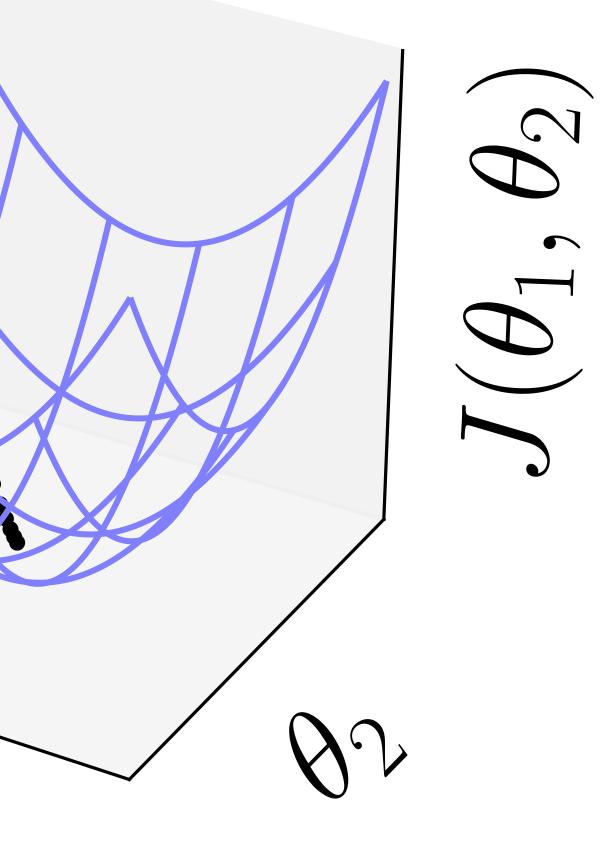
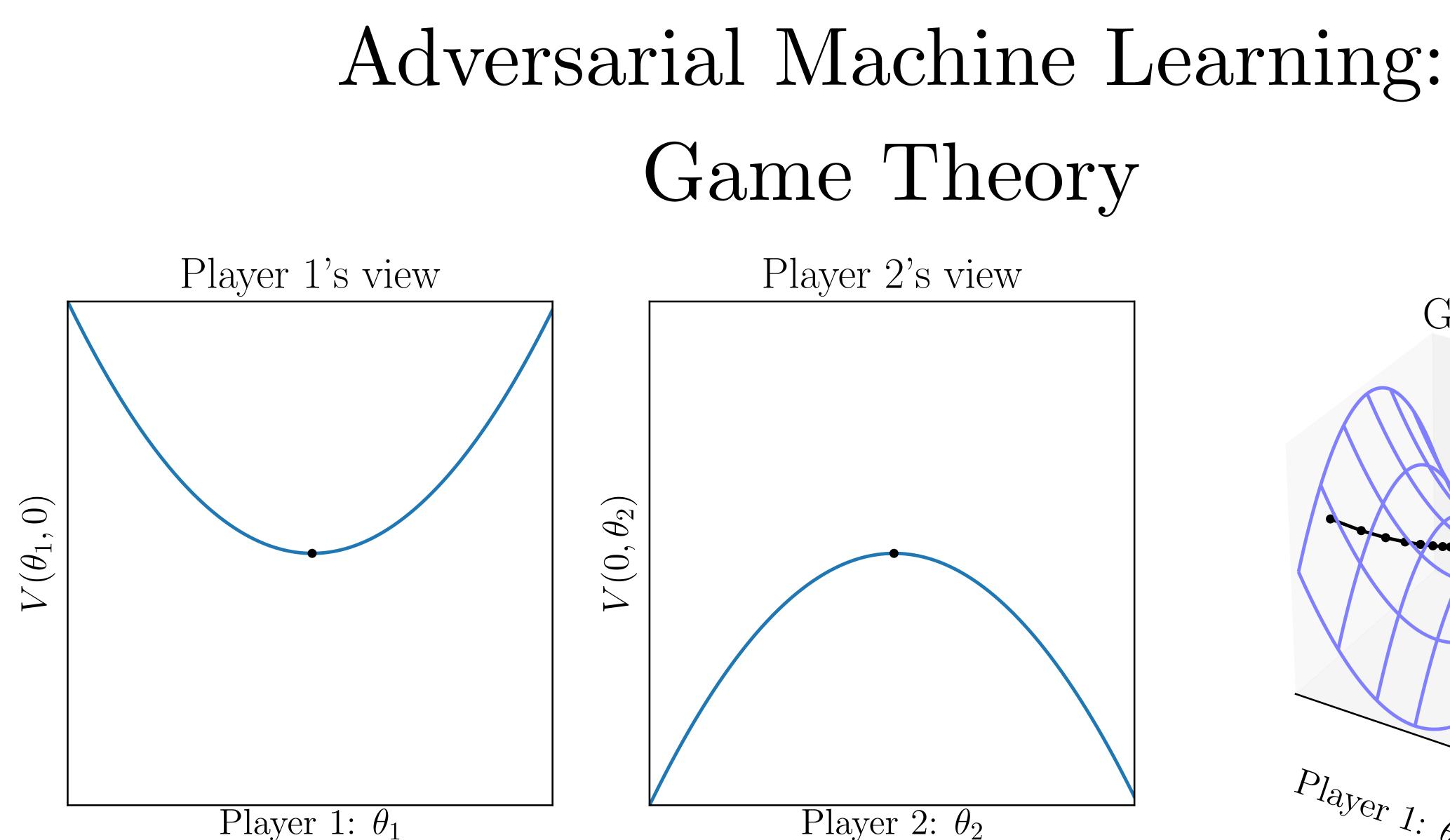
Adversarial Machine Learning Ian Goodfellow ICLR 2019-05-07

