)

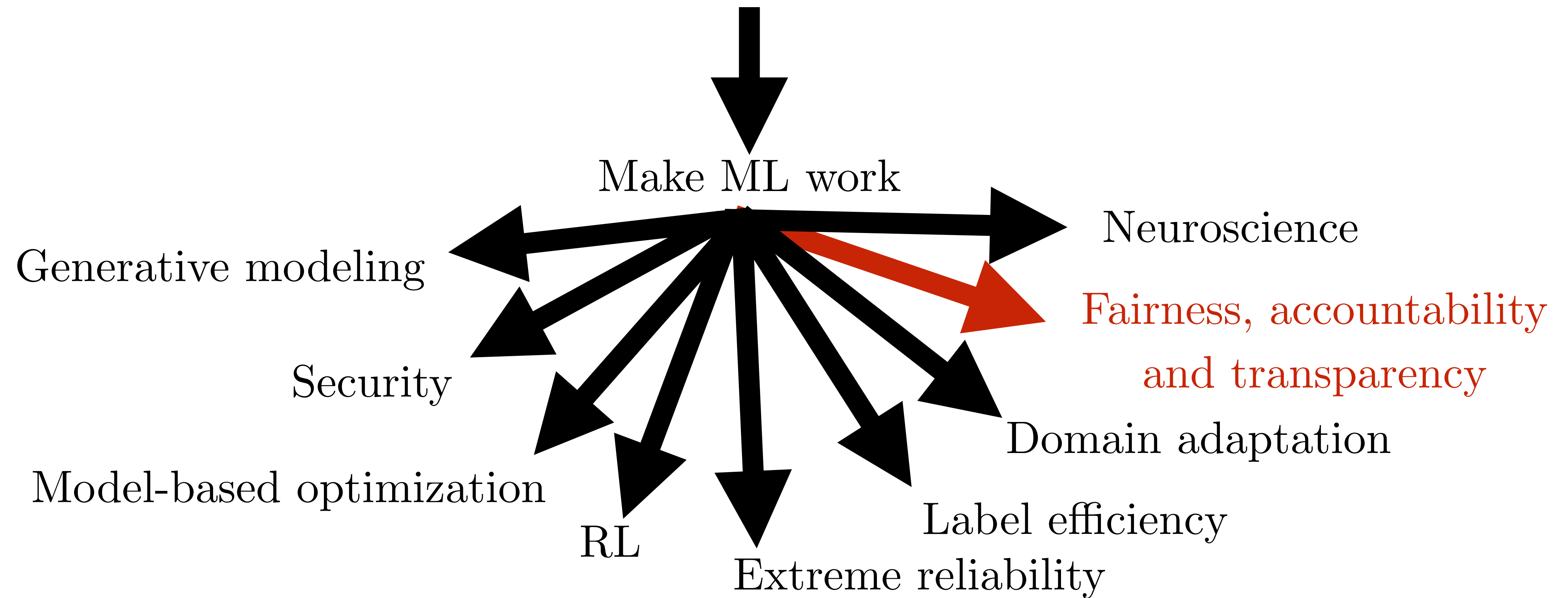
Sim-to-real via sim-to-sim



Learn to grasp
without real data!

(James et al, 2018)

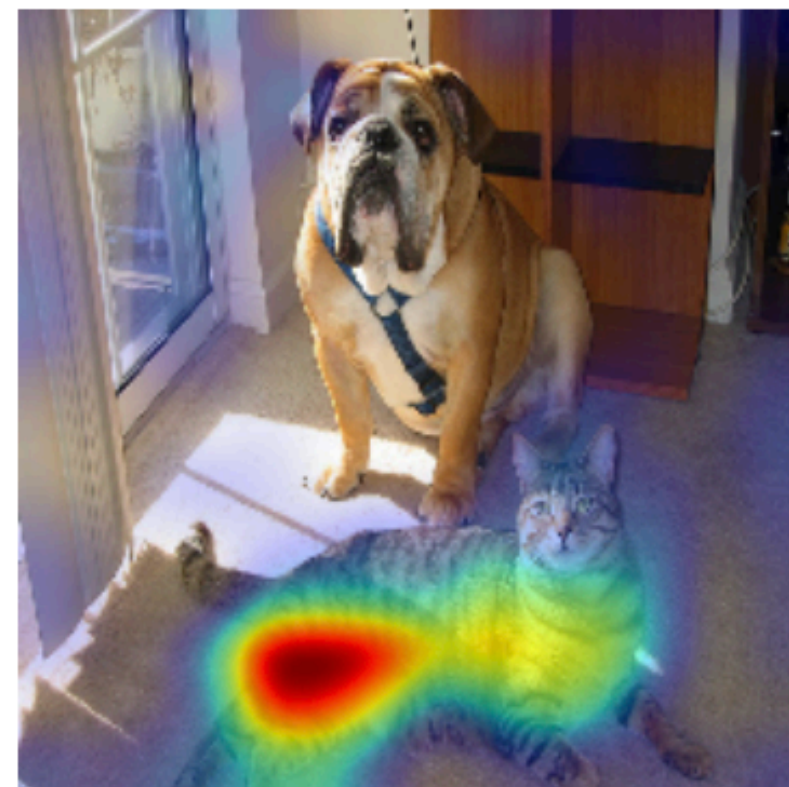
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Adversarially Learned Fair Representations

- Edwards and Storkey 2015
- Learn representations that are useful for classification
- An adversary tries to recover a sensitive variable S from the representation. Primary learner tries to make S impossible to recover
- Final decision does not depend on S

How do machine learning models work?

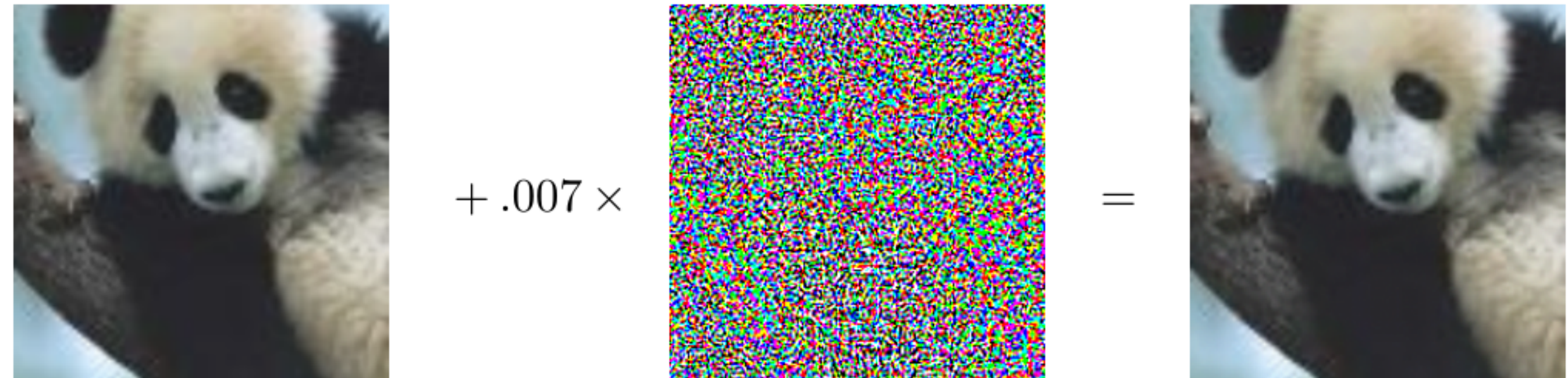


(c) Grad-CAM 'Cat'



(i) Grad-CAM 'Dog'

(Selvaraju et al, 2016)