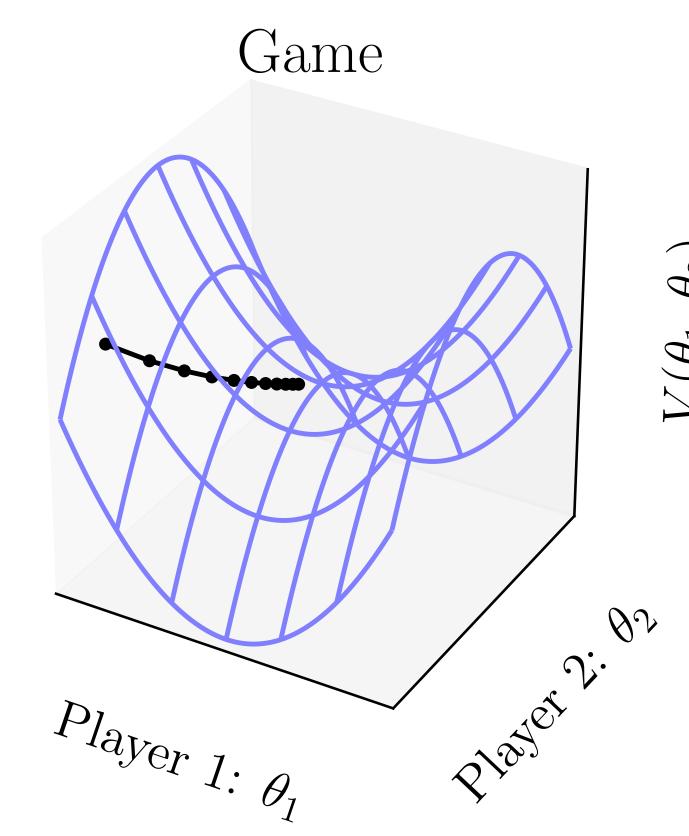


Most Traditional Machine Learning: Optimization



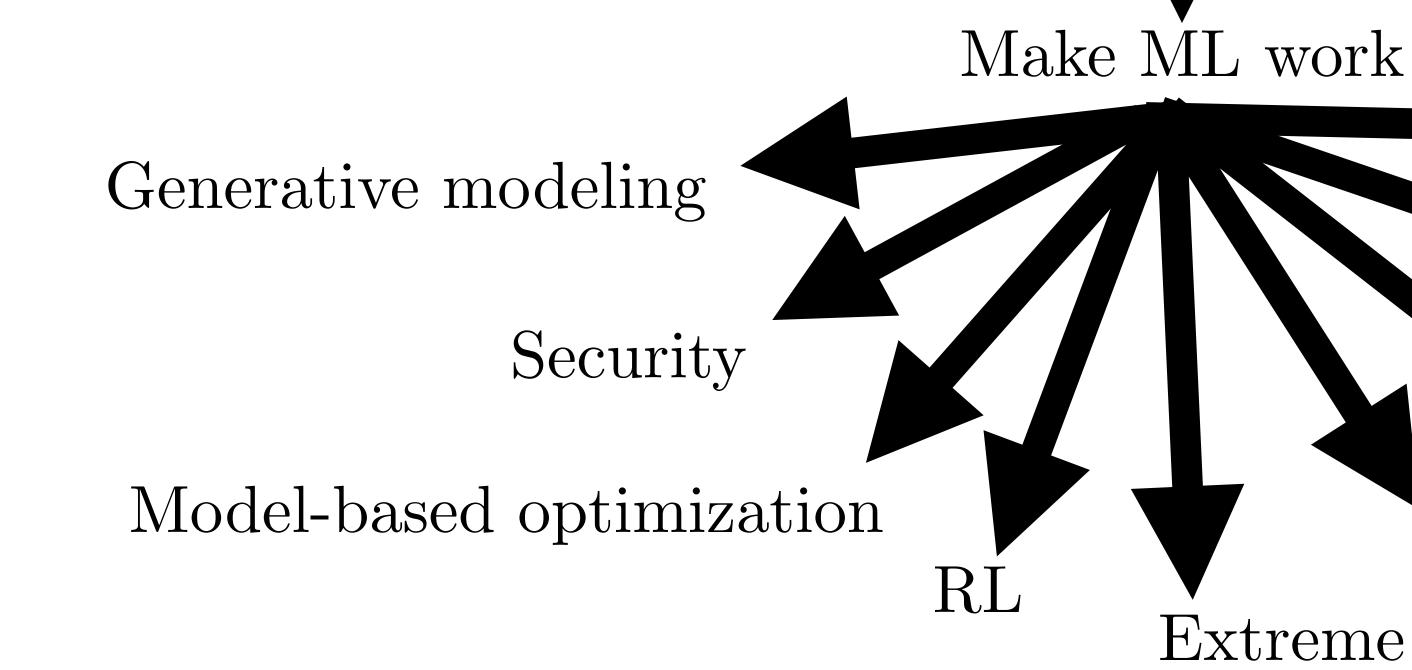








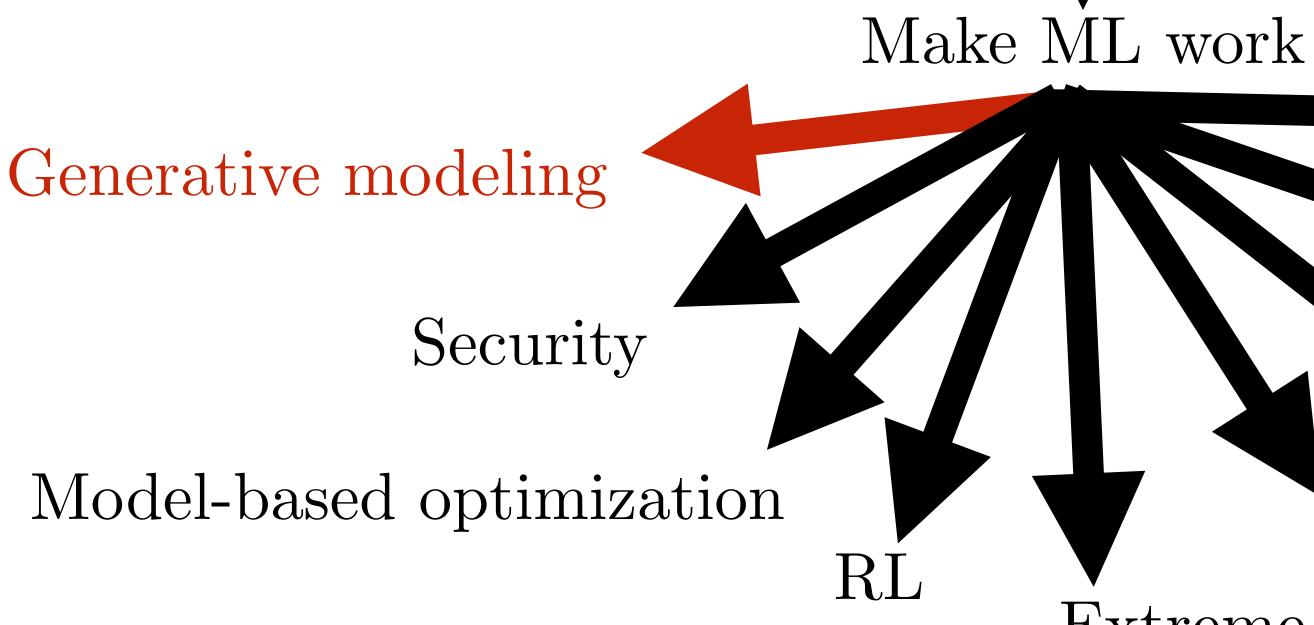




Neuroscience

Fairness, accountability and transparency Domain adaptation





Neuroscience

Fairness, accountability and transparency Domain adaptation



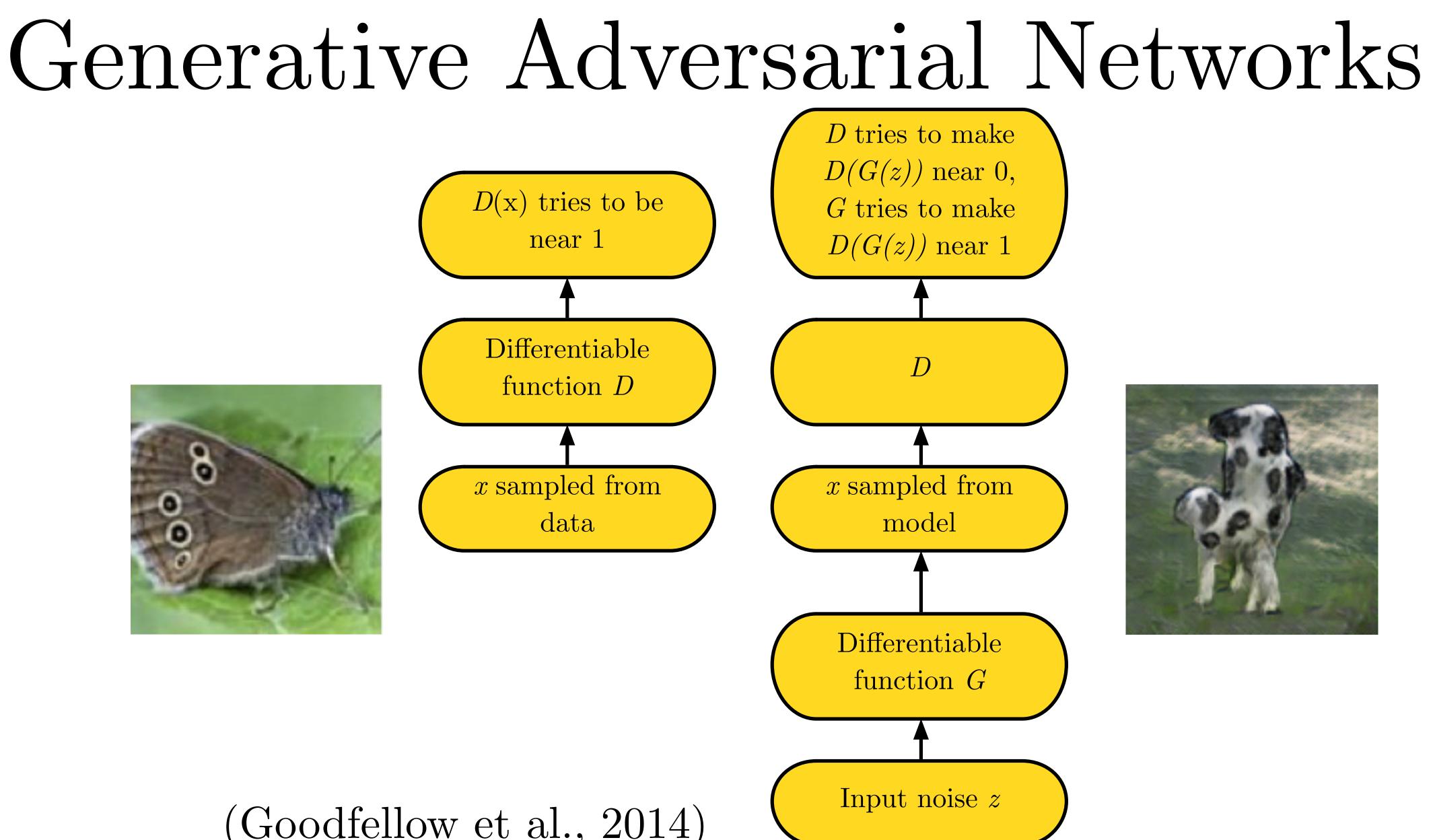
Generative Modeling: Sample Generation



Training Data (CelebA)



Sample Generator (Karras et al, 2017)

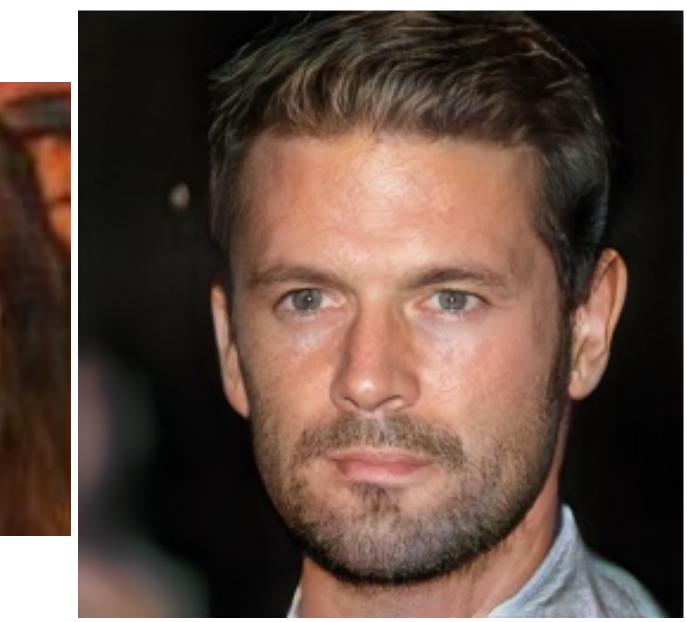


(Goodfellow et al., 2014)



4.5 years of progress on faces









2 Years of Progress on ImageNet

















Odena et al 2016













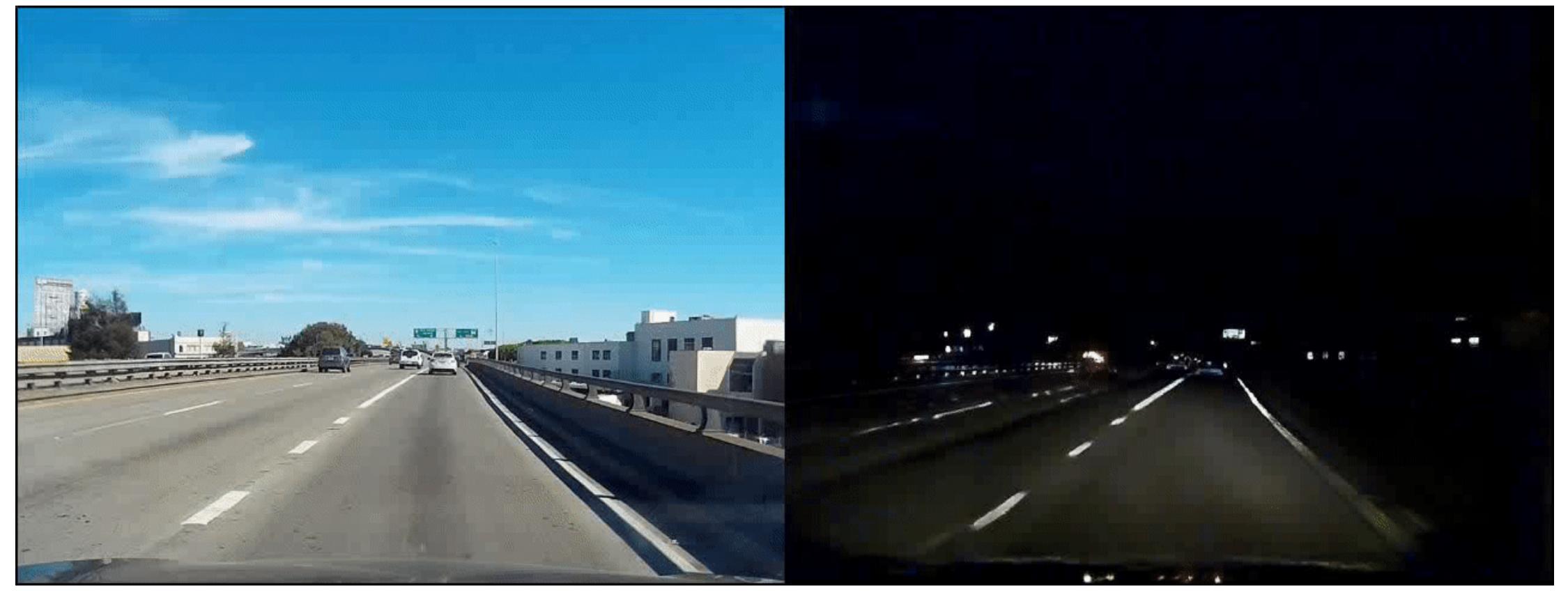
Miyato et al 2017

Zhang et al 2018

Brock et al 2018

(Goodfellow 2018)

Unsupervised Image-to-Image Translation





Day to night

(Liu et al., 2017)



CycleGAN

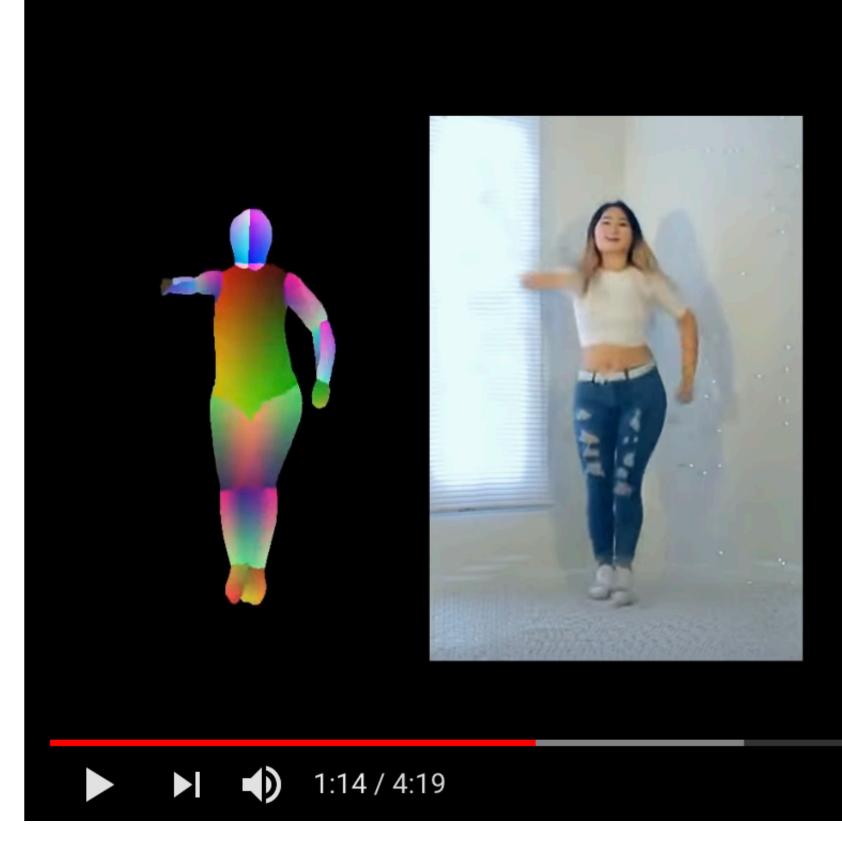




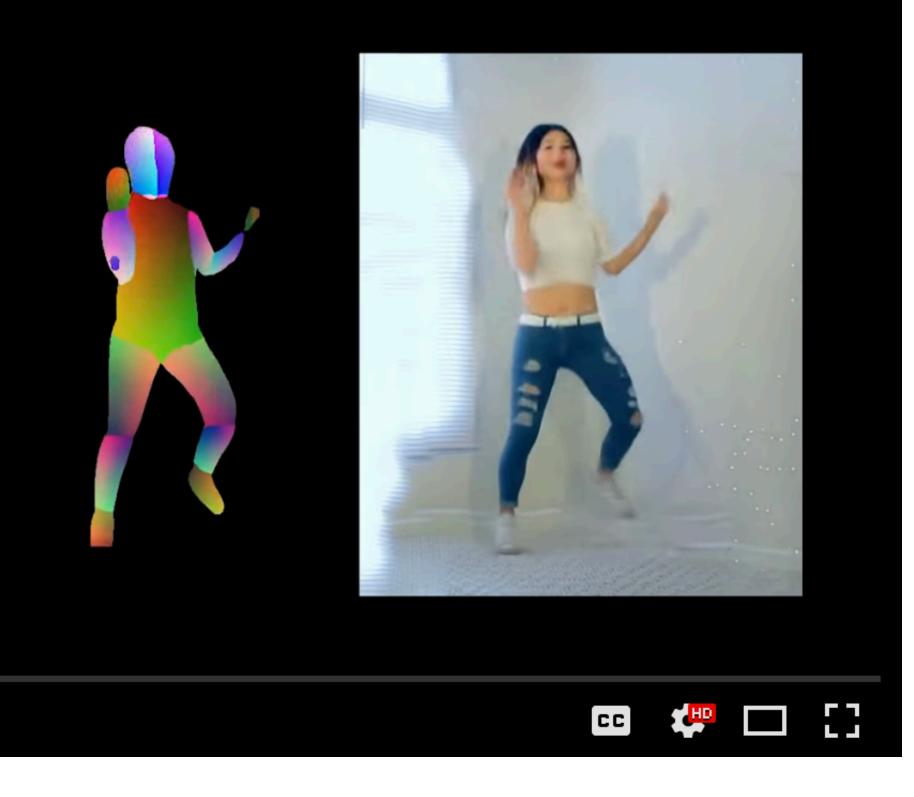
(Zhu et al., 2017)