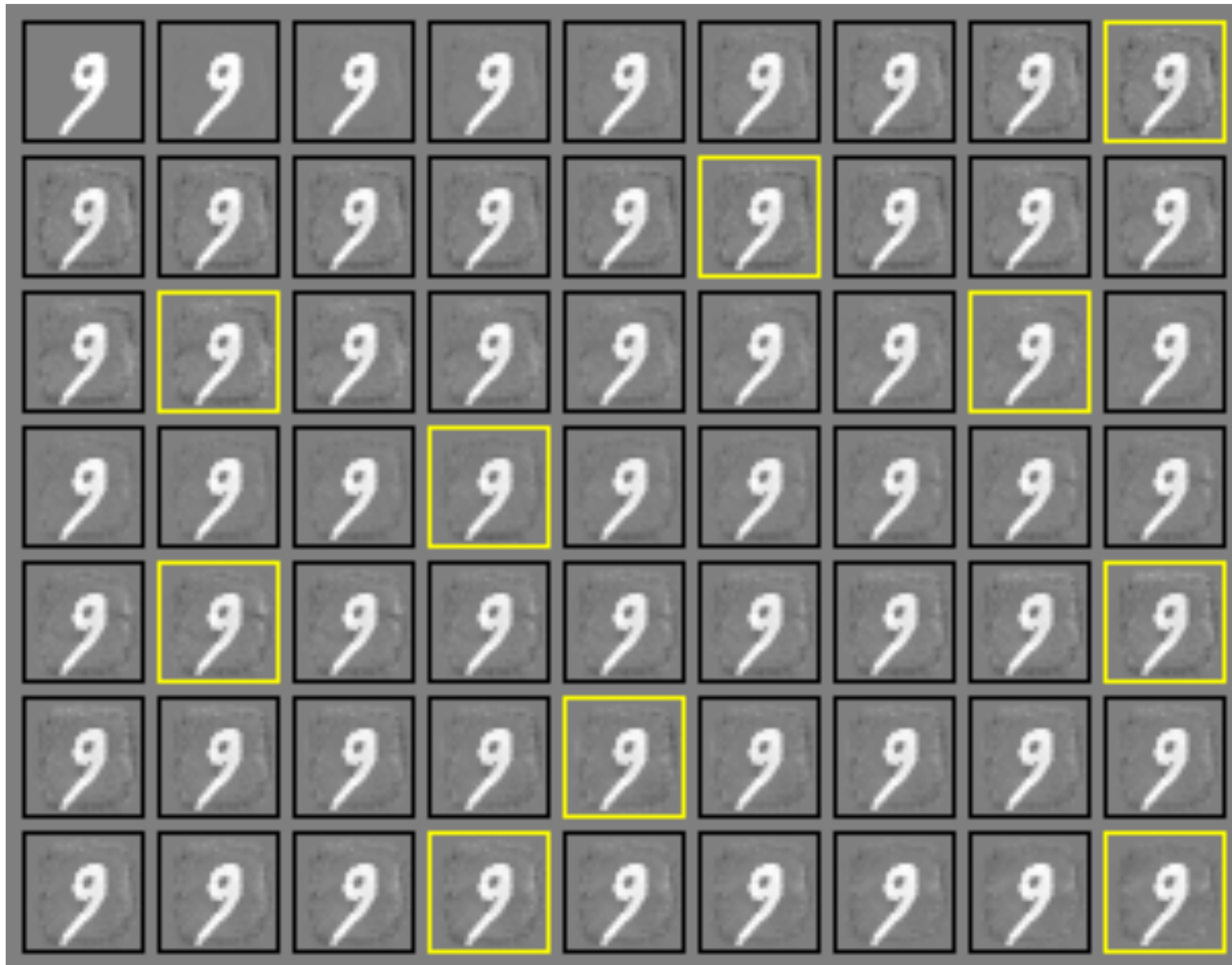


(Goodfellow et al, 2014)

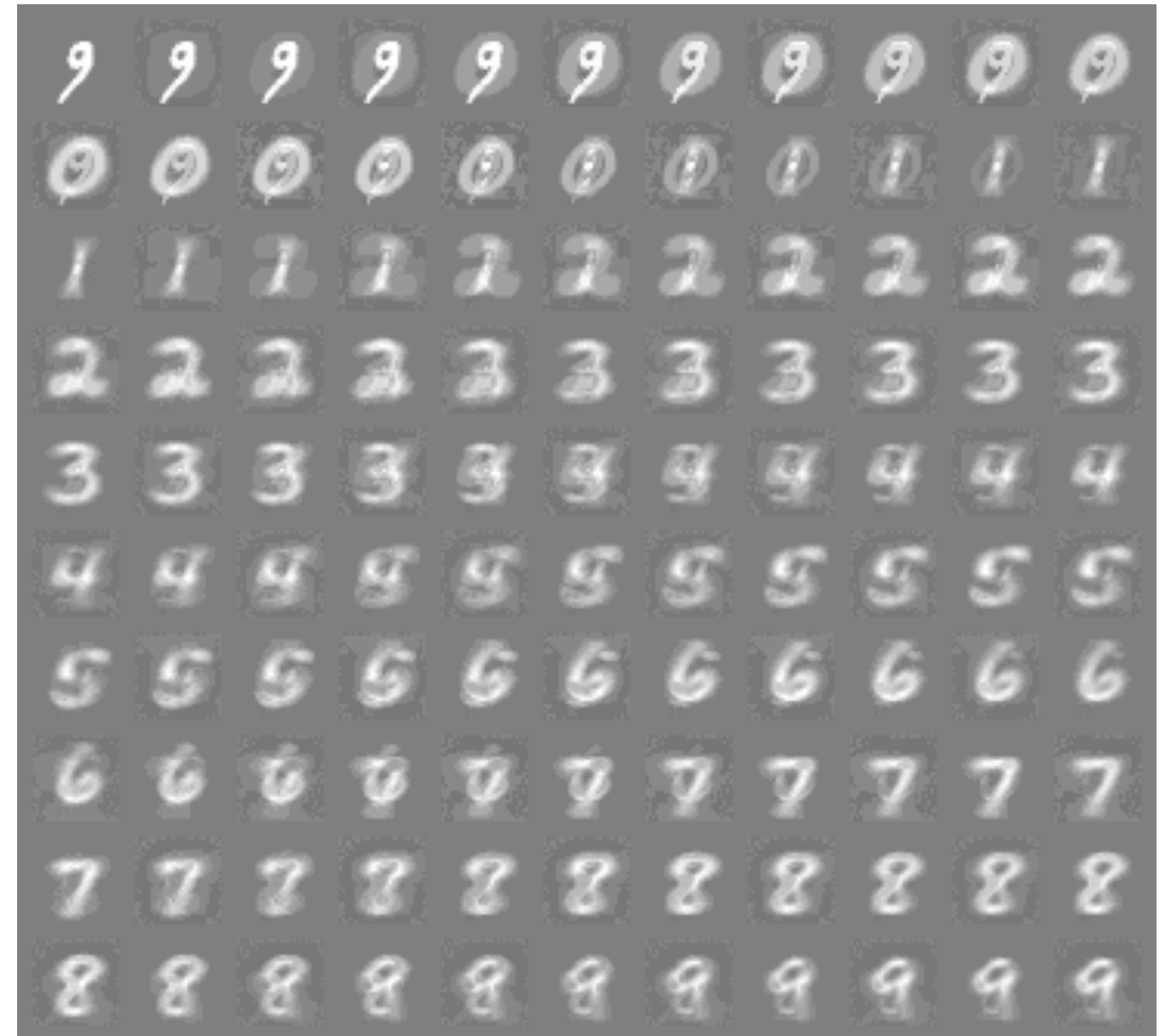
Interpretability literature: our analysis tools show that deep nets work about how you would expect them to.

Adversarial ML literature: ML models are very easy to fool and even linear models work in counter-intuitive ways.