Video-to-Video

Pose-to-Body Results



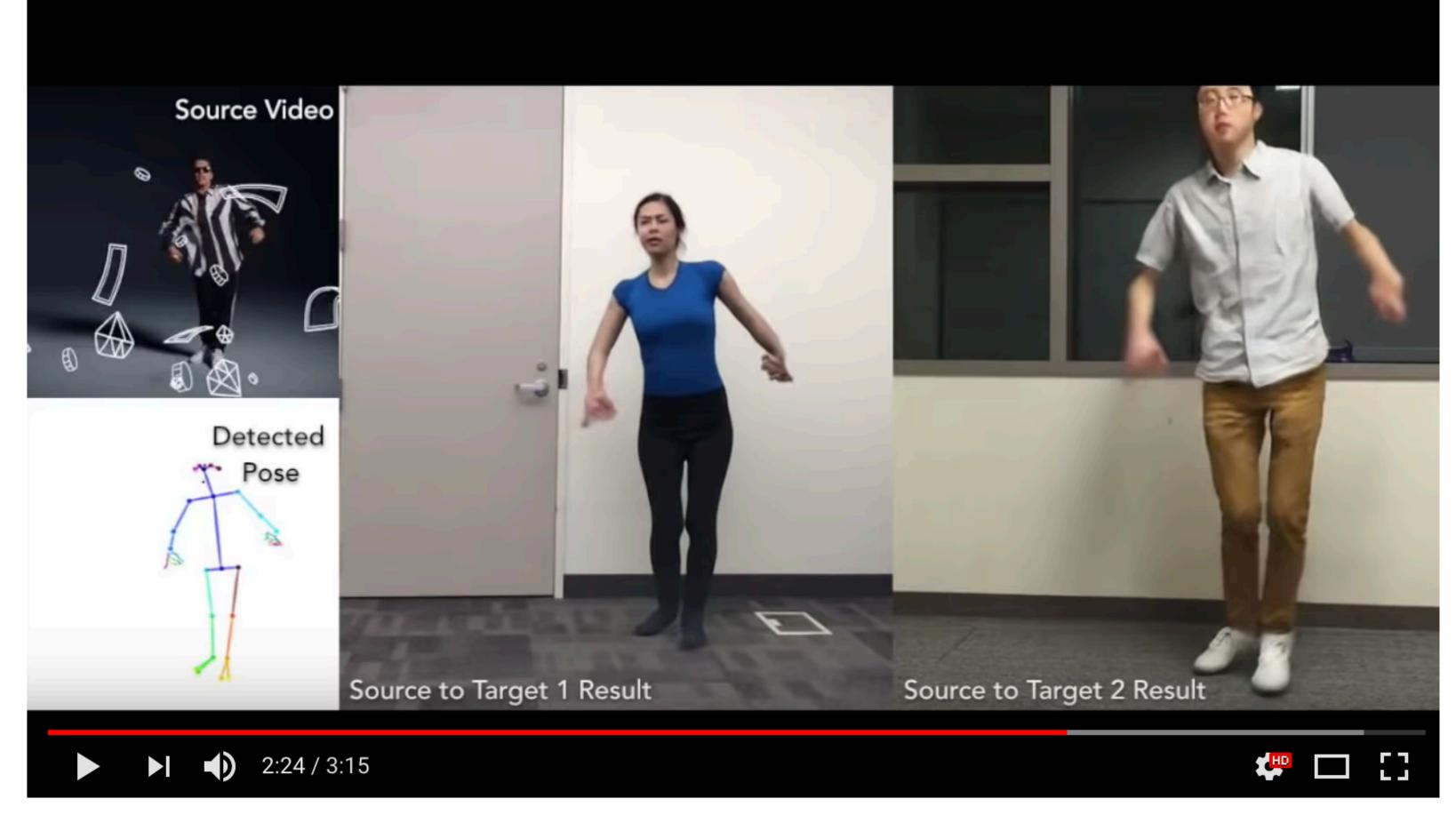








Everybody Dance Now

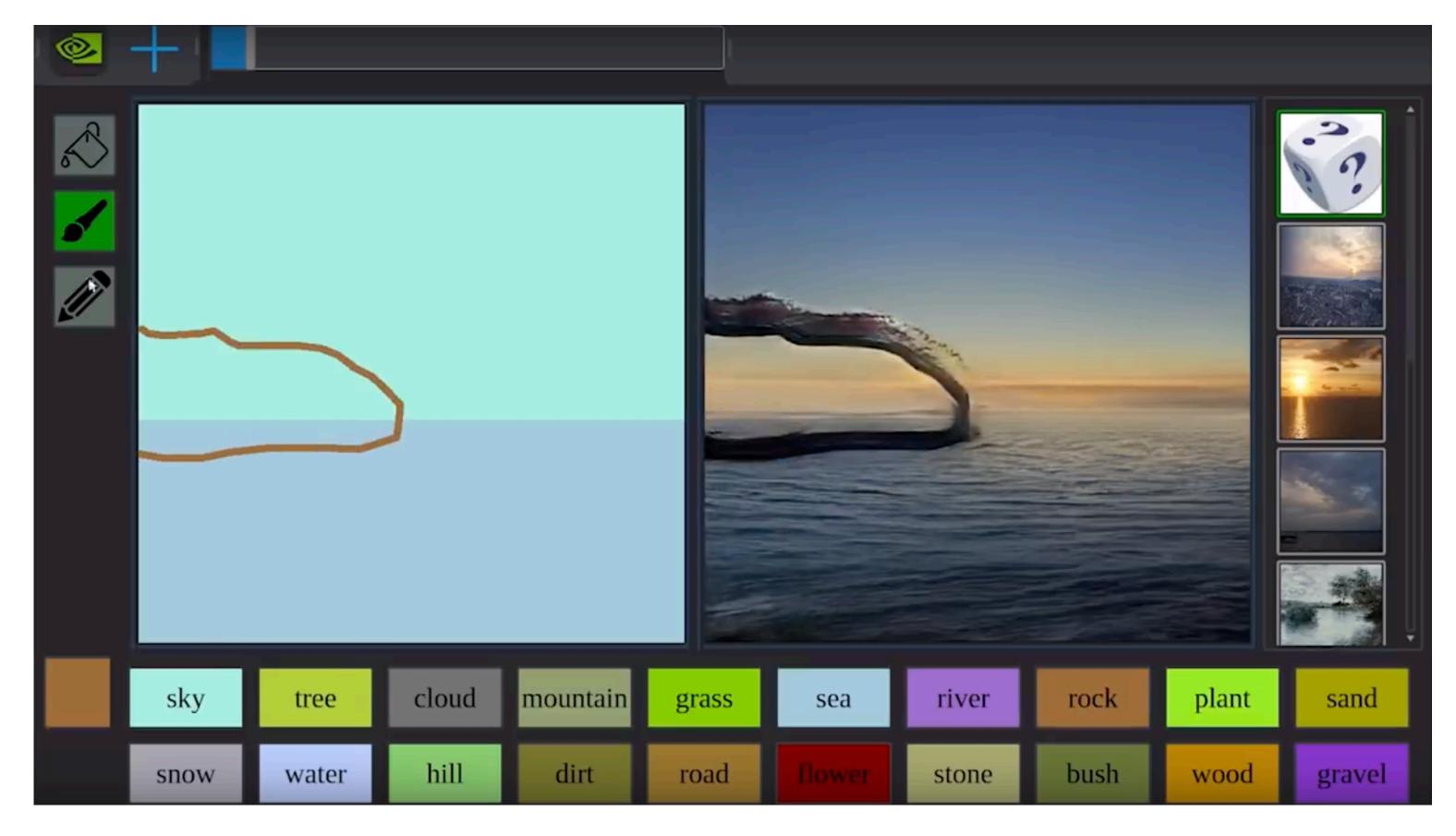








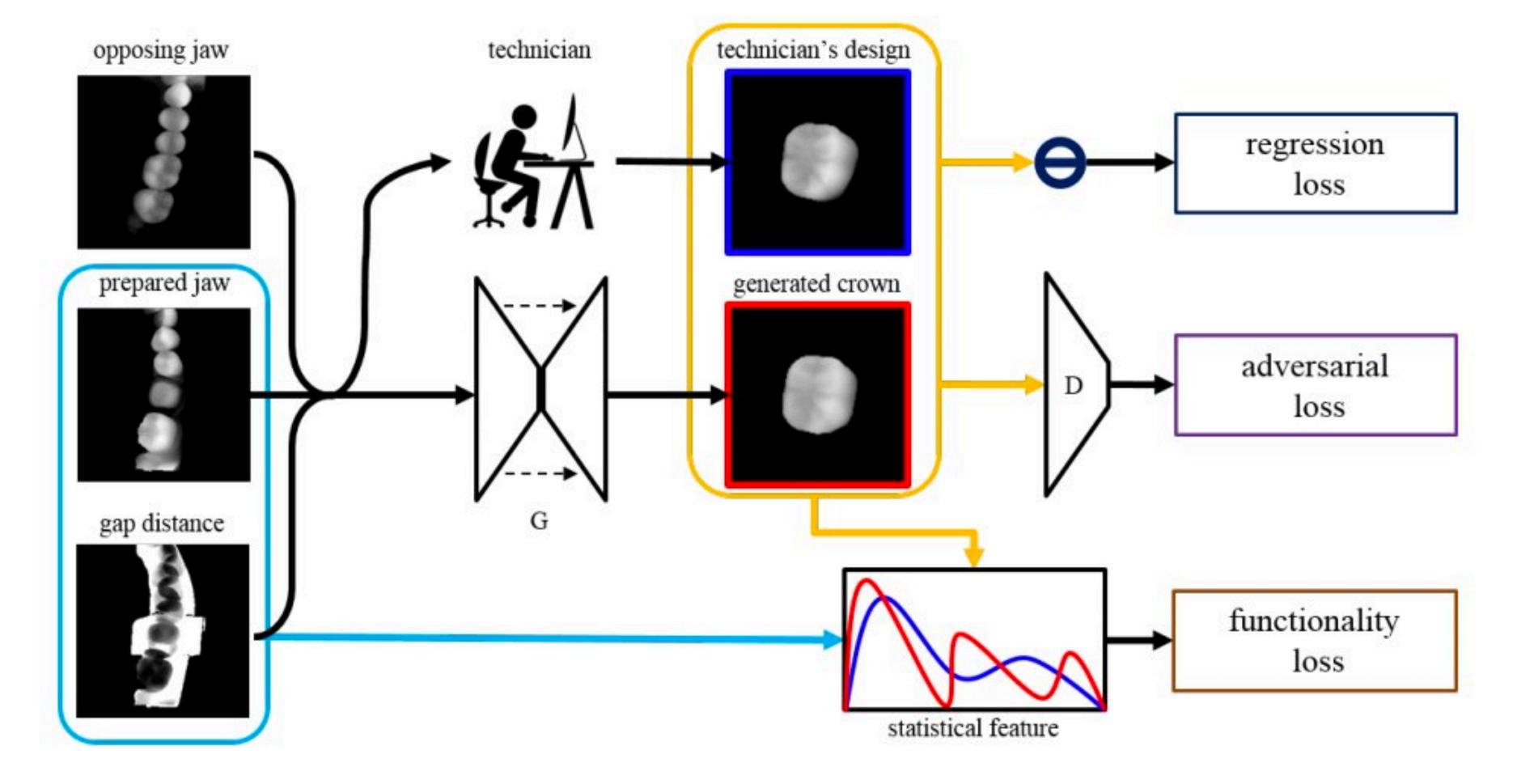
GauGAN





(Park et al 2019)







Personalized GANufacturing

(Hwang et al 2018)







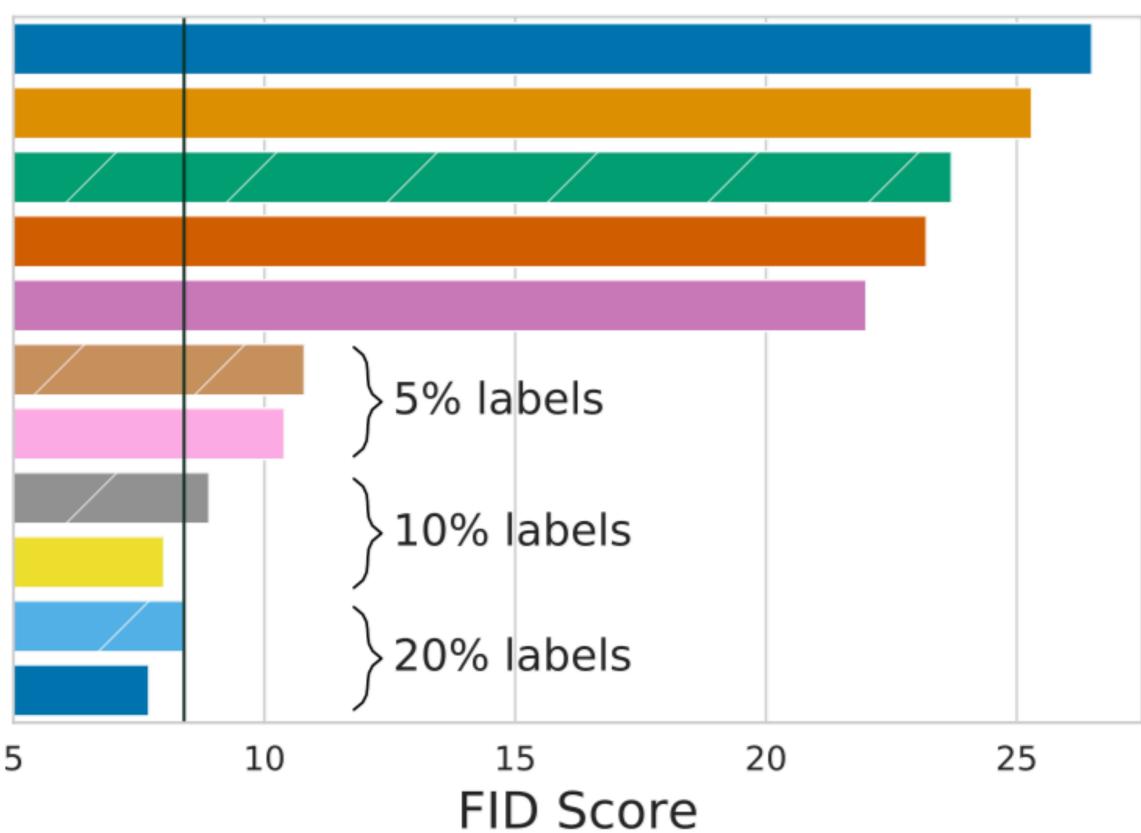
(Fake)

(Brock et al, 2018)BigGAN Large scale TPU implementation

Recent Advances

Style-based generators (Karras et al, 2018)