Robust models are more interpretable



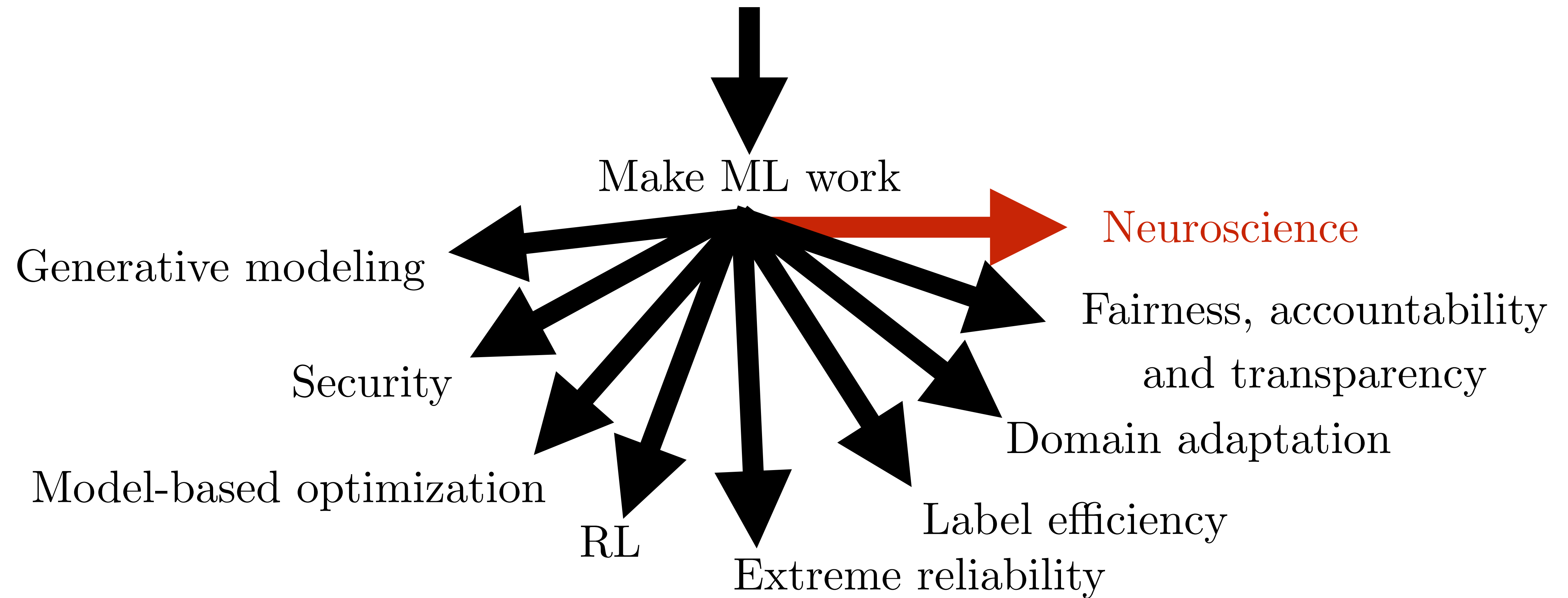
Relatively vulnerable model



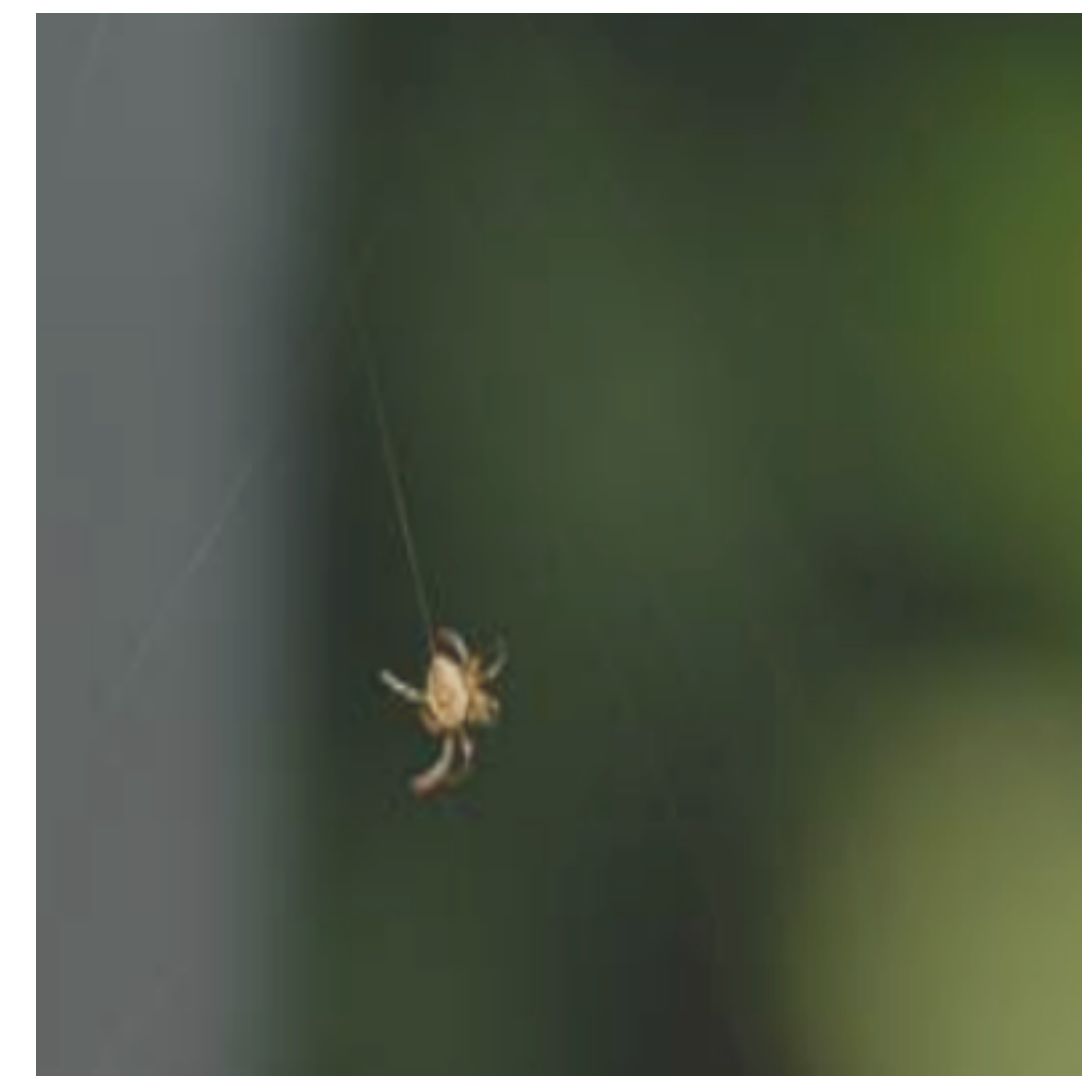
Relatively robust model

(Goodfellow 2015)