Reducing Supervision Needed for "Unsupervised" Learning



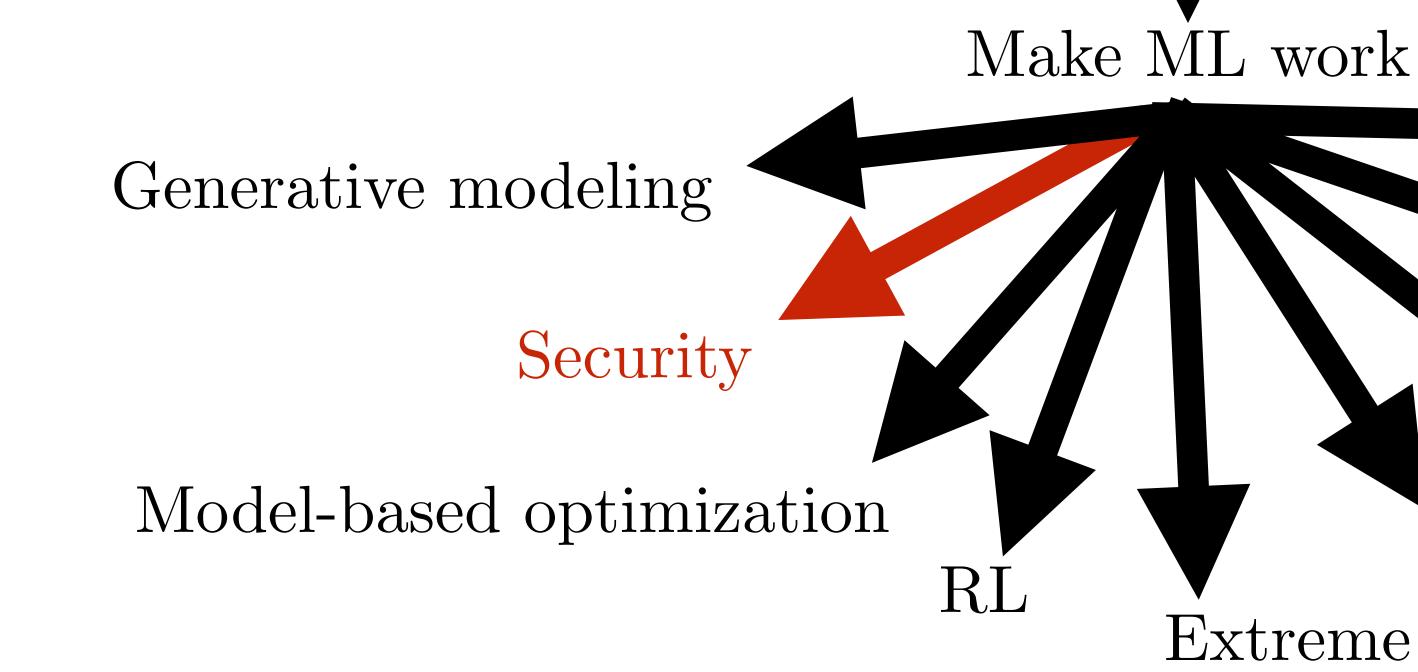
Random label Single label Single label (SS) Clustering Clustering (SS) $S^2 \; \mathsf{GAN}$ $S^3 \mathsf{GAN}$

- $S^2 \; \mathsf{GAN}$
- $S^3 \text{ GAN}$
- $S^2 \operatorname{GAN}$

 $S^3 \text{ GAN}$

(Lucic+Tschannen+Ritter et al 2019)





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Fairness, accountability and transparency Domain adaptation



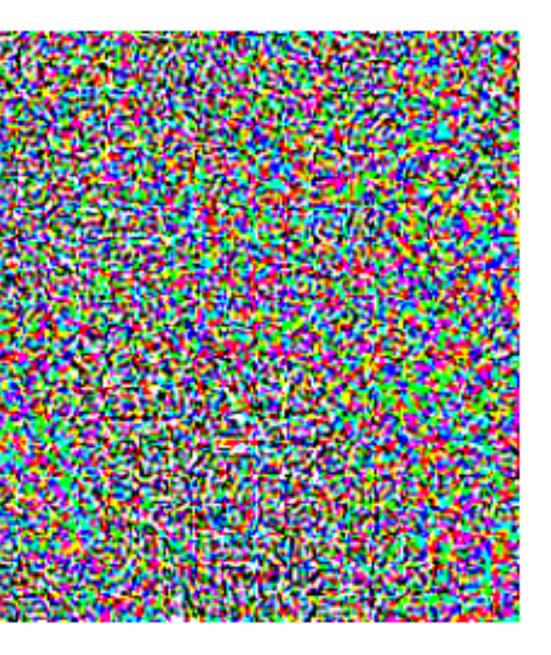
Adversarial Examples

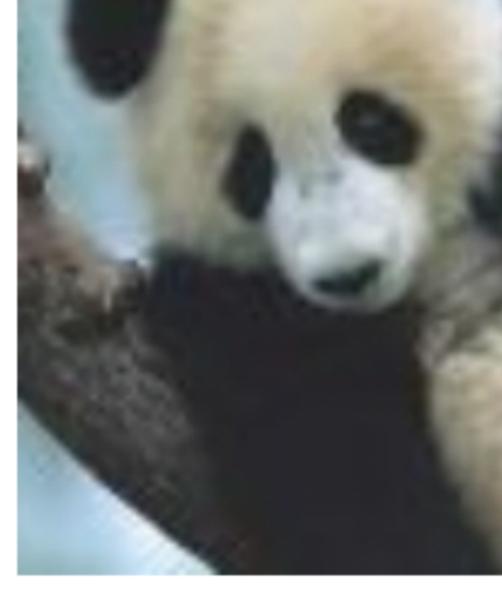


58% panda

 $+.007 \times$







99% gibbon

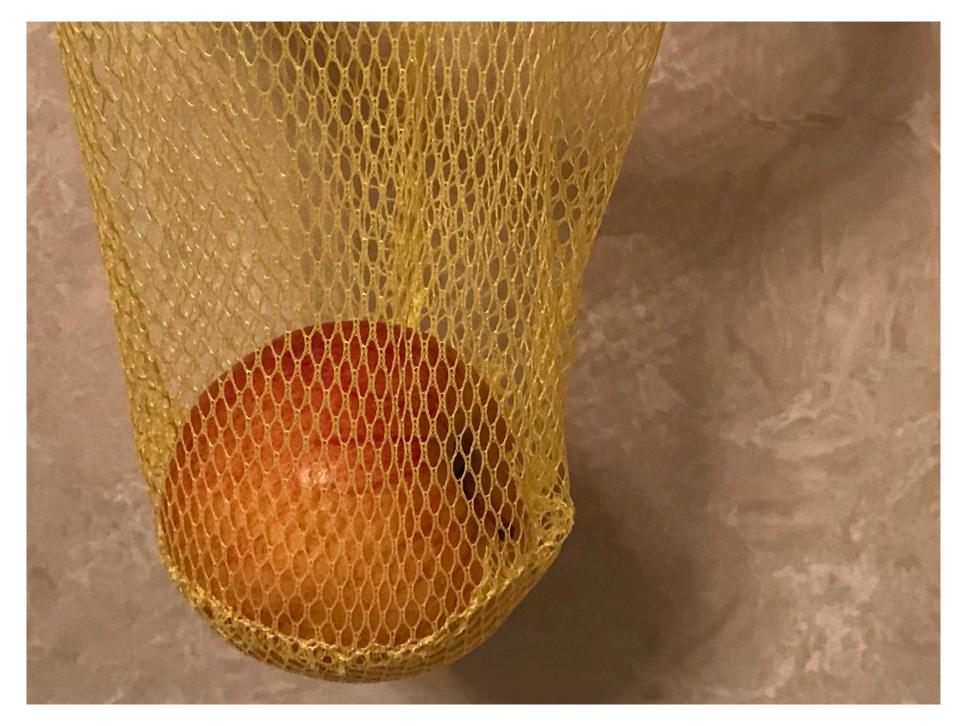
(Goodfellow et al, 2014)



Also Adversarial Examples

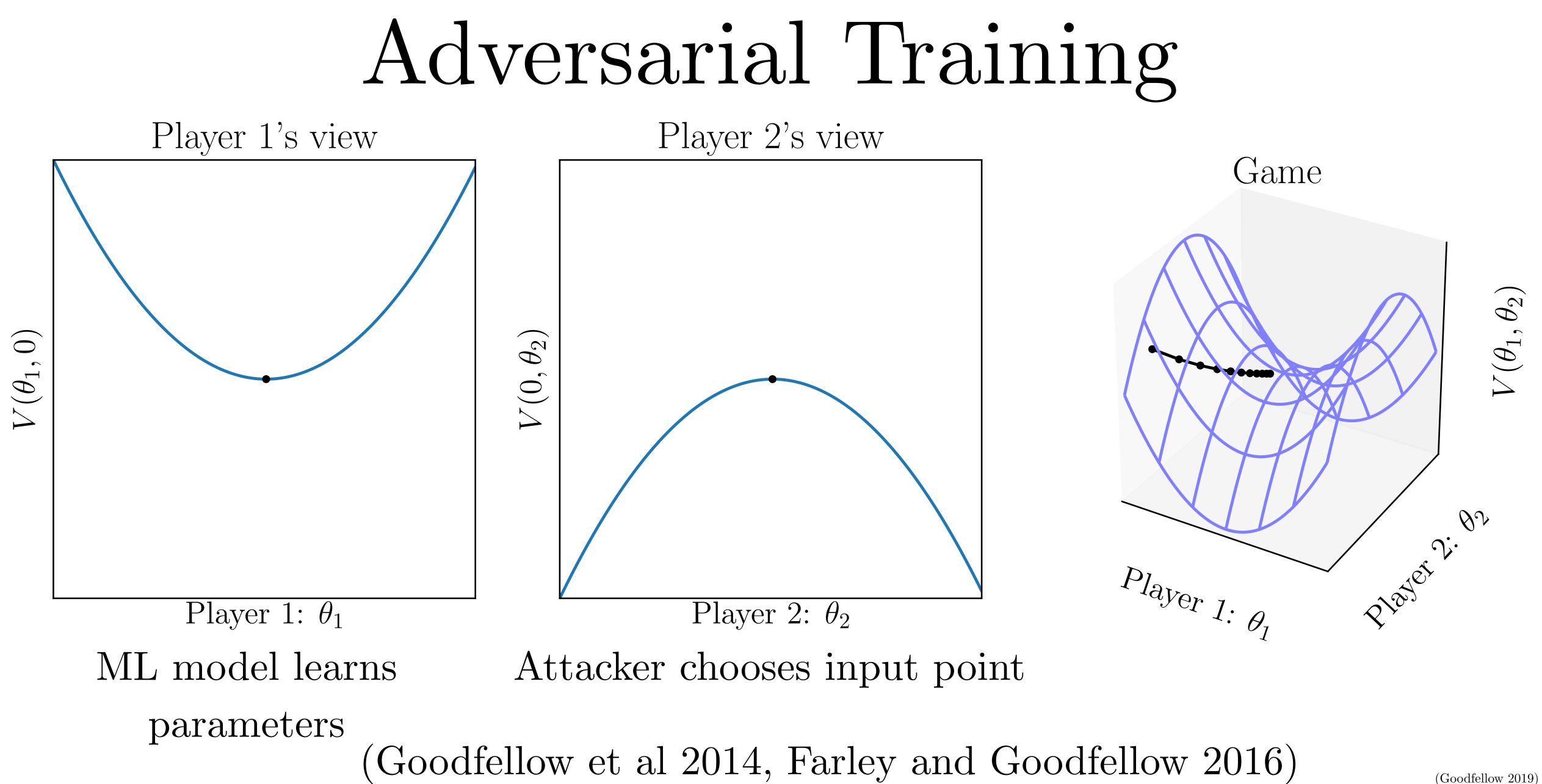


(Eykholt et al, 2017)



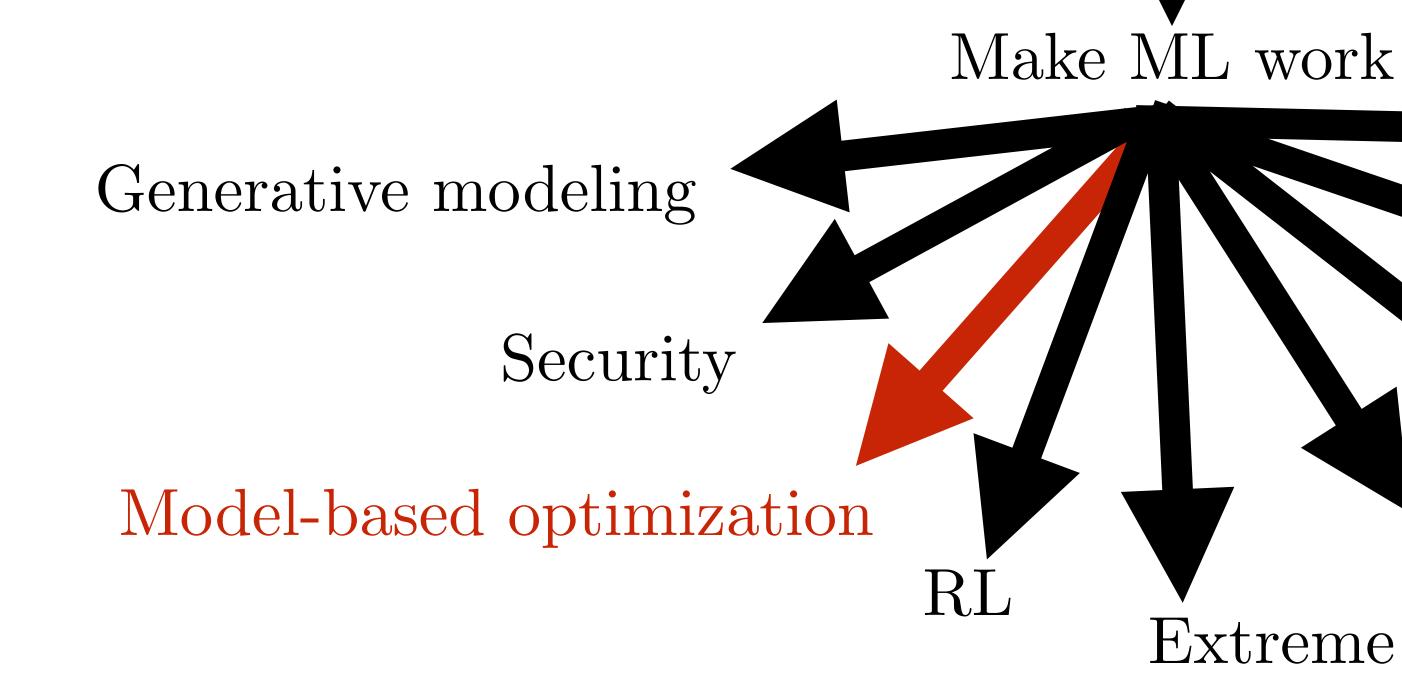
(Goodfellow 2018)