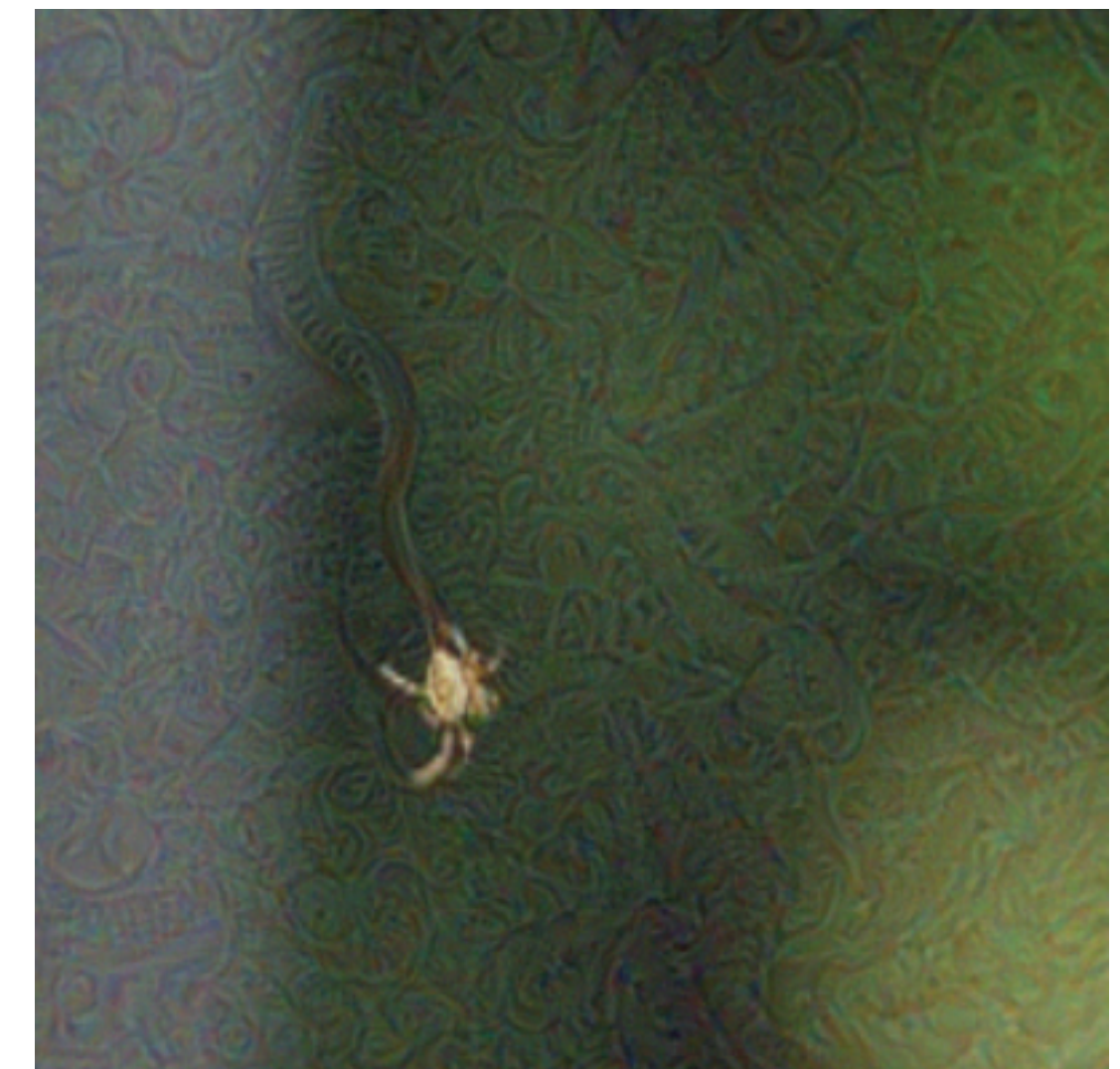
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Adversarial examples that affect both computer and time-limited human vision



25% snake



67% snake

Elsayed et al 2018

Questions