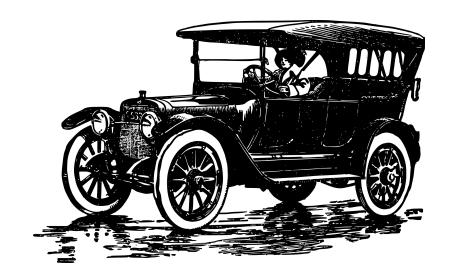


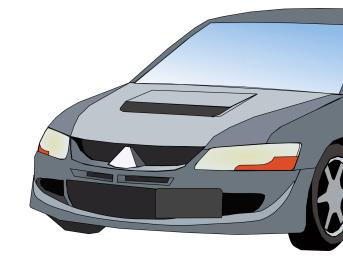
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Model-Based Optimization

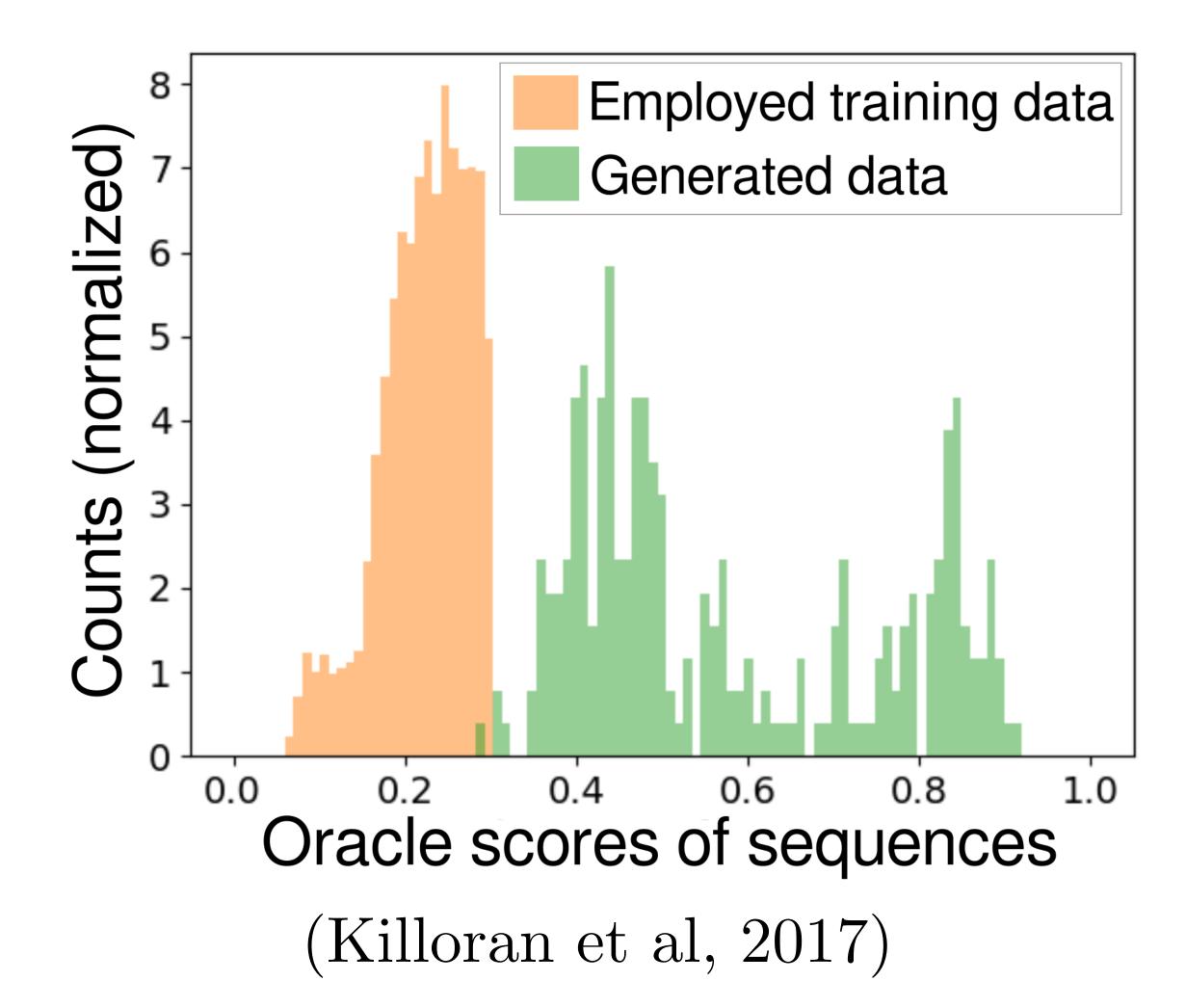






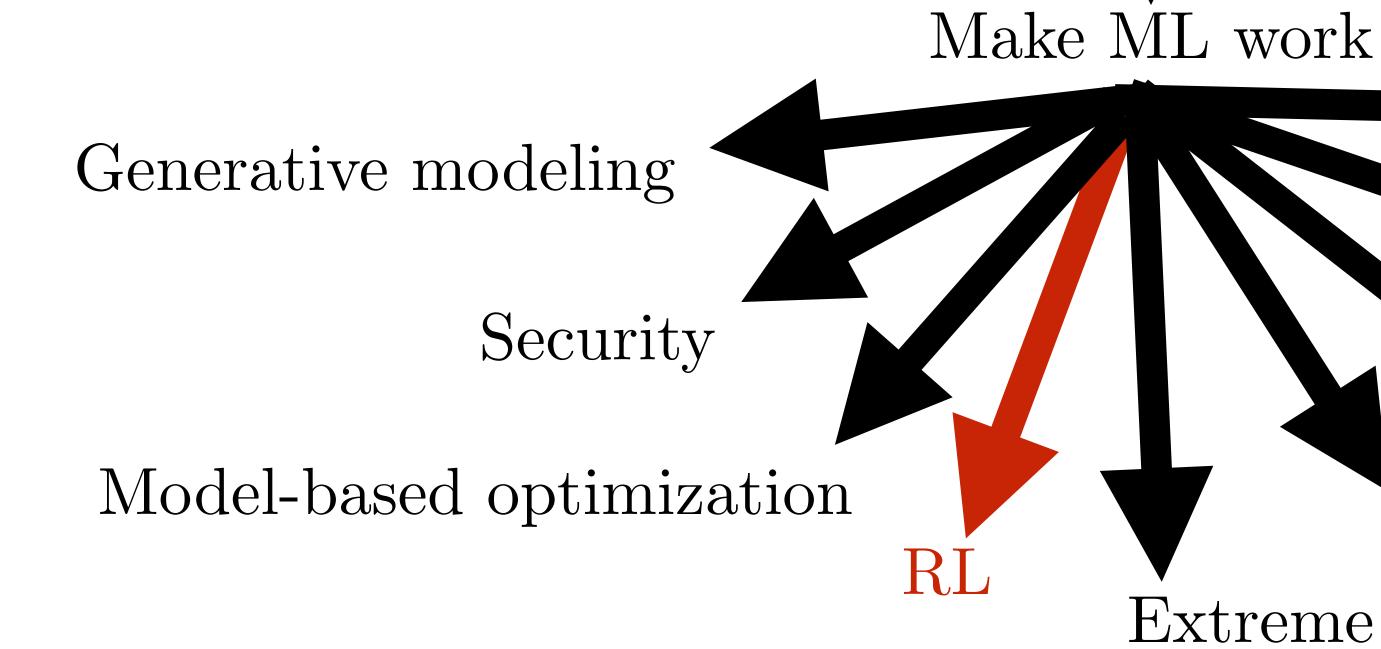


Designing DNA to optimize protein function





(Gupta and Zou, 2018)



Neuroscience

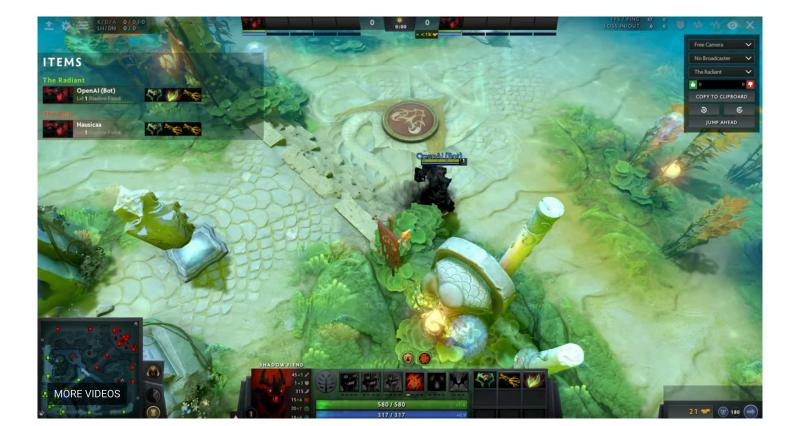
Fairness, accountability and transparency Domain adaptation



Self-Play

1959: Arthur Samuel's checkers agent





(OpenAI, 2017)



Goal: push opponent outside the ring, or topple them over

(Bansal et al, 2017)



Adversarial Examples for RL





 $(\underline{\text{Huang et al.}}, 2017)$



SPIRAL Synthesizing Programs for Images Using Reinforced Adversarial Learning

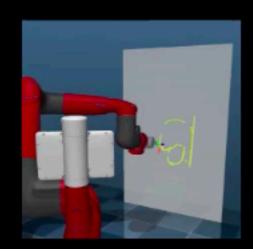
Input Program end = [(9, 12), (3, 16), (17, 26), (30, 26), (30, 26), (30, 26), (20, 22), (16, 14), (30, 21), ...], <mark>ctl</mark> = [(8, 11), (8, 24), (3, → 25), (10, 25), (18, 25), (23, 25), (17, 21), (17, 22), (18, 22), ...], pen = [0, 1, 1, 1, 1, 1, 0, Image 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0]

(Ganin et al, 2018)

Interpreters

Simulated Paint



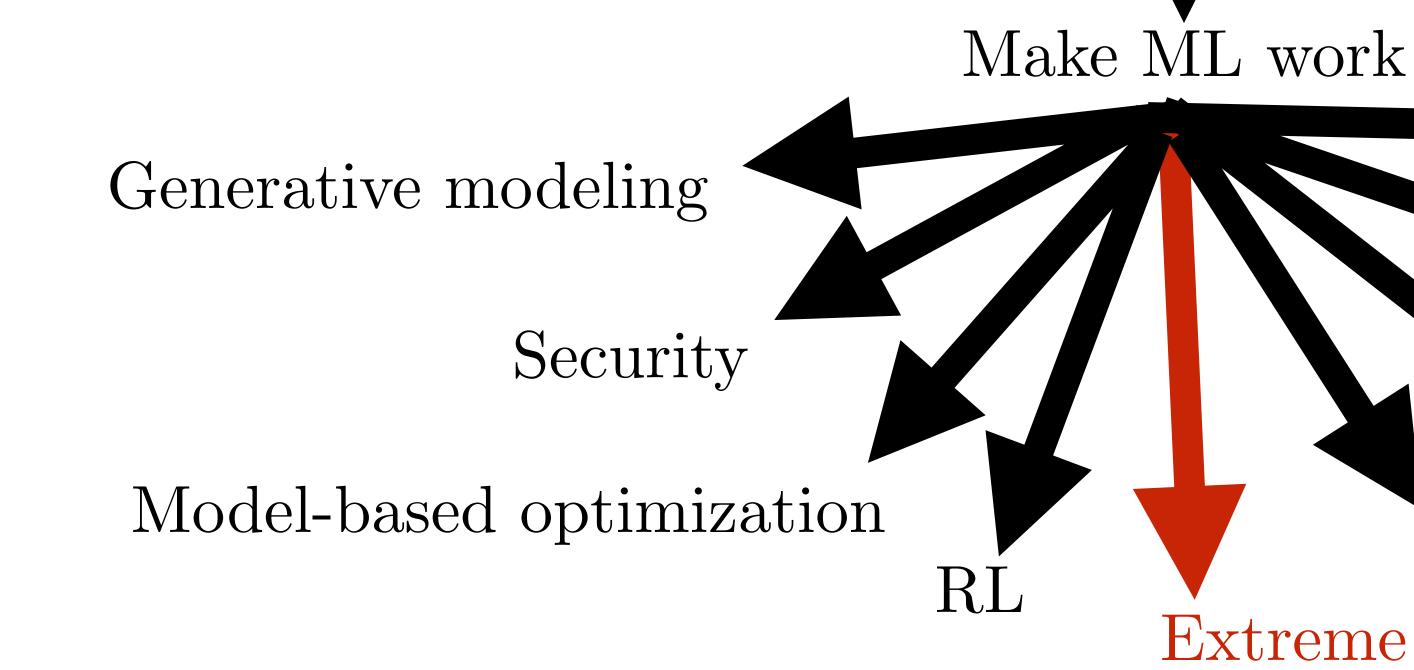




Simulated Arm

Real Arm





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Robustness and verification techniques essential for air traffic control, surgery robots, etc.

0.2

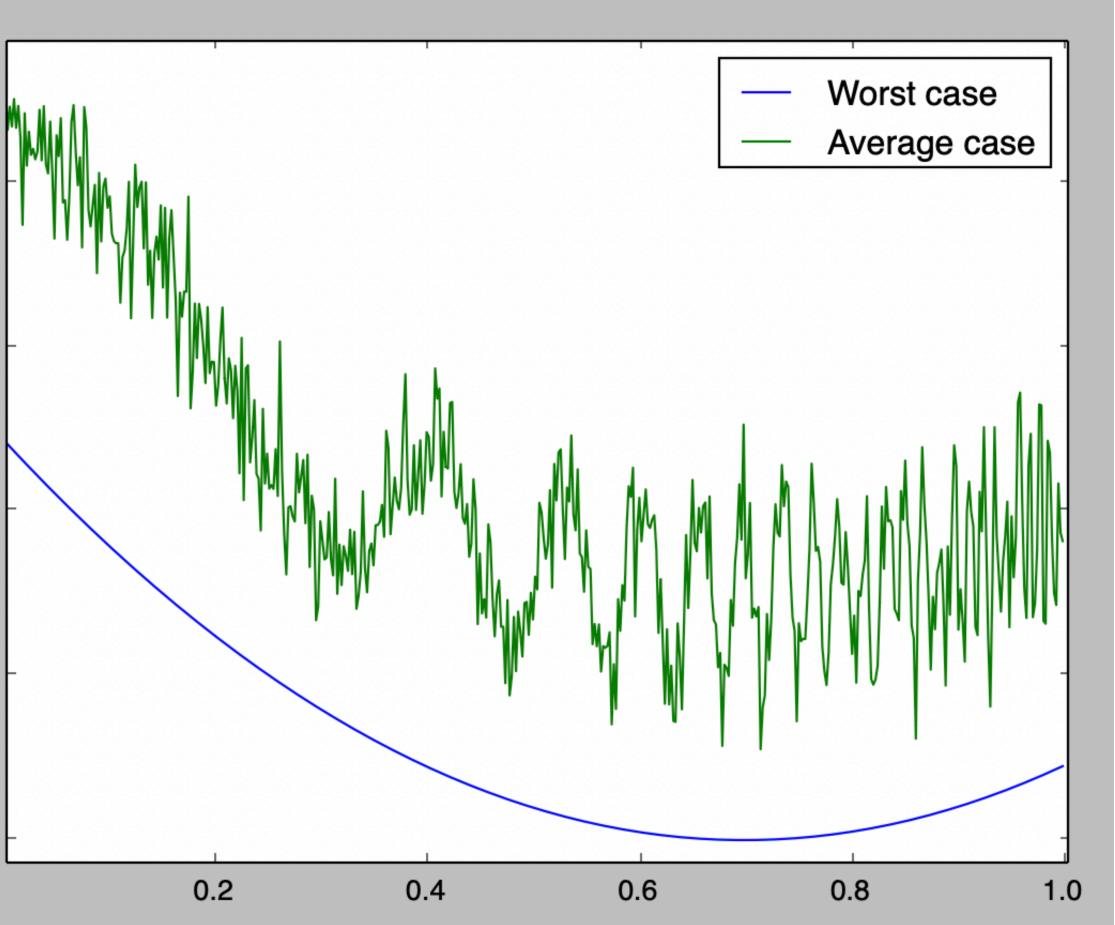
0.8

0.6

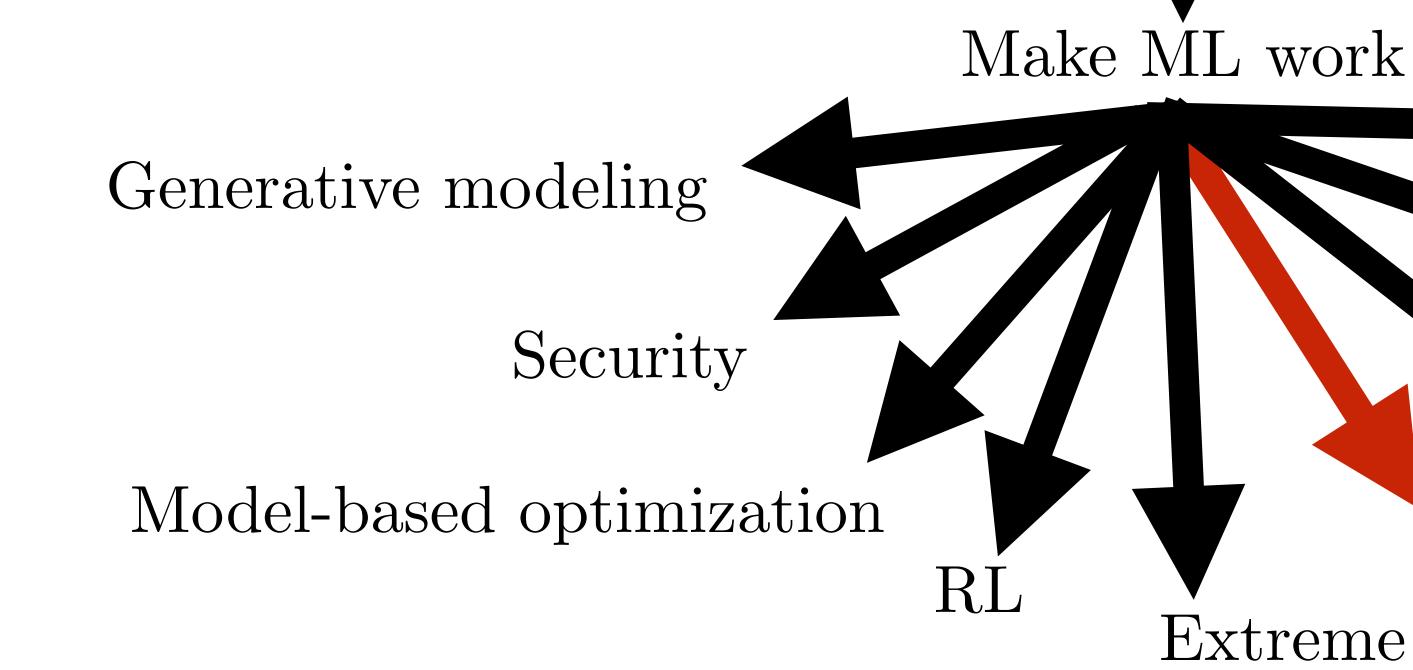
0.4

0.0

Extreme Reliability





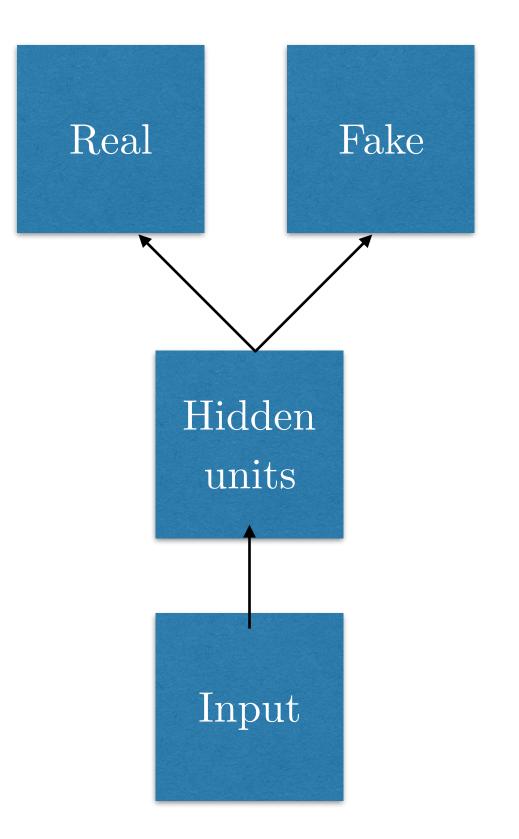


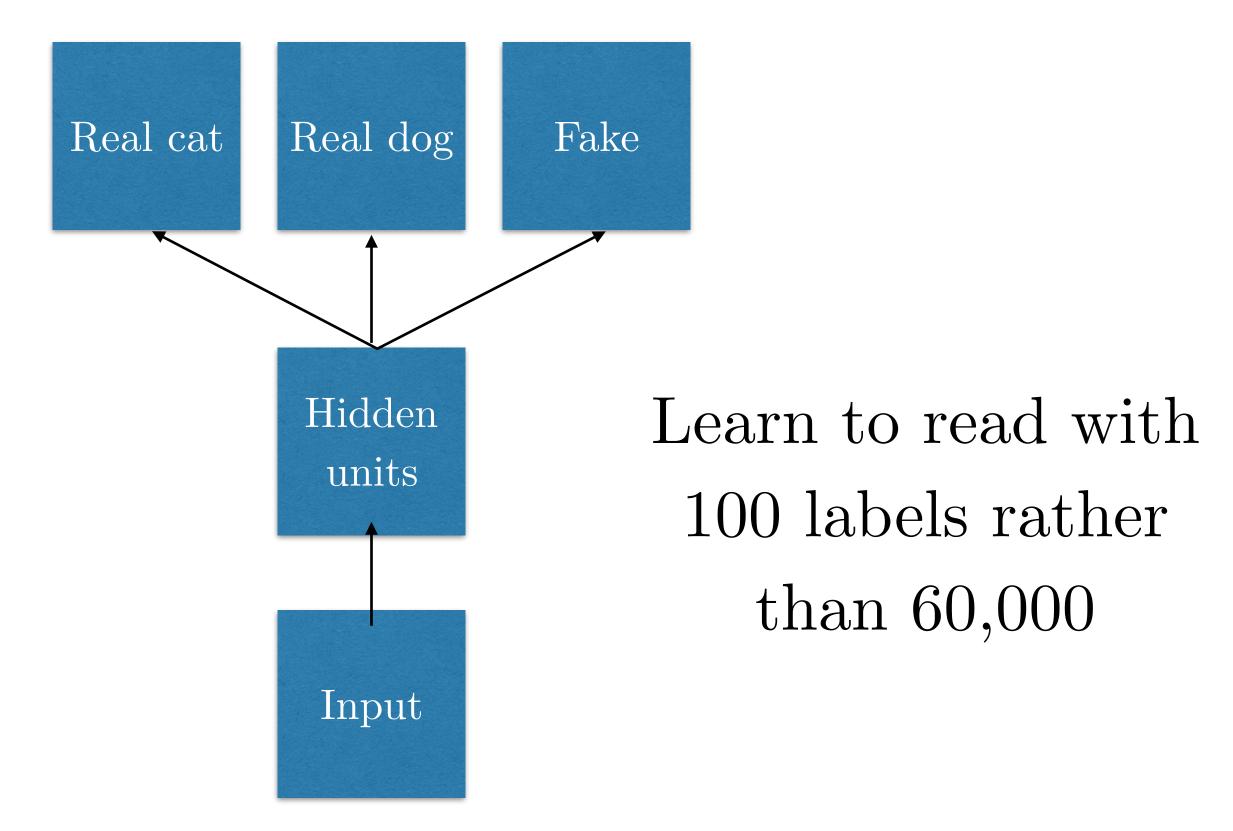
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Supervised Discriminator for Semi-Supervised Learning



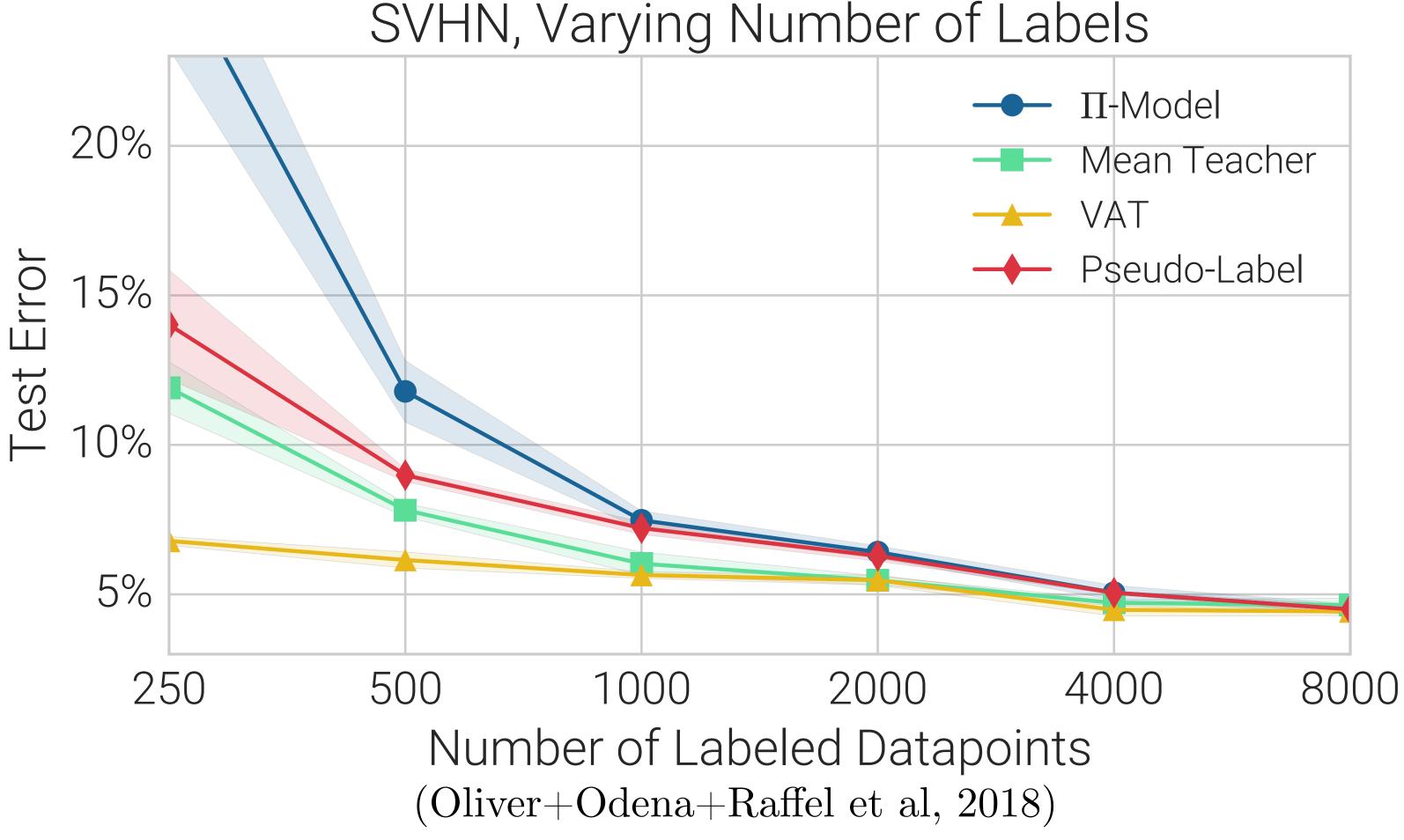


(Odena 2016, Salimans et al 2016)

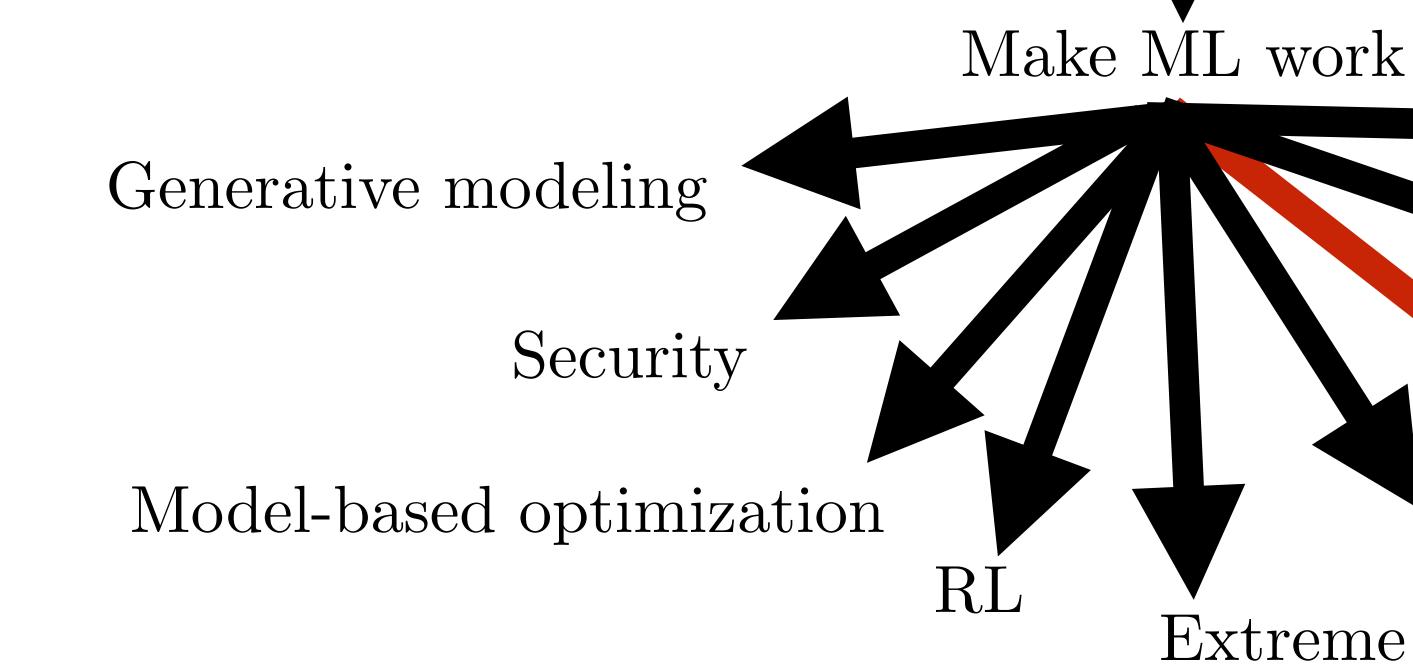
(Goodfellow 2019)

Virtual Adversarial Training Miyato et al 2015: regularize for robustness to adversarial perturbations of

unlabeled data







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• Domain Adversarial Networks (Ganin et al, 2015)



VIPER

• Professor forcing (Lamb et al, 2016): Domain-Adversarial learning in RNN hidden state

Domain Adaptation

PRID

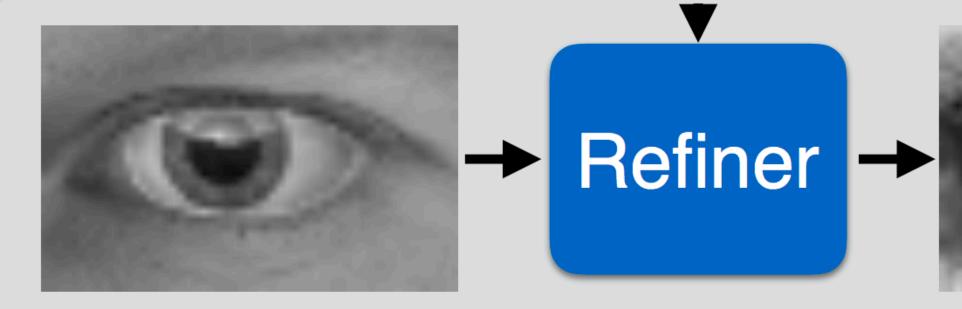
CUHK



GANs for simulated training data Unlabeled Real Images







Synthetic



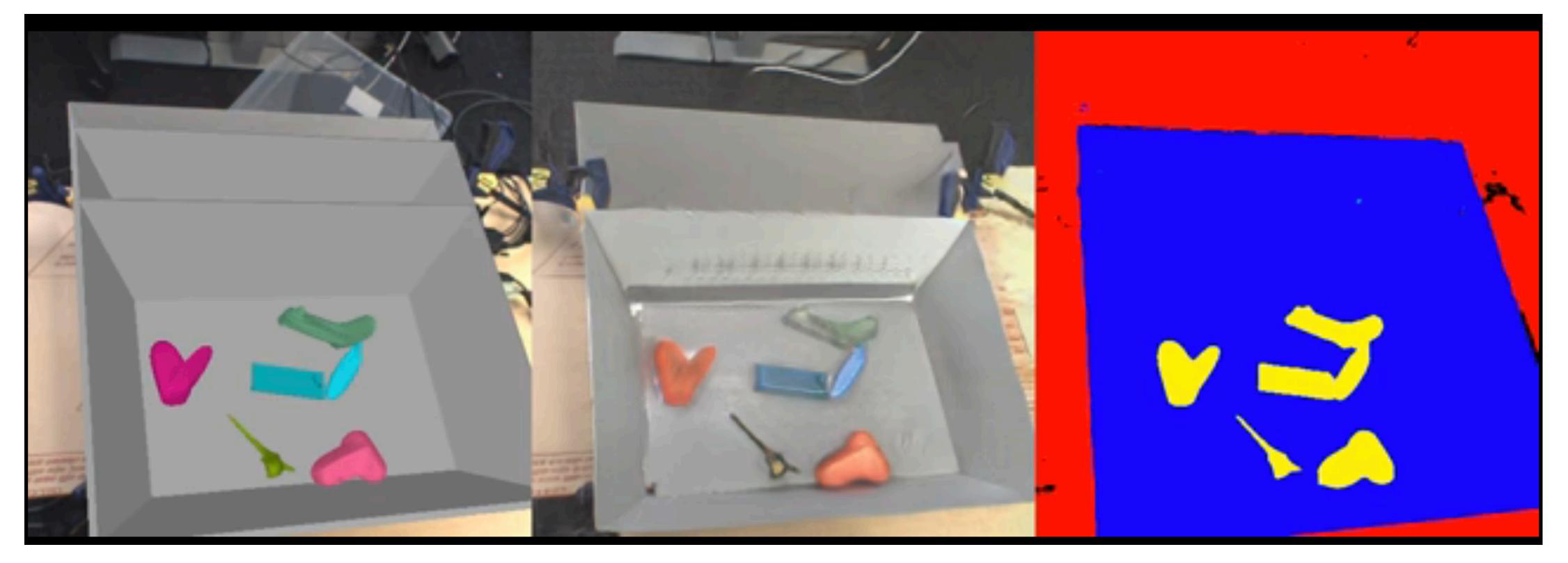


Refined

(Shrivastava et al., 2016)



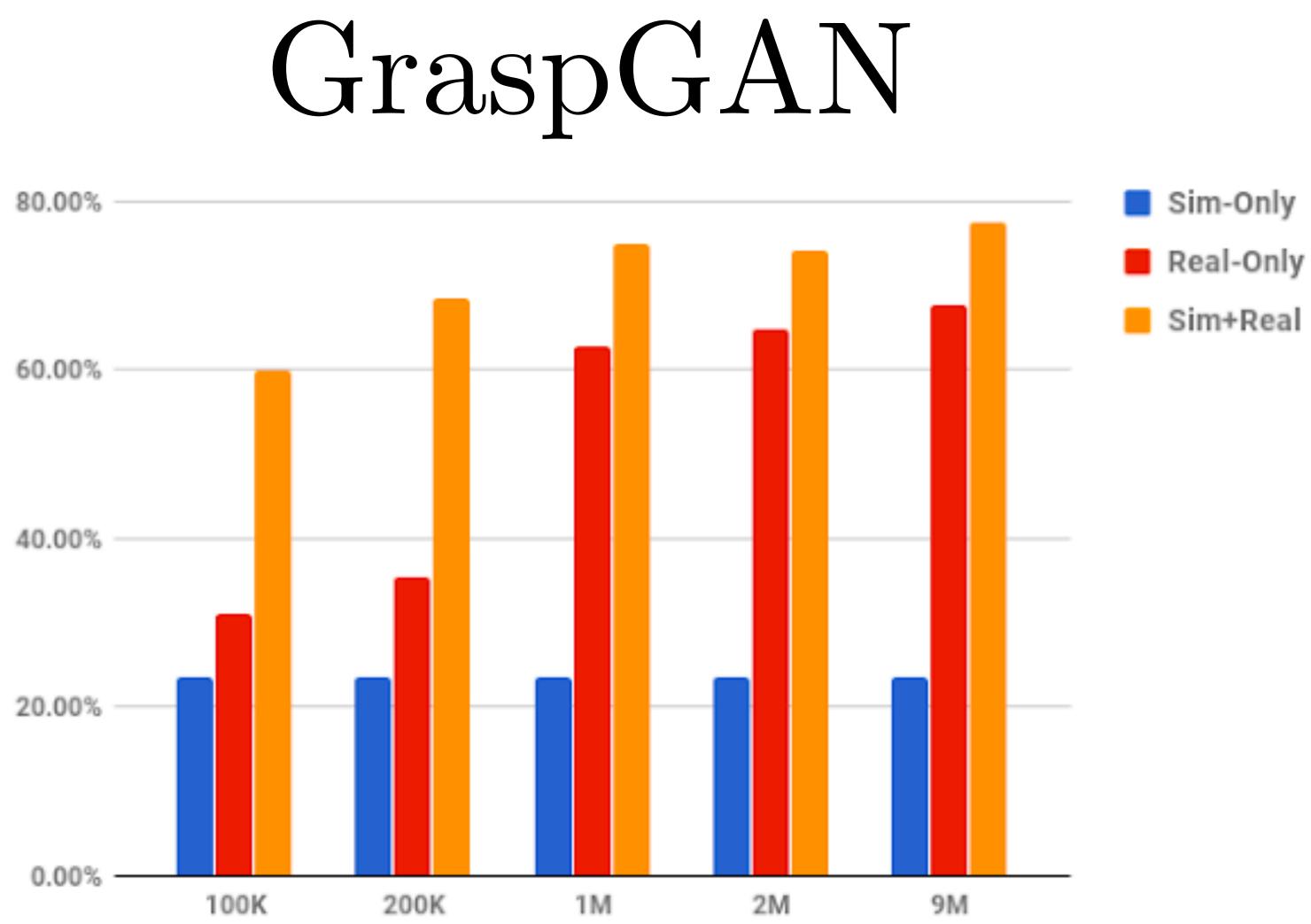
GraspGAN





(Bousmalis et al. 2017)





Grasp Success in the Real World

Number of Real-World Samples Used for Training

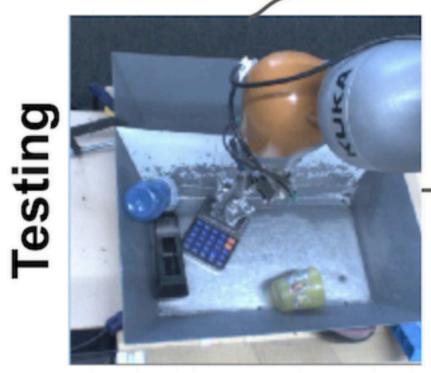
(Bousmalis et al, 2017)



G

Randomized Simulation





Real World

(James et al, 2018)

Sim-to-real via sim-to-sim

action

Agent

Agent

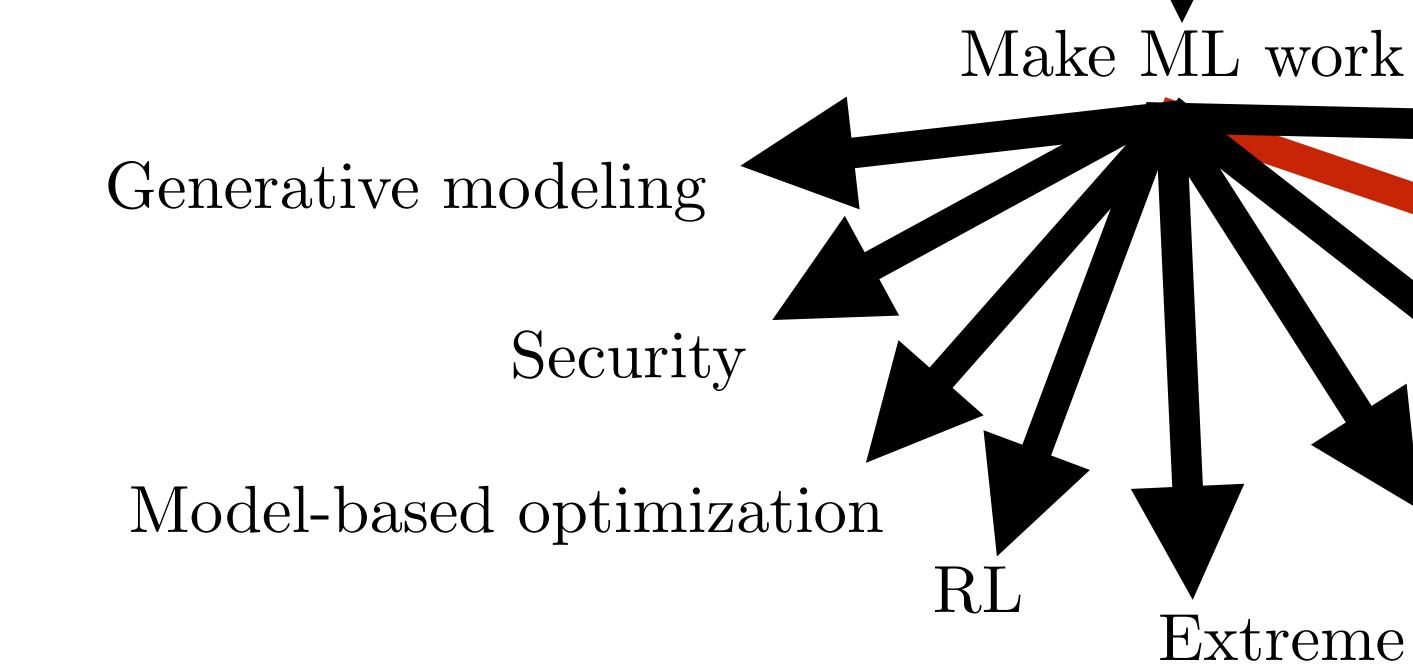
action

Canonical Simulation

> Learn to grasp without real data!

Canonical Simulation





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Label efficiency Extreme reliability



(Goodfellow 2019)

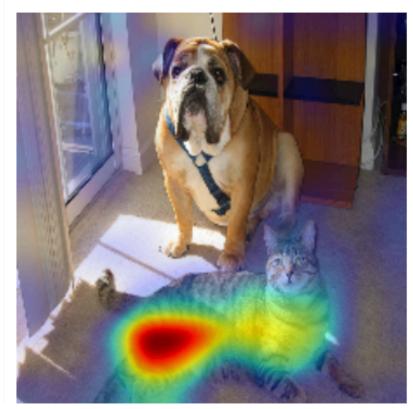
Adversarially Learned Fair Representations

- Edwards and Storkey 2015
- Learn representations that are useful for classification
- make S impossible to recover
- Final decision does not depend on S

• An adversary tries to recover a sensitive variable Sfrom the representation. Primary learner tries to



How do machine learning models work?

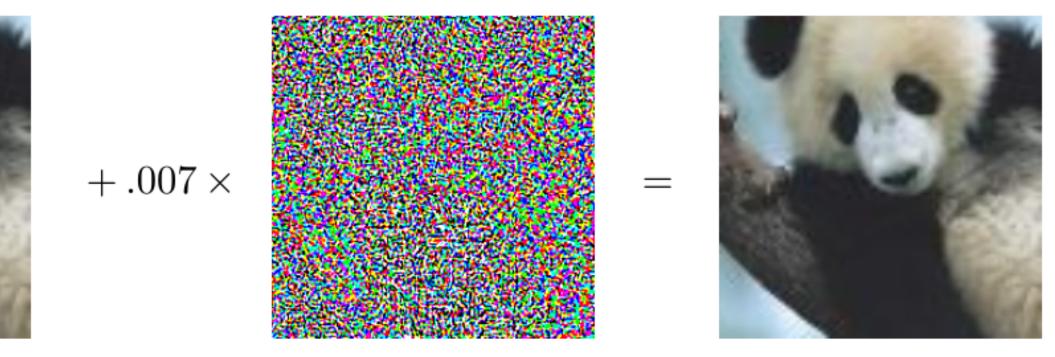


(c) Grad-CAM 'Cat'





(i) Grad-CAM 'Dog' (Selvaraju et al, 2016)



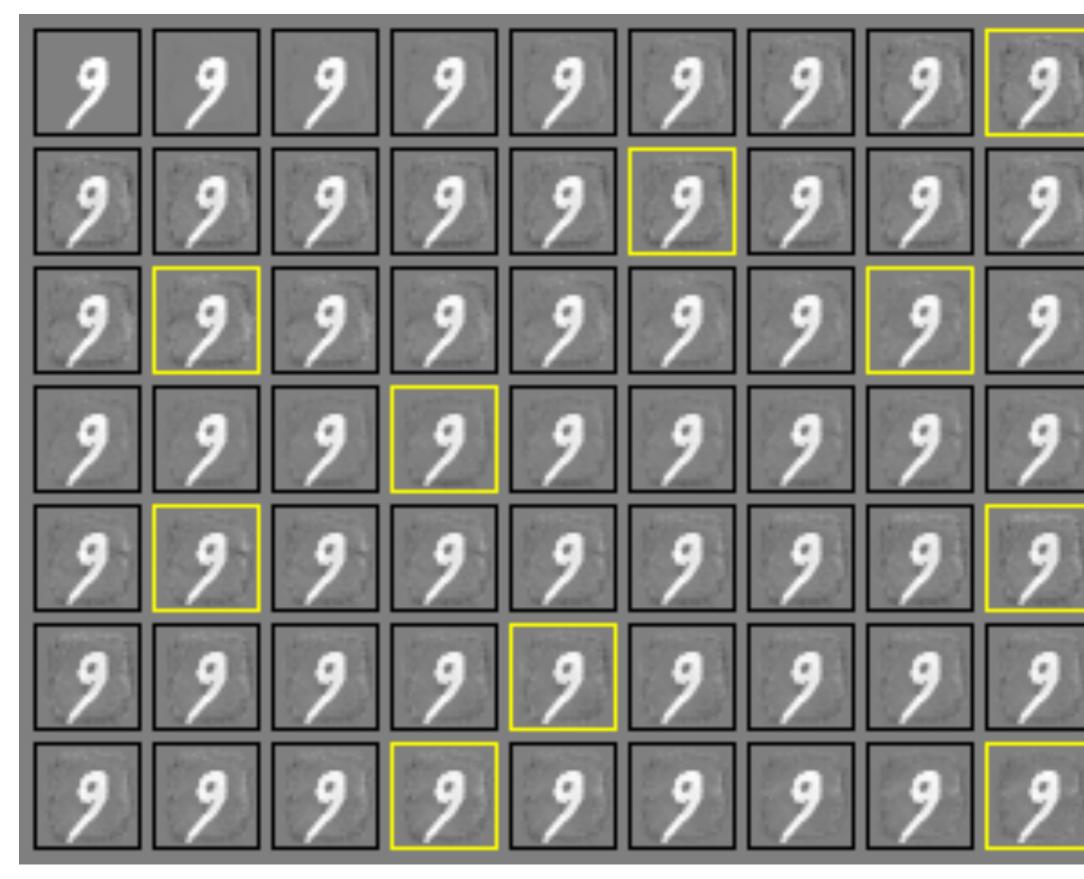
(Goodfellow et al, 2014)

Interpretability literature: our analysis tools show that deep nets work about how you would expect them to.

Adversarial ML literature: ML models are very easy to fool and even linear models work in counter-intuitive ways.

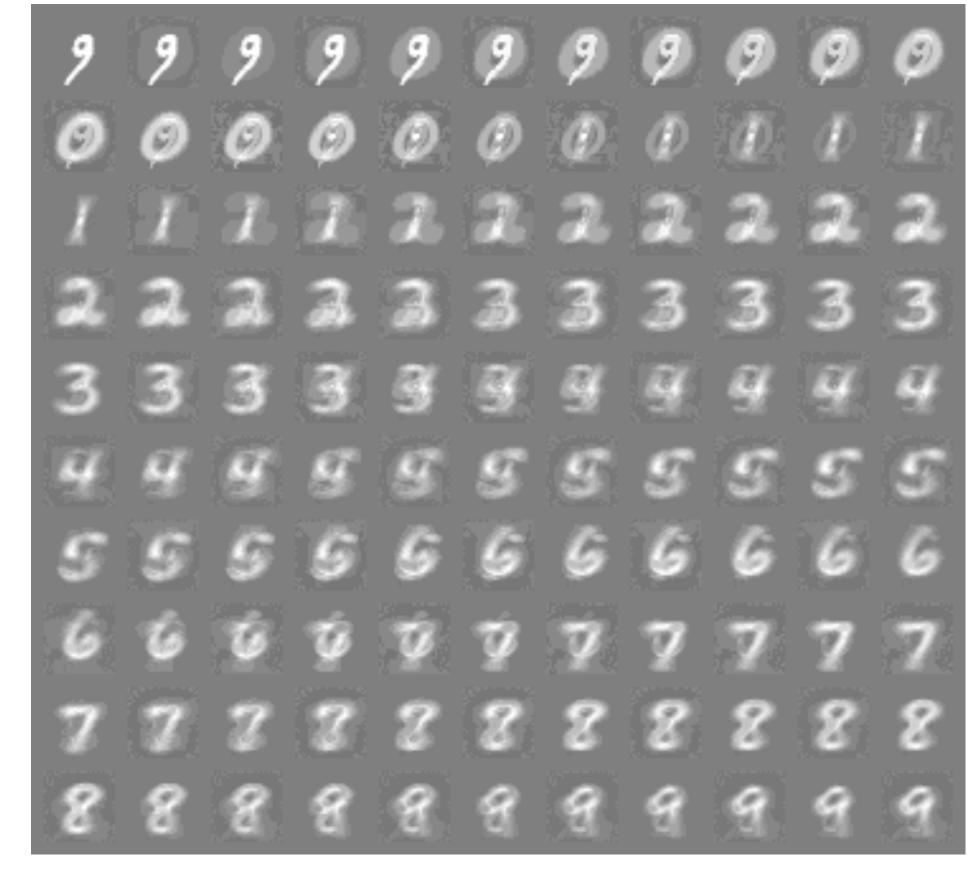


Robust models are more interpretable



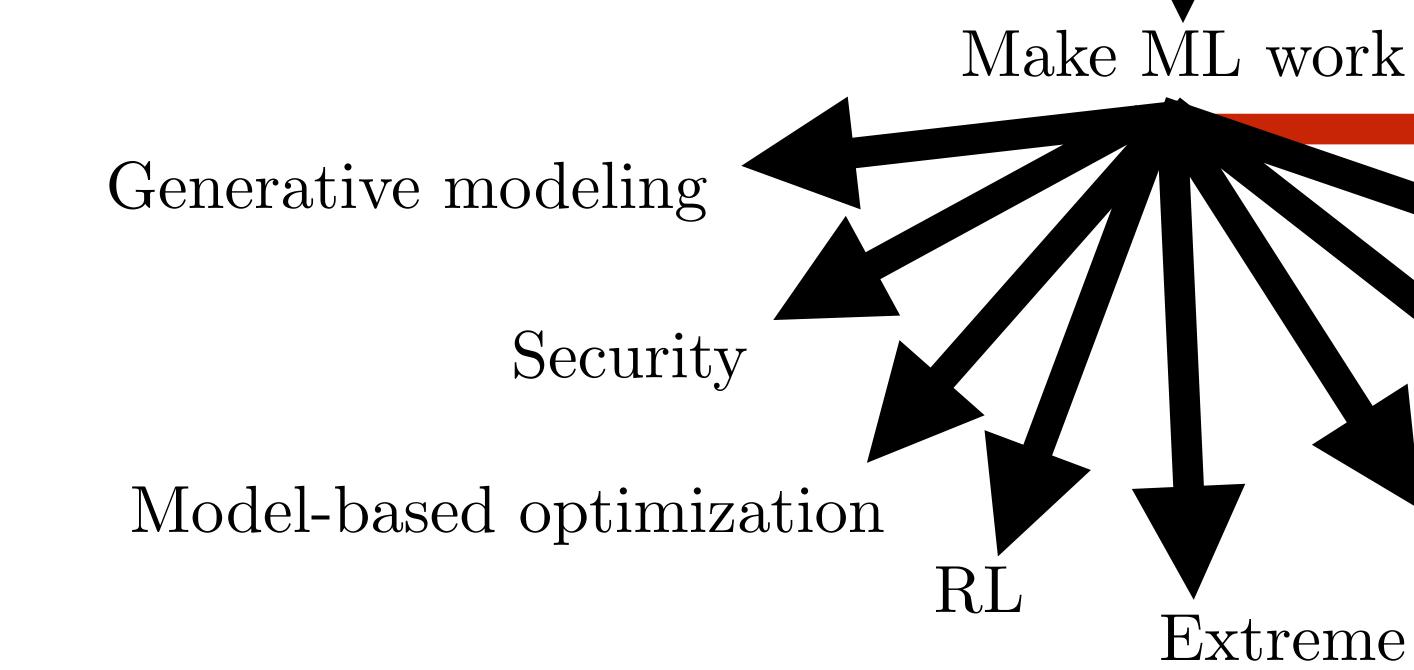
Relatively vulnerable model

(Goodfellow 2015)



Relatively robust model





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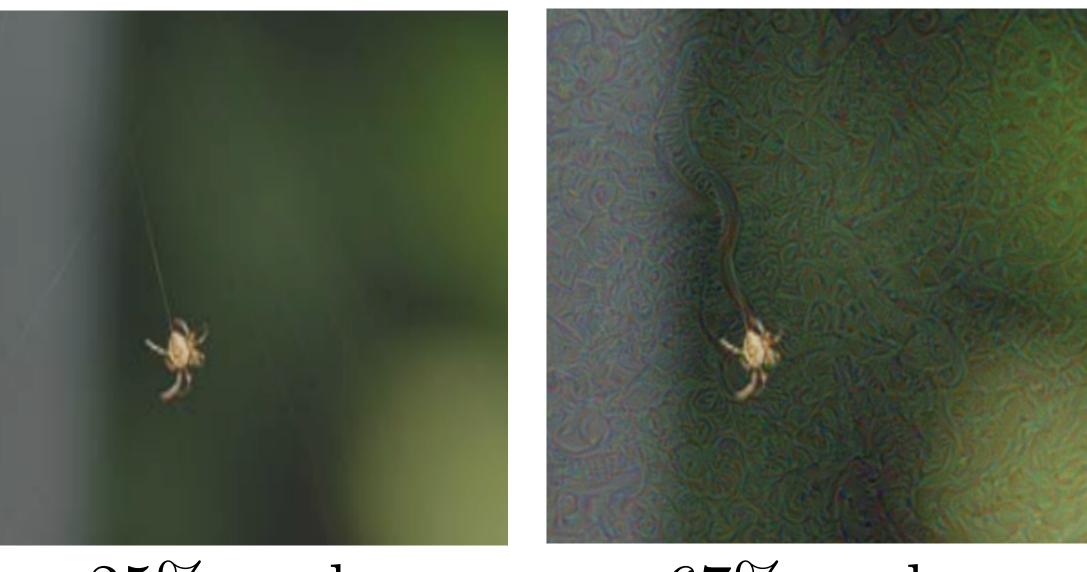
Fairness, accountability and transparency Domain adaptation



Adversarial examples that affect both computer and time-limited human vision







25% snake

67% snake

Elsayed et al 2018

Questions

